# Shortest Path First 

Dijkstra's Famous Algorithm

# "The question of whether computers can think is <br> like the question of whether submarines can swim" 

Edsger Wybe Dijkstra

## Dijkstra's SP Algorithm

- Famous paper "A note on two problems in connection with graphs" (1959)
- Single source SP problem in a directed graph
- Important applications include - Network routing protocols (OSPF, IS-IS)
- Traveller's route planner

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## Terms

- Graph G(V,E) consists of vertices V and edges E
- Edges are assigned costs c
- "Length" of graph $\mathbf{c}(\mathbf{G})=$ sum of all costs Assumed to be positive ("Distance Graph")
- "Distance" between two vertices $d\left(v, v^{\prime}\right)=$ $\min \{c(p)\}, p .$. path

Can be infinite

- $p$ with $c(p)=d\left(v, v^{\prime}\right)$ is called shortest path sp(v,v')

SPs are easier to calculcate for distance graphs where the costs are only positive.

## Definitions

- Select start vertex s
- Three sets of vertices:
- Selected (sp already calculated)
- Boundary (currently subject of calculation)
- Outside (not yet examined)



## The Algorithm



## Example


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Note that the left list ("Selected") is sometimes called the PATH list, and the right list ("Boundary") is sometimes called the TENT list (from tentative). It's got nothing to do with a beer tent.

## Result



## Performance

- Greedy algorithm
- Most critical: Implementation of boundary data structure
- No explicit structure: $\mathbf{O}\left(|\mathrm{V}|^{2}\right)$
- Fibonacci heap: $\mathbf{O}(|E|+|V| \log |\mathrm{V}|)$
- Alternatives
- Bellman-Ford (RIP) algorithm
- Floyd-Warshall algorithm
- A* algorithm

Extends SPF with a estimation function to enhance performance in certain situations

The SPF algorithm is of "greedy" type. Dijkstra originally proposed to treat the boundary vertices like outside vertices, therefore no explicit data structure is needed for the boundary vertices. This implementation is efficient for graphs with lots of edges but not efficient with so-called "thin" graphs. One of the best implementations use Fibonacci heaps for boundary representation.
Alternative algorithms are for example the Bellman-Ford or the Floyd-Warshall algorithm, which bases on Belman's optimization principle ("if the shortest path from A to C runs over B , then the partial path AB must also be the shortest possible").

## About E. W. Dijkstra

- Born in 1930 in Rotterdam
- Degrees in mathematics and theoretical physics from the University of Leyden and a Ph.D. in computing science from the University of Amsterdam

Programmer at the Mathematisch Centrum, Amsterdam, 1952-62

- Professor of mathematics, Eindhoven University of Technology, 1962-1984
Burroughs Corporation research fellow, 1973-1984
- Schlumberger Centennial Chair in Computing Sciences at the University of Texas at Austin, 1984-1999
- Retired as Professor Emeritus in 1999
- 1972 recipient of the ACM Turing Award,


Member of the Netherlands Royal Academy of Arts and Sciences, a member of the American Academy of Arts and Sciences, and a Distinguished Fellow of the British Computer Society. He received the 1974 AFIPS Harry Goode Award, the 1982 IEEE Computer Pioneer Award, and the 1989 ACM SIGCSE Award for Outstanding Contributions to Computer Science Education. Athens University of Economics awarded him an honorary doctorate in 2001. In 2002, the C\&C Foundation of Japan recognized Dijkstra "for his pioneering contributions to the establishment of the scientific basis for computer software through creative research in basic software theory, algorithm theory, structured programming, and semaphores".
Dijkstra enriched the language of computing with many concepts and phrases, such as structured programming, separation of concerns, synchronization, deadly embrace, dining philosophers, weakest precondition, guarded command, the excluded miracle, and the famous "semaphores" for controlling computer processes. The Oxford English Dictionary cites his use of the words "vector" and "stack" in a computing context.
(Source: http://www.cs.utexas.edu)


[^0]:    Single source SP algorithms find all shortest paths to all vertices at once. The only difference to single-pair SP algorithms is the termination condition.

