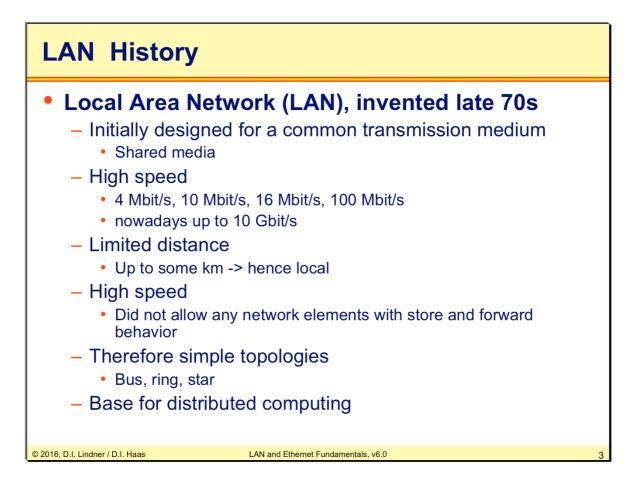
LAN, Legacy Ethernet, Bridging

LAN Introduction, IEEE Standards, Logical Link Control (LLC), Ethernet Fundamentals, Bridging Fundamentals, Bridging vs. Routing

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Logical Link (Sontrol
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Originally there was no packet switching or routing in the LAN world because of the high speed wanted to be achieved. Note: Ethernet bridging / Ethernet switching was invented as L2 packet switching technology in the late 80s.

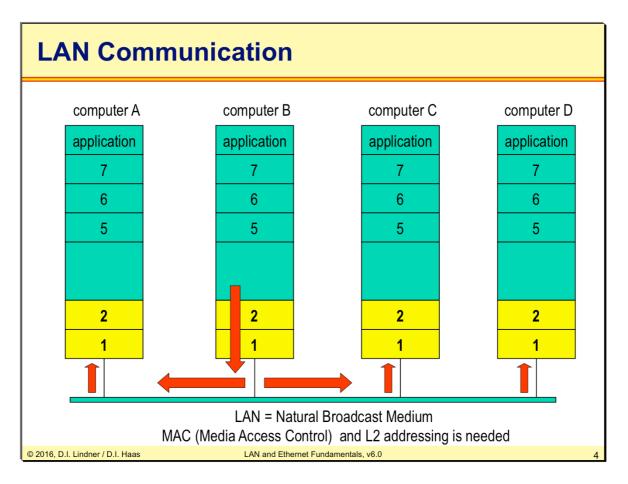
The LAN technologies of these days allowed a high speed extension of internal computer bus for the first time in data communication history. Hence LANs became the basis for any kind of distributed computing and client-server computing.

Some basic LAN characteristics:

All network stations share the same media and all stations have equal rights. A station can directly communicate with all other stations of the same LAN. In HDLC we have seen already a shared media in the multipoint topology using MSD. But here the duties and rights of HDLC primary and secondary station were unbalanced. Remember only secondary stations have a L2 address but primary station - as one and only master - needs no address.

LANs have a natural broadcast behavior: A message sent out by one station reaches all other stations on same LAN. A LAN is therefore a multipoint line which needs addressing and access control.

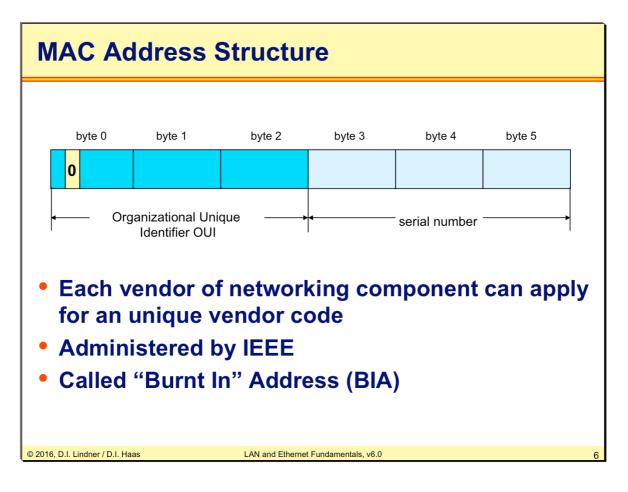
Therefore the terms MAC (media access control) and MAC address as unique but unstructured address are used in the LAN world. Initially there were no routing requirements and hence no need for structured addresses because store and forward (packet switching) done by CPUs was too slow. Layer 1 and layer 2 of the OSI model are sufficient to allow communication between systems connected to a single LAN. Have a look to the next slide to see the resulting protocol stack for LAN systems.



6 Byte MAC Addresses						
I/G Destination MAC Address						
b45,,b44	b45,,b44 b7,,b1,b0					
U/L Source MAC Address						
b45,,b44					b7,,b1,b0	
 U/L Individual/Group (I/G) I/G=0 is a unicast address I/G=1 is a group (broadcast) address Universal/Local (U/L) U/L=0 is a global, IEEE administered address U/L=1 is a local administered address 						
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Every station on a LAN is identified by a unique MAC-address which may be used either as source or destination MAC-address in LAN frames.

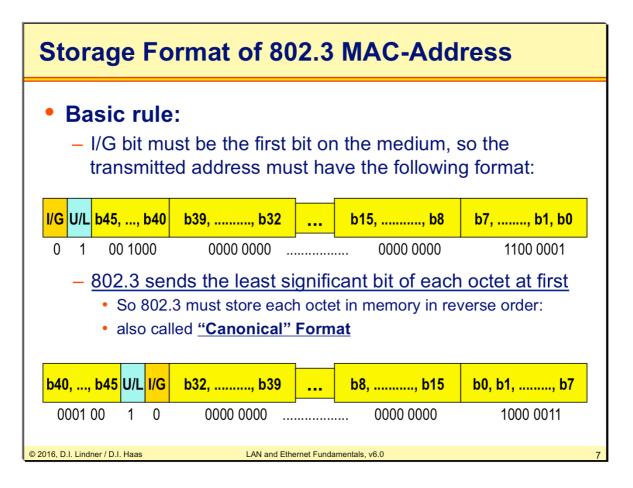
A MAC address is 6 bytes or 48 bits long and is typically written in hexadecimal notation. The first two bits of a MAC address on the have a special meaning. The first bit (I/G) specifies whether the MAC address is a unicast address (0) or a broadcast/multicast address (1). A multicast is a broadcast for a group whereas broadcast addresses all stations on a single LAN. The broadcast-address is an address with all bits set to 1 (hex FFFF FFFF, U/L is set to 1). Please recognize that bit 47 (I/G) has no meaning in the source address of a LAN frame. The second bit (U/L) specifies whether it's a global and unique MAC address administered by the IEEE, or a local administered address.



The MAC addresses are globally administered by the International Electrical and Electronic Engineering (IEEE) standardization organization.

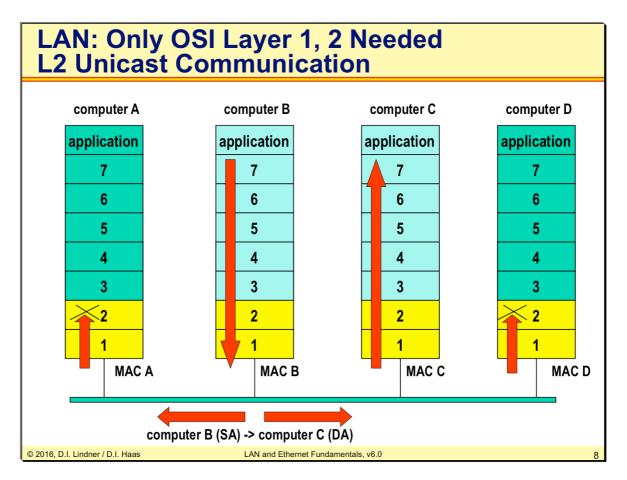
Each vendor of networking components can apply for an globally unique vendor code. The vendor code costs 1000\$ and occupies the first three bytes of the MAC address.

The remaining three bytes of the MAC address may be used by the vendor to address its components. Every Ethernet network card has one burnt in MAC address (BIA). Network cards of some vendors even support the use of programmable local administered MAC addresses.



Ethernet is using a canonical address format, which defines the order how bits from the transmission buffer are put onto the medium. In Ethernet systems the least significant bit of each byte is put on the medium first followed by the more significant bits.

Remember that the first two bits of a MAC address on the **wire** have a special meaning (I/G and U/L) per definition. Hence if MAC addresses - as parameters for LAN communication - are stored in the memory of a computer system, they have to be stored in the right format.



Receipt of frames:

Because of the inherent broadcast behavior of a LAN every frame is received by the Network Interface Card (NIC) of a station. The NIC decides if a frame should be forwarded to the higher layers (3-7) of a station depending on its own BIA and the destination address of the received frame. Usually NIC interrupts the CPU of the station if frame is to be forwarded. Otherwise the received frame is silently discarded by the NIC.

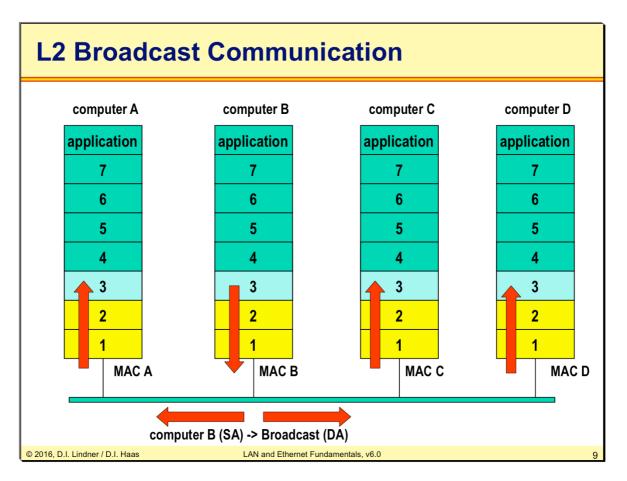
Frame are only forwarded to the higher layers (3-7) :

1. The destination address of the frame is equal with own BIA address

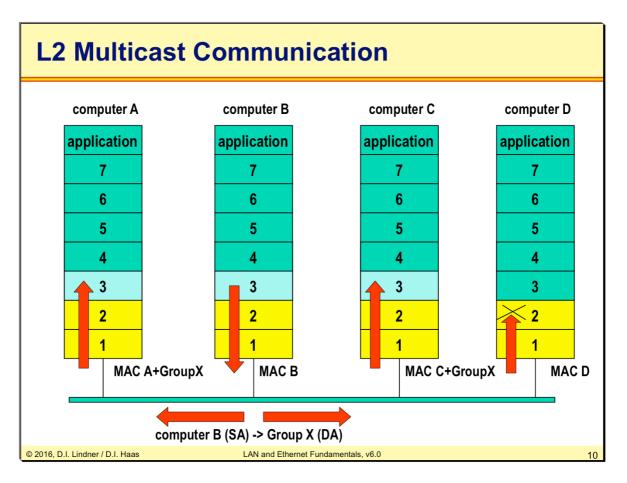
2. The destination address was a broadcast address

3. The destination address was a multicast (group) address and the given station is member of such a group.

The later two are seen on the next two slides.



Keep in mind that for normal operation frames should be destined to a station specific MACaddresses (direct communication), because broadcast frames will interrupt all stations for further handling by the higher layers. Even if it turns out that a station needs not to act on such a broadcast frame the CPU time of this stations will be wasted. Broadcast should be used in initialization phases of a network only!



In this example computer A and C are programmed to listen to group address X. Computer D will not be disturbed by this frame because it is not programmed to listen to X.

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IEEE 802

LAN Standardization is done

- By IEEE (Institute of Electrical and Electronics Engineers)

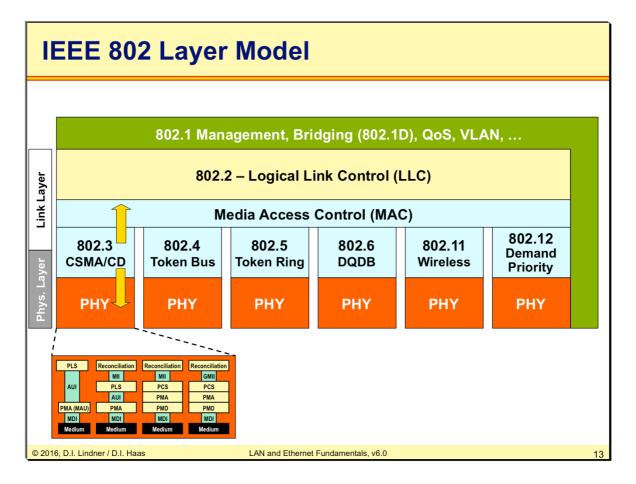
- Workgroup 802 (Start: February 1980)

• OSI Data Link Layer (Layer 2)

- Was originally designed for point-to-point line
- But LAN = multipoint line, shared media
- Therefore OSI Layer 2 was split into two sublayers
 - Logical Link Control
 - Media Access Control

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802.3 standard specifies "Ethernet". The standard covers part of OSI layer 2 (MAC layer) and OSI layer 1 (physical Layer).

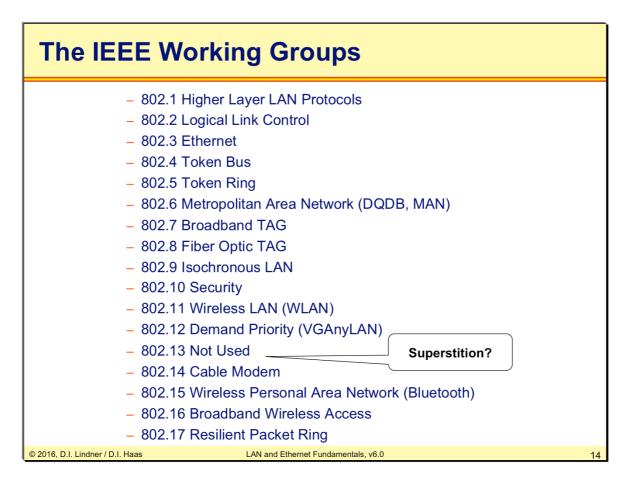
The physical layer of Ethernet is responsible for the speed of the transmission (currently there are four different speeds available, 10, 100, 1000, 10000 Mbit/s). In the graphic the physical interface structure of the 10, 100, 1000 Mbit/s systems is shown.

The interface function between the physical layer and the Ethernet data-link layer is performed by the CSMA/CD algorithm.

The Medium Access Control layer is responsible for addressing and it controls whether a data frame is picked up from the wire and is loaded into the buffer of the Ethernet card or not.

The Logical Link Control layer is responsible for the interface function between the Ethernet layer and higher layers on top of Ethernet plus the support of connection-less or connection-oriented mode.

The 802.1 Management cannot be seen as an separate Ethernet layer but it describes additional optional Ethernet functions like bridging, QoS, flow control, SPT, etc.



On this slide you can see a summary of the most important IEEE standards so far. An Ethernet system is covered by the standards 802.1, 802.2 and 802.3.

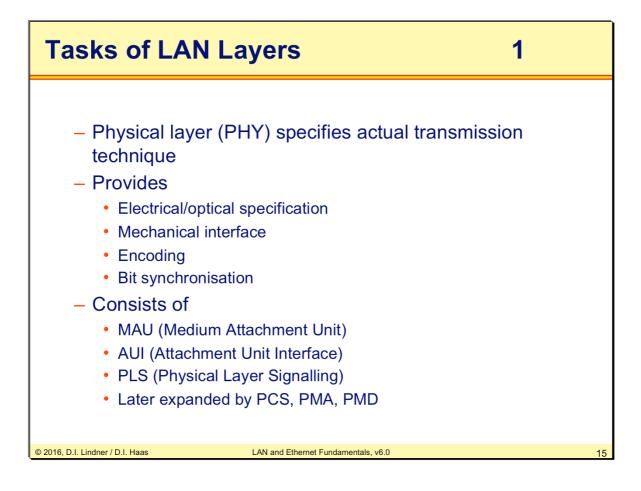
The 802.1 describes management and optional functions inside the Ethernet technology like the Spanning-tree (STP) process, Ethernet bridging, VLAN systems, etc.

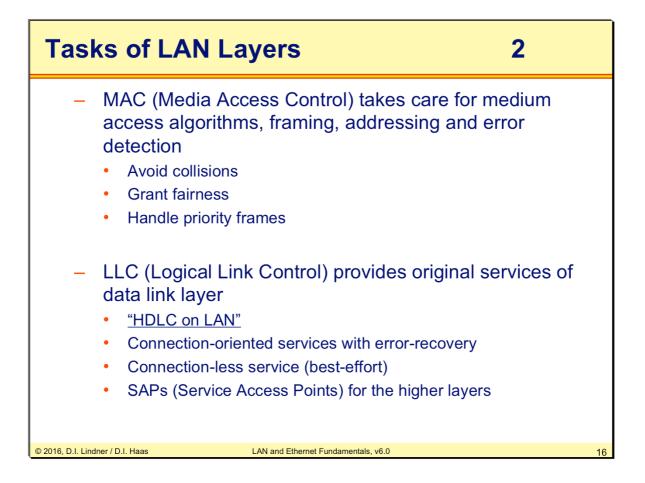
The 802.2 standards describes the Logical Link Control (LLC) function, which is only used in 802.3 Ethernet systems. With LLC it is possible to provide connection-oriented or connection-less mode service to the upper layers.

The 802.3 standard describes the physical layer of the Ethernet system plus the media access that is controlled by the CSMA/CD procedure.

Note: At the early days of Ethernet there were two competing organizations: the IEEE committee responsible for the 802.X standards and the companies Digital, Intel and Xerox (DIX) which where responsible for the Ethernetv2 aka DIX standard. In the year 1984 the DIX committee disappeared and the IEEE took over the responsibility to maintain and adapt the DIX standard for new upcoming Ethernet technologies.

Today all Ethernet interface cards support both frame types the 802.3 and the ETH 2 frame.





IEEE 802.1 Standards

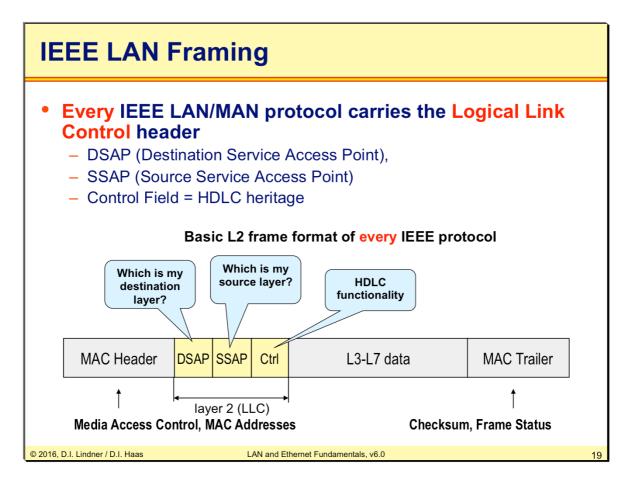
Specifies a common framework for all 802.x LANs

- Addressing rules, relations to the OSI model
- Subnet addressing, Bridging Ethernetv2 to 802.2 LANs
- Management (802.1B)
- Bridging (802.1D-1998) including STP (Spanning Tree Protocol)
 Single STP in case of VLANs
- System Load Protocol (802.1E)
- Virtual (V) LANs (802.1Q)
 - Tagging
- STP Rapid Configuration (802.1w or 802.1D-2004)
- Multiple STP (802.1Q-2003)
 - Multiple STP instances in case of VLANs
- EAP Authentication (802.1x)
 - Extensible Authentication Protocol

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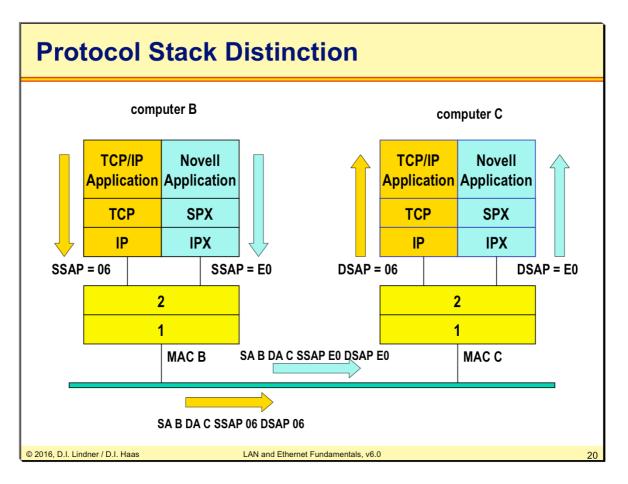


The LLC (802.2) is part of every basic frame format that is specified by the IEEE e.g. Token ring, Token bus, Ethernet, etc.

The DSAP and SSAP field are both eight bit in length and are used to address layer 3 processes. With the SSAP the layer 2-3 interface used at the source is specified, while the DSAP specifies the layer 2-3 interface at the destination. But typically it is very unlikely to use a SSAP value different from the DSAP value, because only layer 3 processes of the same kind are able to communicate with each other. For IP to IP communication a SSAP and DSAP value of 0 x 06 is defined by IEEE.

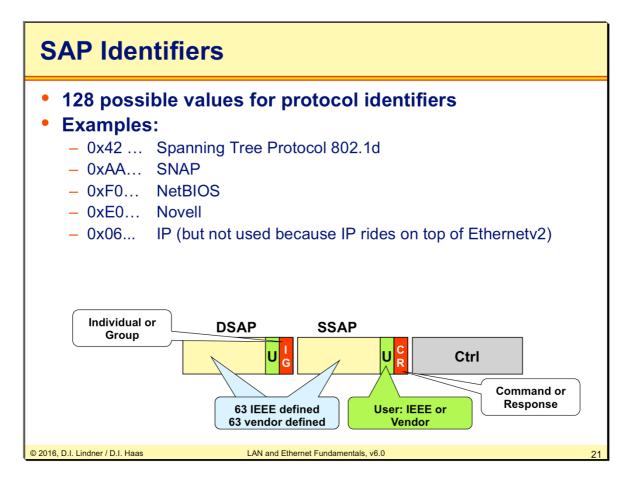
The Control field inside the LLC can be used for connection-oriented or connection-less communication and the way it works is basically the same what HDLC does.

The connection-less mode of LLC is used by IP, IPX, AppleTalk. The connection-oriented mode of LLC is used by SNA over LLC Type 2 and NetBIOS over LLC Type 2 (NetBeui -> old style Microsoft Network -> already obsolete).



An IEEE 802 LAN can be used by different protocol families sharing the same communication media e.g. TCP/IP parallel to Novell IPX, IBM SNA, NetBeui, AppleTalk

DSAP and SSAP identify the higher level protocol family, which is the destination and the source of the given frame. They can be seen as protocol type or protocol stack identifier.

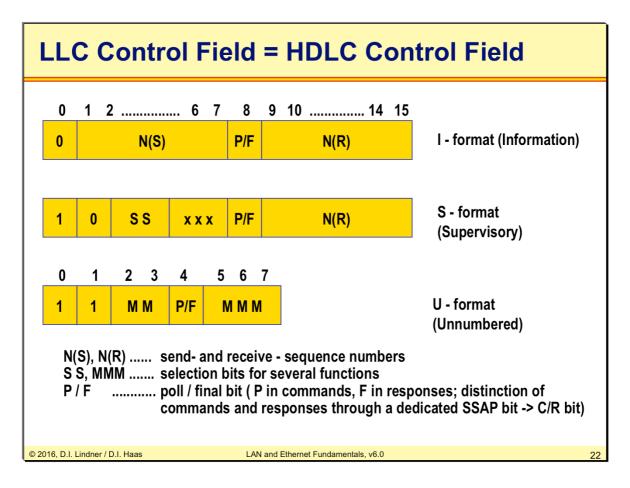


The DSAP and the SSAP are both 8 bit in length. The least significant bit in the DSAP is reserved to indicate whether it's a individual or group access point. In the SSAP this bit is the command/response bit which works together with LLC connection-oriented protocol mode. The U bit is used to specify whether its an IEEE or vendor specific access point.

Some examples:

Hex E0	Novell (U=0)
Hex Fy	reserved for IBM (U=0)
Hex F0	NetBIOS (U=0)
Hex F4	IBM LAN manager individual (U=0)
Hex F5	IBM LAN manager group (U=0, I/G =1)
Hex F8	remote program load (U=0)
Hex 04	SNA path control individual (U=0)
Hex 05	SNA path control group (U=0, I/G =1)
Hex 03	LLC sub-layer management (U=1)
Hex 06	DoD IP (U=1)
Hex 42	802.1d Spanning Tree Protocol (U=1)
Hex AA	TCP/IP SNAP (U=1)
Hex FE	ISO Network Layer (U=1)
Hex 00 SAP -> a kind of Ll	Null SAP, a station with operating LLC software always responds to a frame destined to the Null _C Ping can be implemented

The range Hex 8y to 9C (with U=0) is reserved for free usage except y = xx1x (binary notation); U=1



- LLC Control field and protocol procedures are very similar to HDLC remember: HDLC procedures allow connection-less and connection-oriented services on a layer 2 link
- Connection-less mode of LLC is used by IP, IPX, AppleTalk, etc

Connection-oriented mode of LLC was used by SNA over LLC Type 2 NetBIOS over LLC Type 2 (NetBeui) e.g. Microsoft Network (old style – already obsoleted)

LLC Frame Types and Classes							
Cmd	Control	Resp	Control	1	Cla 2	ass 3	4
UI XID TEST	1100p000 1111p111 1100p111	XID TEST	1111f111 1100f111	x x x	x x x		
I RR RNR REJ SABME DISC	0 n(s) p n(r) 10000000 p n(r) 10100000 p n(r) 10010000 p n(r) 1111p110 1100p010	I RR RNR REJ UA DM FRMR	0 n(s) f n(r) 10000000 f n(r) 10100000 f n(r) 10010000 f n(r) 1100f110 1111f001 1110f001		x x x x x x x x		x x x x x x x x x
AC0 AC1	1110p110 1110p111	AC0 AC1	1110f110 1110f111			x x	X X
	Cmd UI XID TEST I RR RNR REJ SABME DISC	Cmd Control UI 1100p000 XID 1111p111 TEST 1100p111 I 0 n(s) p n(r) RR 10000000 p n(r) RNR 10100000 p n(r) RLJ 10010000 p n(r) RLJ 10010000 p n(r) SABME 1111p110 DISC 1100p010 AC0 1110p110 AC1 1110p111	Cmd Control Resp UI 1100p000 XID XID 1111p111 XID TEST 1100p111 TEST I 0 n(s) p n(r) I RR 10000000 p n(r) RR RR RNR 10100000 p n(r) RR RNR SABME 1111p110 UA DM DISC 1100p010 DM FRMR AC0 1110p110 AC0 AC1	Cmd Control Resp Control UI 1100p000 XID 1111p111 TEST XID 1111f111 TEST 1100p111 I 0 n(s) p n(r) I 0 n(s) f n(r) RR 10000000 p n(r) RR 10000000 f n(r) RR 10000000 f n(r) RNR 10100000 p n(r) RR 10100000 f n(r) RLJ 10010000 f n(r) SABME 1111p110 UA 1100f110 DM 1111f001 DISC 1100p010 DM 1110f001 FRMR 1110f001 AC0 1110p110 AC0 1110f110 AC1 1110f111	Cmd Control Resp Control 1 UI 1100p000 XID 1111p111 XID 1111f111 x TEST 1100p111 TEST 1100f111 x x I 0 n(s) p n(r) I 0 n(s) f n(r) RR 10000000 p n(r) RR 10000000 f n(r) RR 10000000 f n(r) RNR 10100000 p n(r) RNR 10100000 f n(r) REJ 10010000 f n(r) SABME 1111p110 UA 1100f110 M 1110f110 DISC 1100p010 DM 1110f001 FRMR 1110f001 AC0 1110p110 AC0 1110f110 AC1 1110f111	Cmd Control Resp Control 1 2 UI 1100p000 XID 1111f111 X x x XID 1111p111 XID 1111f111 x x x TEST 1100p111 TEST 1100f111 x x x I 0 n(s) p n(r) I 0 n(s) f n(r) x x I 0 n(s) p n(r) I 0 n(s) f n(r) x x RR 10000000 p n(r) RR 10000000 f n(r) x x x REJ 10010000 p n(r) REJ 10010000 f n(r) x x SABME 1111p110 UA 1100f110 x x AC0 1110p110 AC0 1110f110 x x AC1 1110p111 AC1 1110f110 x x	Cmd Control Resp Control 1 2 3 UI 1100p000 XID 1111f111 X x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x

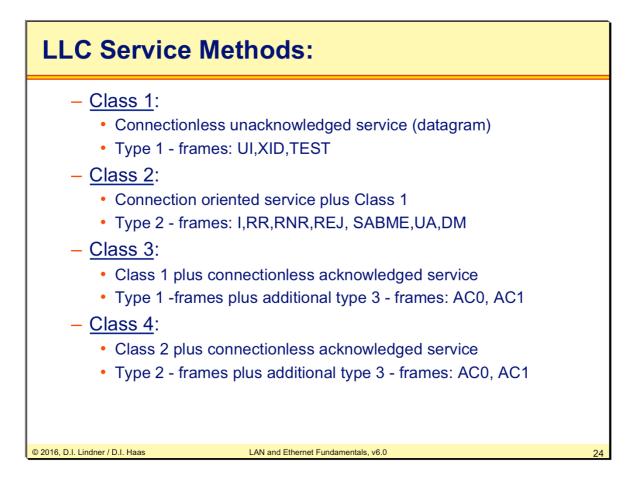
Frames used for connectionless service, datagram service (type1): UI (Unnumbered Information) -> Datagram Info -> Best-Effort XID (Exchange Identification) -> LLC Ping TEST -> Ping plus test data

Frames used for connection-oriented service (type2): "HDLC in extended ABM mode" SABME (Set Asynchronous Balanced Mode Ext.)

- connection establishment UA (Unnumbered Acknowledgement)
- connection establishment acknowledgement
- DM (Disconnected Mode)
- negative acknowledgement for connection establishment or connection abort
- DISC (Disconnect)
 - connection tear down
- I (Information)
 - data frame
- RR (Receiver Ready)
- ACK plus station ready
- RNR (Rec. Not Ready)
- ACK plus station not ready
- REJ (Reject)
- NACK with GoBackN FRMR (Frame Reject)
 - for signalling error situations

Frames additionally used for acknowledged datagram-service ACx command with data immediately acknowledged by ACx response, next ACy command allowed only after arrival of ACx Idle RQ protocol (stop and wait)

Note: Information what frame is command and what frame is response is taken from the C/R bit in the SSAP field.



Class 1 offers best effort service only, while Class 2 works connection-oriented with error recovery and flow control support.

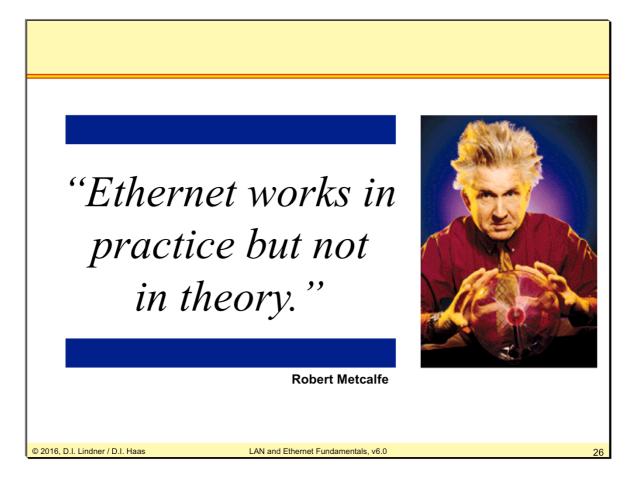
The most important service class is the Class 1 connection-less service, because the tasks of error recovery and flow control are typically performed by higher layer processes e.g. TCP.

Only protocols like Microsoft's NetBeui or IBM's SNA need Class 2 connection-oriented service, because error recovery and flow control is not supported by their protocol stacks.

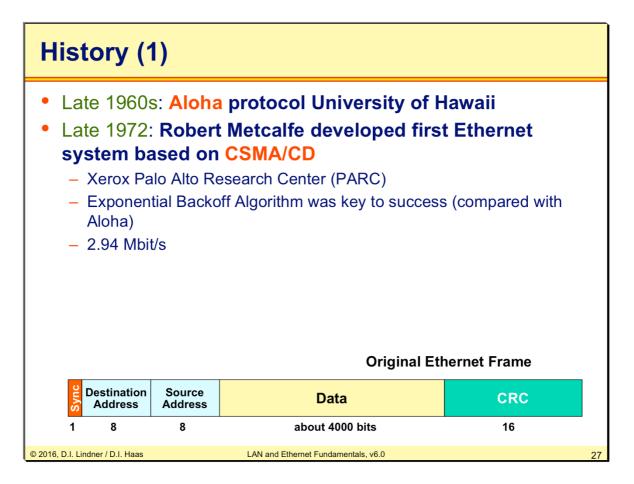
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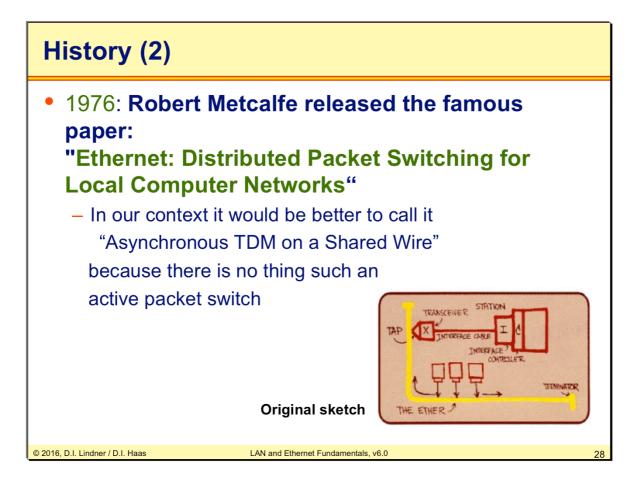


Yeah,...Robert Metcalfe was the inventor of Ethernet.



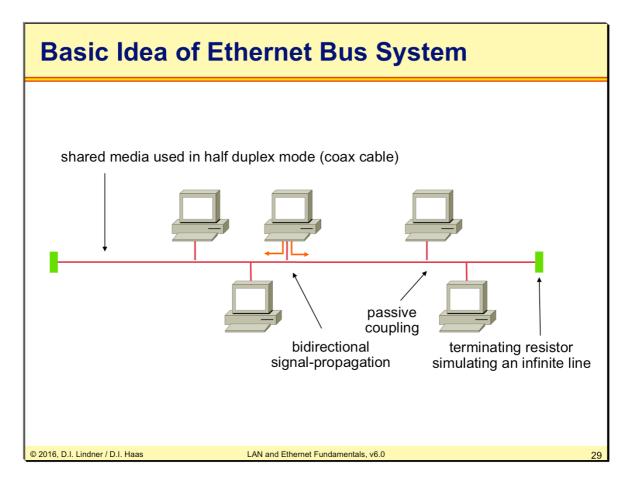
The Aloha protocol was fairly simple: send whenever you like, but wait for an acknowledgement. If there is no acknowledgement then a collision is assumed and the station has to retransmit after a random time. "Pure Aloha" achieved a maximum channel utilization of 18 percent. "Slotted Aloha" used a centralized clock and assigned transmission slots to each sender, hereby increasing the maximum utilization to about 37 percent. Robert Metcalfe perceived the problem: another backoff algorithm was needed but also "listen before talk". Metcalfe created Carrier Sense Multiple Access Collision Detection (CSMA/CD) and a truncated exponential backoff algorithm which allows a 100 percent load.

Robert Metcalfe's first Ethernet system used a transmission rate at 2.94 Mbit/s which was the system clock of the Xerox Alto workstations at that time. Originally, in 1972 Metcalfe called his system Alto Aloha Network, but one year later he renamed it into "Ethernet" in order to emphasize that this networking system could support any computer not just Altos – and of course to clarify the difference to traditional Aloha!



The press has often stated that Ethernet was invented on May 22, 1973, when Robert Metcalfe wrote a memo to his bosses stating the possibilities of Ethernet's potential, but Metcalfe claims Ethernet was actually invented very gradually over a period of several years. In 1976, Robert Metcalfe and David Boggs (Metcalfe's assistant) published a paper titled, "Ethernet: Distributed Packet-Switching For Local Computer Networks."

Metcalfe left Xerox in 1979 to promote the use of personal computers and local area networks (LANs). He successfully convinced Digital Equipment, Intel, and Xerox Corporations to work together to promote Ethernet as a standard. Now an international computer industry standard, Ethernet is the most widely installed LAN protocol.



Basic ideas:

Bus topology based on coax-cables with passive, uninterrupted coupling.

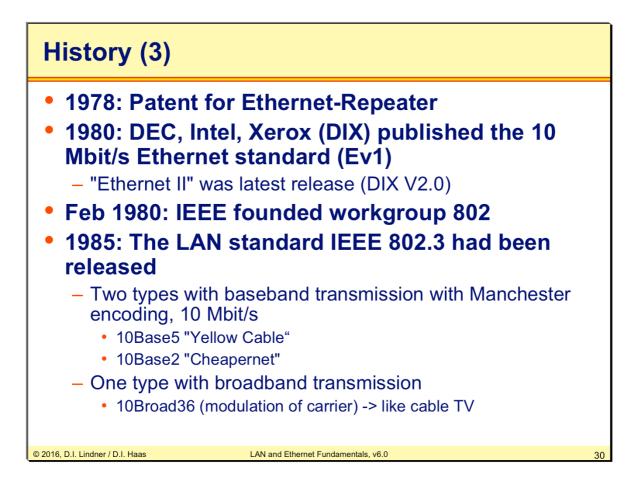
Shared media like the "Ether" of air.

Bidirectional signal-propagation -> termination resistors avoid signal reflections.

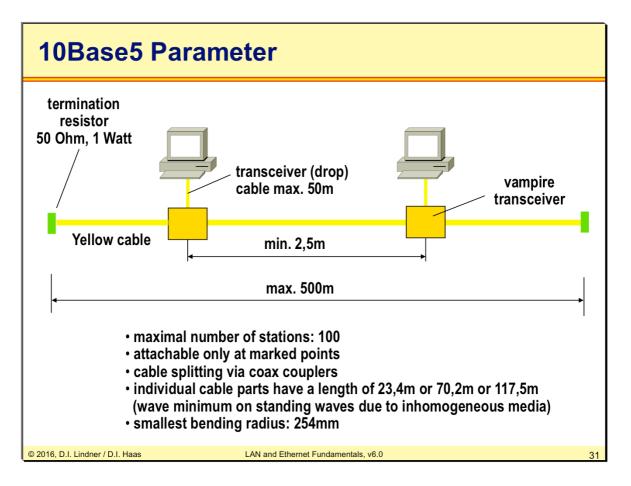
Given transmitting power of a network station limits cable length and number of (receiver-) stations.

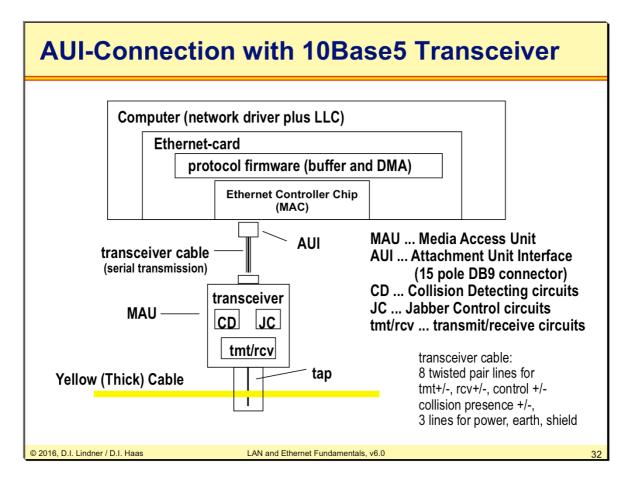
10 Mbit/s baseband transmission with Manchester encoding.

To differentiate between network stations we need addresses -> source and destination MAC addresses



First Ethernet standard was entitled "The Ethernet, A Local Area Network: Data Link Layer and Physical Layer Specifications" and focused on thick coaxial cable only.





Different transceiver types for 10Base5, 10Base2, FOIRL (Fiber Optic Inter Repeater Link) and 10BaseT, 10BaseF (these types will be handled later in this presentation).

Transmitter/Receiver = provides electronic circuits for:

1. Inserting and receiving signal currents

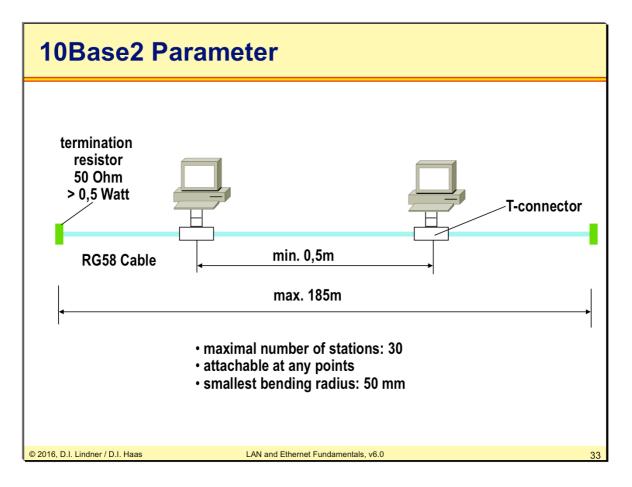
2. Collision detection (measurement of DC level):

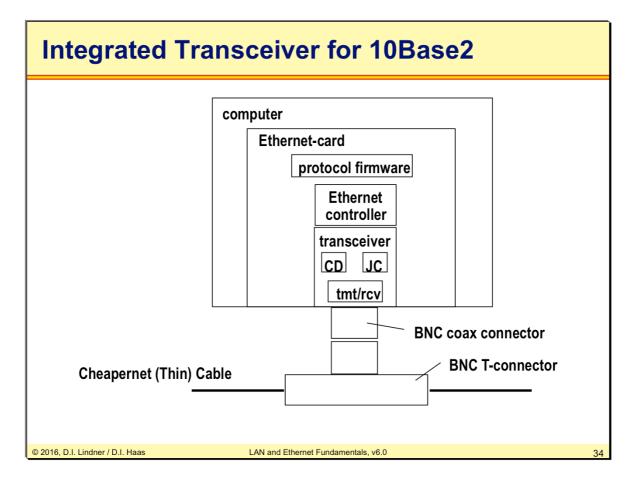
10Base5: Level High (1) = 0 mA, Level Low (0) = -80 mA -> DC of Manchester-encoded signal = -40 mA -> two signals at same time: DC Level < -40 mA

- 3. Heartbeat function
- 4. SQE Signal Quality Error

5. Jabber control (prevents continuously emitting of frames beyond the maximal frame size caused by an erroneous Ethernet controller)

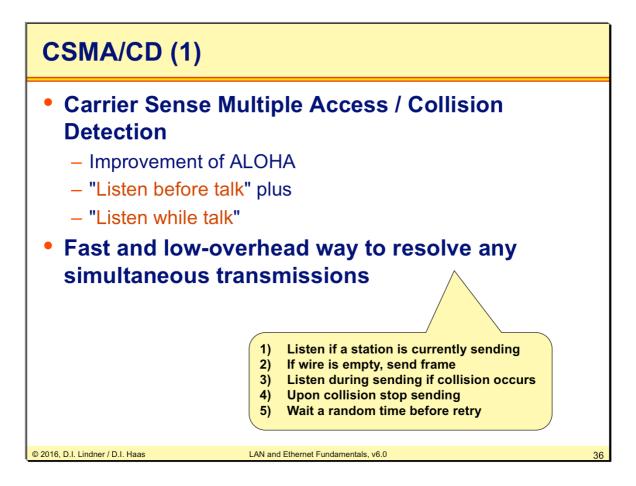
External transceiver: AUI interface (with or without transceiver cable) connects end system and transceiver; transceiver powered by end system





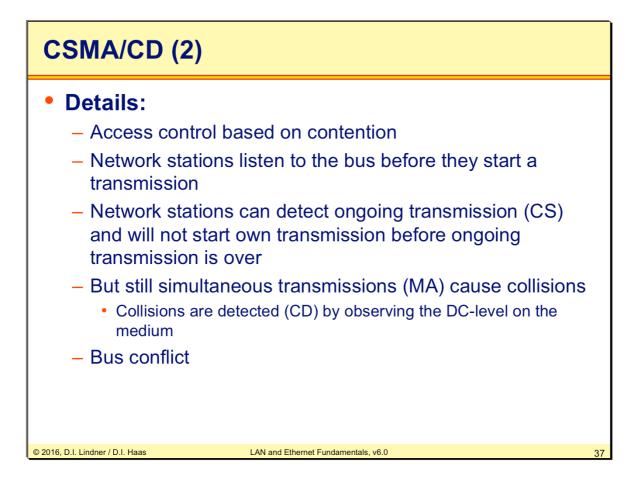
Integrated transceiver: Transceiver is integrated on network card of end system network card provides necessary physical connector like BNC (10Base2), RJ45 (10BaseT), ST (10BaseF)

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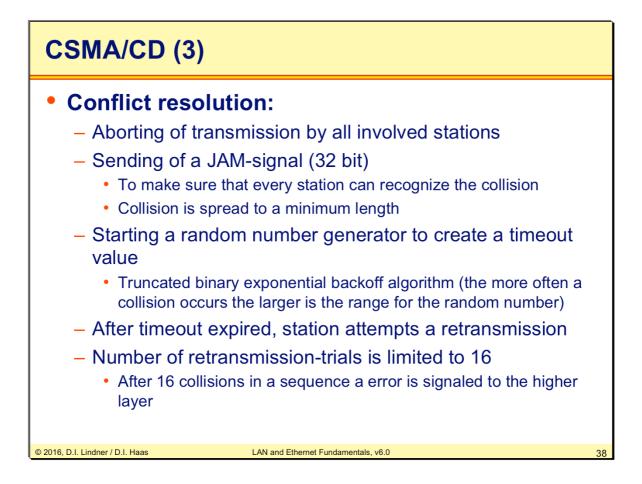
Ethernet is a shared media technology, so a procedure had to be found to control the access onto the physical media. This procedure was called the Carrier Sense Multiple Access Collision Detection (CSMA/CD) circuit.

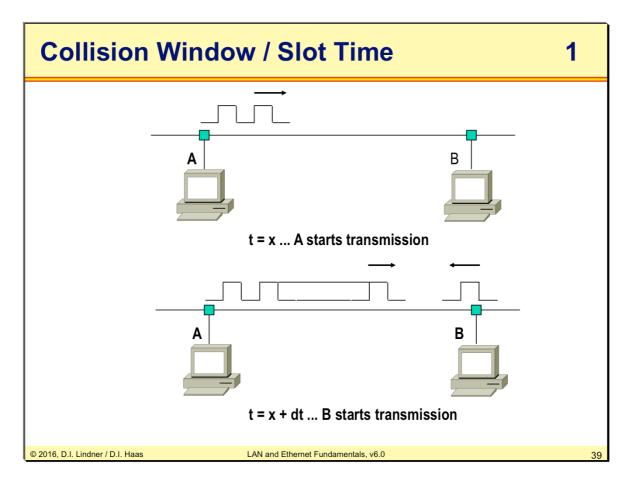
The way it works is quite simple, every stations that wants to send need to do a Carrier Sense to check if the media is already occupied or not. If the media is available the station is allowed to perform an Media Access and may start sending data. In the case that two stations almost at the same time access the media, a collision will happen. To recognize and resolve a collision is the task of the Collision Detect circuit. Every station listens to its own data while sending. In the case of a collision the currently sending stations recognize the collision by the superimposition of the electrical waves on the wire. Collisions are detected (CD) by observing the DC-level on the medium. A jamming signal will be sent out to make sure all involved stations recognize the occurrence of an collision. All stations involved in the collision stop sending and start a randomize timer. When the randomize timer expires the station may try to access the media again.

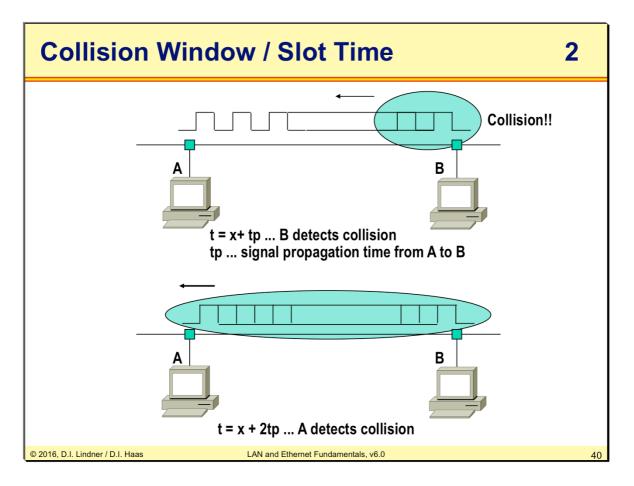


Collision Detection details:

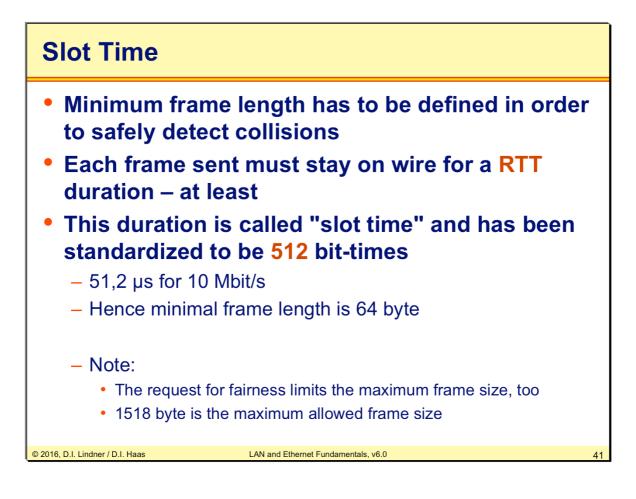
In coaxial Ethernet, transceivers send their Manchester code using the DC offset method. A "high" value is nominally zero current; a "low" value is nominally -80 mA. This results in a DC component to the signal of -40 mA, which creates a voltage of -1 VDC (the transceiver sees a 25 ohm load from the two 50 ohm cables going "left and right" away from the transceiver). When two transceivers send at the same time, their currents add, increasing the DC component of the combined signal to -2 VDC Thus, we can detect collisions by looking for DC signals in excess of the maximum that could possibly be generated by a single transmitter.



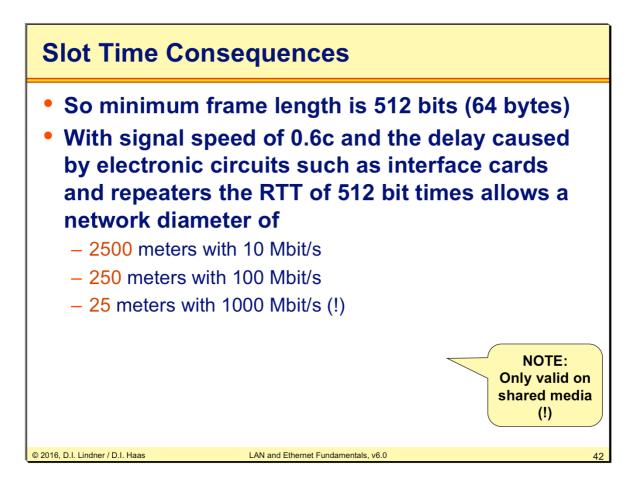




In the worst case stations have to send bits twice the maximum signal propagation time (RTT) for reliable collision detection. Otherwise a collision may not be seen by the transmitting station for the currently transmitted frame.



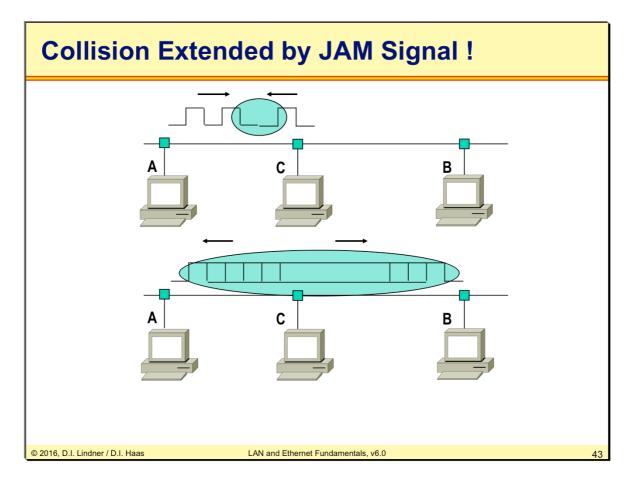
There is a very basic Ethernet rule that says a collision must be detected while a station is transmitting data. Therefore a stations needs to keep on sending at least of the duration of the RTT of the Ethernet system. The maximum allowed RTT is standardized and is called the slot time. The slot time for 10Mbit/s Ethernet systems is set to 51,2 μ s. If collisions occur after expiration of the slot time we talk about "late collisions", which may cause malfunctions in the network. For example if a station transmits a frame and no collision was detected, the station assumes correct delivery of the frame. Now the station removes the frame from the transmit buffer, leaving no chance to retransmit the frame in the case of a late collision.



The minimum frame length in Ethernet systems is set to 64 byte or 512 bit. This minimum frame length plus the slot time in combination with the speed of electrical signals on a wire (\sim 180.000 km/s) determines the maximum outspread of an Ethernet system.

Therefore we end up at a maximum outspread of 2500 meters for 10Mbit/s Ethernet systems. The maximum outspread of faster Ethernet systems is directly related to their shorter slot times, because of the higher speed.

These distance limitations must only be taken into account in shared media environments like Ethernet Bus and Hub systems. In more modern switched environments using full duplex communication these distance limitations can be neglected.



The picture shows how a collision between closely located stations is extended by the jam signal to a minimal length in order to be recognized by network station too. Without jam signal the collision would cause A and C to immediately stop their transmission and that short collision (small signal spike on the media) may not be recognized by the receiving circuits of all other stations.

Exponential Backoff	
 Most important idea of Ethernet ! Provides maximal utilization of bandwidth After collision, set basic delay = slot time Total delay = basic delay * random 	
 0 <= random < 2^k k = min (number of transmission attempts, 10) Allows channel utilization After 16 successive collisions 	
 Frame is discarded Error message to higher layer Next frame is processed, if any 	
 Truncated Backoff (k<=10) 1024 potential "slots" for a station Thus maximum 1024 stations allowed on half-duplex Ethernet 	
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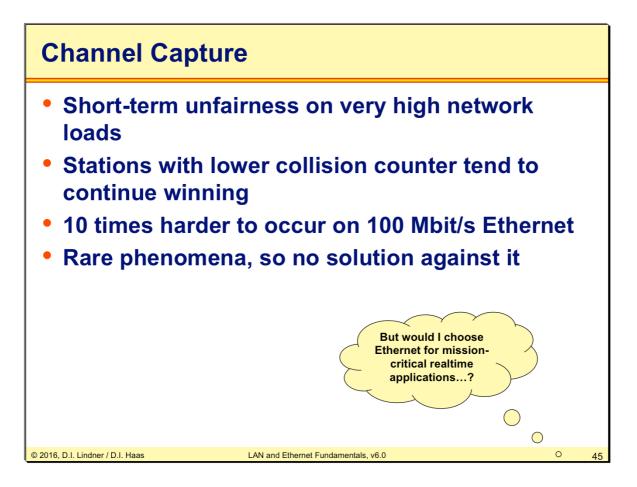
The retransmission in case of collisions is controlled by the exponential backoff algorithm.

The retransmission is delayed about a basic delay, which is set to 51,2 microseconds for 10 Mbit/s Ethernet, times a random factor. The range out of which the randomize factor is selected is increasing with the number of retransmission attempts. Repeated collisions indicate a busy medium, therefore the station tries to adjust to the medium load by progressively increasing the time delay between repeated retransmission attempts.

The retransmission of a frame is attempted up to a defined maximum number of retries typically known as the attempt limit. The attempt limit is set to a maximum of 16 retries by the standard.

After 16 retries the frame is discarded and a error message is sent to higher layers. Then the station continuous to process the next frame.

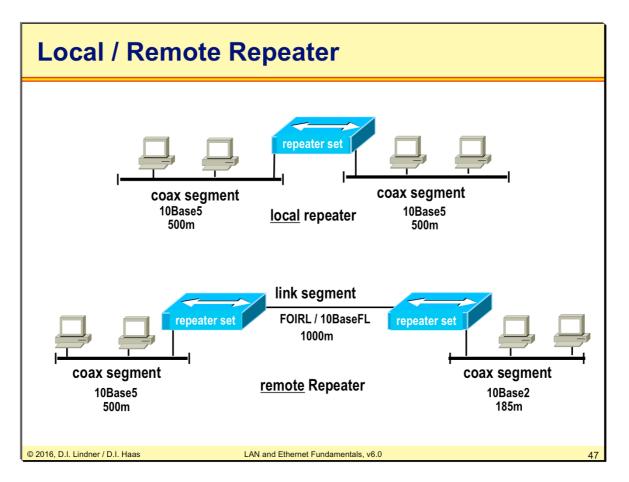
Due to the truncated backup algorithm a maximum of 1024 potential time slots for a station are available. So the maximum number of stations attached to half duplex Ethernet systems should not exceed 1024 stations.



In the case of very high network loads Ethernet tends to prefer stations with lower collision counters, because they try to access the media in shorter time intervals than stations with a higher collision counter.

This is a phenomena that was never solved in Ethernet systems, but can be disregarded for today's Ethernet networks, because most of them are switched networks where collisions play no or just a minor role.

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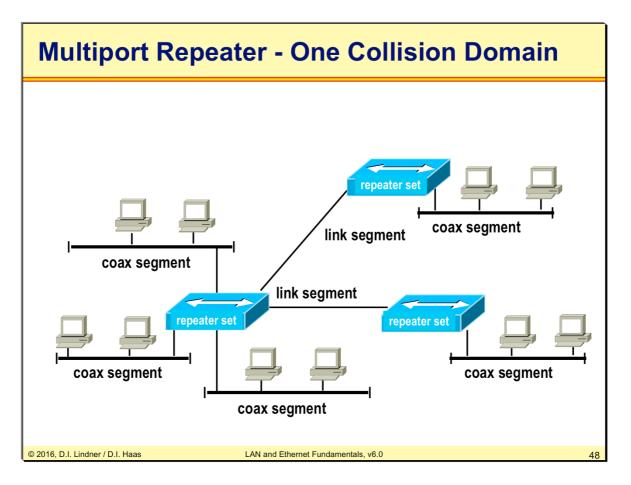
Repeater is an <u>amplifier</u> expanding the maximal distance of an Ethernet-LAN segment. It regenerates signals on the receiving port, amplify them, and send these signals to all other connected net segments (no buffering, just a short delay, which must be taken into account for the collision window / slot-time). In case a collisions is detected all other ports are notified by jam-signal. Optionally auto partition on erroneous ports may be performed by a repeater.

Coax segment: the shared media as bus for network stations

Link segment: a physical point-to point connection between two devices

Important: Collision domain is preserved by repeaters.

Local repeaters directly connect two (coax) segments. Remote repeaters are connected by so called linked segments which are point-to-point links between repeaters.



Link segment: a physical point-to point connection between two devices

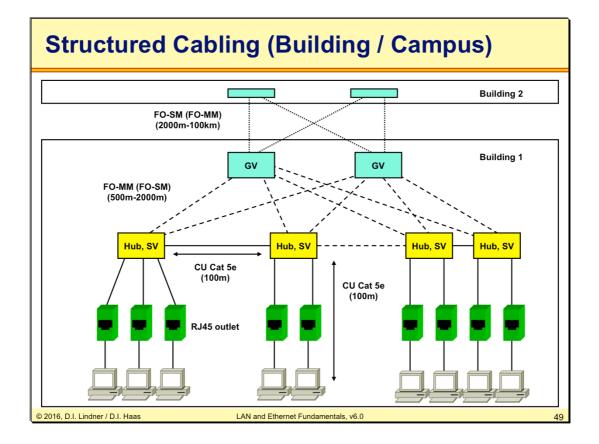
First link segments were used for repeater interconnection only. Several types were defined (fiber based, copper based):

FOIRL (Fibre Optic Inter Repeater Link: maximal length 1000m, for repeater - repeater)

10BaseFL (asynchronous, maximal length 2000m for repeater - repeater, end system - multiport repeater)

10BaseFB (synchronous (idle signals during communication pauses), maximal length 2000m, for repeater - repeater links only

10BaseFP (passive hub, no active repeater function, remark: active means electrically powered)



So far we have seen mainly coax cables for Ethernet, but physical wiring within buildings and between buildings should follow the principle of structured cabling, which is a standard for nowadays wiring of buildings.

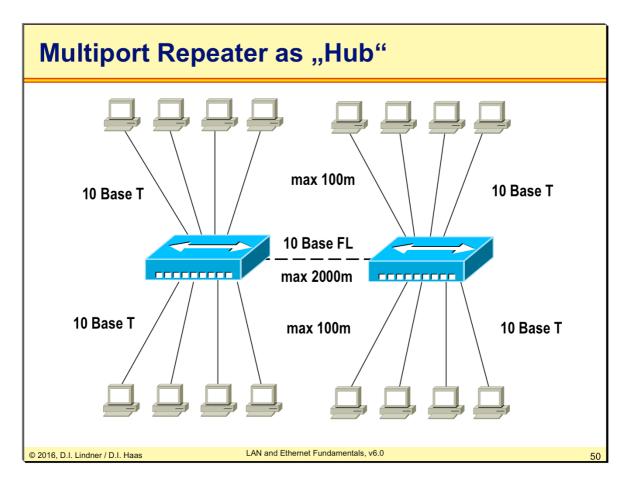
An example for structured cabling is outlined in the picture.

Primary cabling:

End system to first "Hub" (Repeater or nowadays a L2 Switch) "Stockwerkverteiler" CU-UTP, Category 5e or better FO for extreme conditions only

Secondary cabling: Hubs to central functions "Gebäudeverteiler" FO-MM (FO-SM)

Tertiary cabling: Interconnections of buildings FO-MM (FO-SM)



The link segment was later also defined for connection of a network station (end system) to a multiport repeater using a dedicated physical point-to-point line.

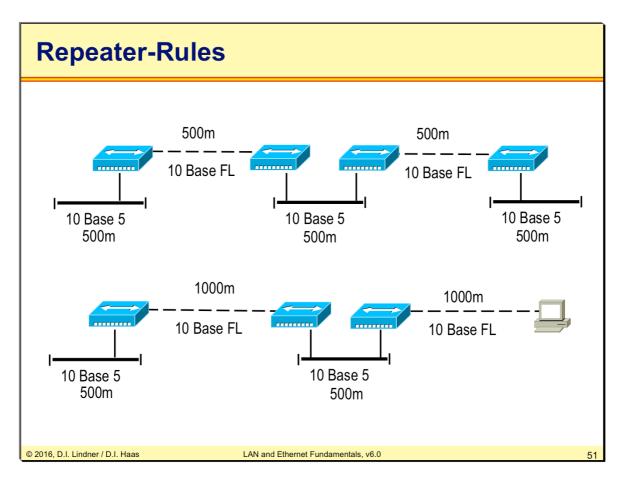
The reason: Ethernet was originally based on coax cabling and bus topology which was hard to wire in a building. Later an international standard for **structured cabling** of buildings was defined which was star wired to (a) central point(s) based on twisted pair cabling. That excellently fits to Token ring cabling at that time. Ethernet had been adapted to that in order to survive. Otherwise Token ring would have won the LAN battle. Ethernet standard 10BaseT supporting structured cabling was created in order to reuse the voice-grade twisted-pair cables already installed in buildings. 10BaseT had been specified to support Cat3 cables (voice grade) or better, for example Cat4 (and today Cat5, Cat6, and Cat7).

The first implementation of such link segment was 10BaseT (unshielded twisted pair, maximal length 100m, 2 lines Tmt +-, 2 lines Rcv+-, RJ45 connector, Manchester-Code with no DC offset). In such an environment the collisions can not be detected any longer just by measurement of the DC level as done in 10Base5 because tmt and rcv travels on different physical lines. Now a collision is interpreted, if signals are on the tmt and rcv line at the same time. The repeater has to watch out, if two or more signals are received at the same time (-> that means collision in the LAN). Now the hub has to produce a Jam signal on all ports in order to signal a collision to all systems. During transmission pauses a "Start of Idle" signal followed by periodic link test pulses (LTP; every 16ms a 100ns lasting puls) is sent. LTP is used to check the link state. No LTP signal received on the wire means disconnected.

We can see: the method of collision detection is different for every physical layer.

In 10BaseT, the Manchester code is sent symmetrically, with no DC offset. Collisions are detected in the repeater hub, which can observe when two or more devices are transmitting at the same time. Normally, the hub does not repeat a station's own signal back to the station on its receive cable pair. However, when a collision is noted, the hub does send a signal (the so-called "collision enforcement", or "jam") to the transmitting stations. The stations detect collisions by noting when they see a signal on their receive pair at the same time that they are transmitting on their transmit pair.

A repeater with more than two segments and different physics is called a multiport repeater. Multiport repeater in a star like topology is called a "Hub". Be careful using this expression because it is also used for L2 Ethernet-Switch which is a packet switch but not an amplifier like a repeater.



The collision domain of a 10Mbit/s Ethernet LAN is limited by the slot-time of 51,2 microsecond. Topology of repeaters must obey this budget. Therefore so called repeater rules existed for cabling an Ethernet LAN.

Maximal 5 segments over 4 repeater-sets are allowed, in this case 2 segments have to be linksegments (rest arbitrary), length of fibre optic link segments must not exceed 500m each

-> results in a maximum diameter of 2500m

On 4 segments with 3 repeater-sets, the length of a fibre optic link segment must not exceed 1000m, the segments may be mixed in any desired way

-> results in a maximum diameter of 3000m

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Ethernet Version 2 Frame (aka DIX Frame -> DEC, Intel, Xerox)					
Ethernet Version 2 ("Etherr Preamble DA SA Type	net II") data	FCS			
(6 DADr SASc TypePr DataPa FCSFr	or clock synchronization (64 Bit) 2 bits 1010101010 + 2 bits 11 as SD) estination MAC-Address (48 Bit) ource MAC-Address (48 Bit) rotocol-type field (16 Bit) ayload rame Check Sequence (32 Bit) ased on CRC (Cyclic Redundancy Check)			
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Some Ethernet parameters:

Interframe gap between to Ethernet frames is 9.6 microsecond.

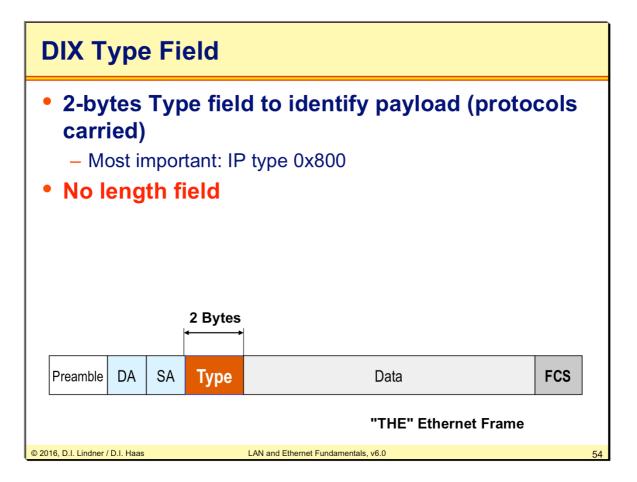
Jam size is 32 bit.

Slot time is 512 bits, minimal frame length 64 Byte

Maximal frame length 1518 byte (6+6+2+1500+4)

Maximum number of frames on a 10 Mbit/s Ethernet: 14880 frames of minimal length per second

(6+6+2+46+4, FCS counted, preamble not counted)



The Type field used by the DIX Eth2 frame format is 16 bit in length and allows therefore to address up 65 536 different layer 3 processes. The Type field only allows the addressing of the destination service access point. The indication of the source service access point is not supported by the DIX frame format. Typically only layer 3 processes of the same kind are able to communicate with each other.

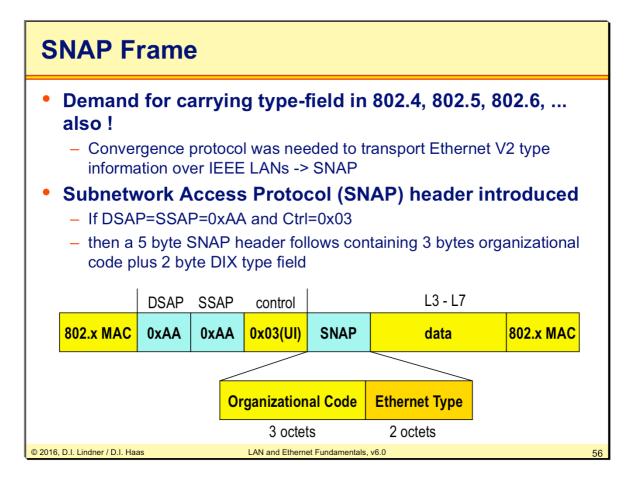
Some Type field examples:

Hex 0800	IP
Hex 0806	ARP
Hex 8035	RARP
Hex 814C	SNMP
Hex 6001/2	DEC MOP
Hex 6004	DEC LAT
Hex 6007	DEC LAVC
Hex 8038	DEC Spanning Tree
Hex 8138	Novell

IEEE 802.3/802.2 Frame								
802.3 v	vith 80	2.2 (LLC)					
Preamble	DA	SA	Length	DSAP	SSAP	Ctrl	data	FCS
		46	/ -1500	∢ lay	er 2 (Ll	LC)		
Length field instead of Ev2 type field Additional 802.2 LLC header for implementation of HDLC-like protocol procedures on LAN wire Length Of IEEE 802.3 frame (16 Bit) = bytes following without FCS (46-1500) LLCLogical Link Control (HDLC for LAN) DSAP (Destination Service Access Point) 8 Bit SSAP (Source Service Access Point) 8 Bit Ctrl (Control) (8 or 16 Bit)								
 Ethernet II and 802.3 can coexist on the same cable, but each associated sending and receiving station must use the same format. 					nding			
 Fortunately all type-field values are larger than 1518 (max frame length), so any incoming frame can be recognized and handled properly. 					any			
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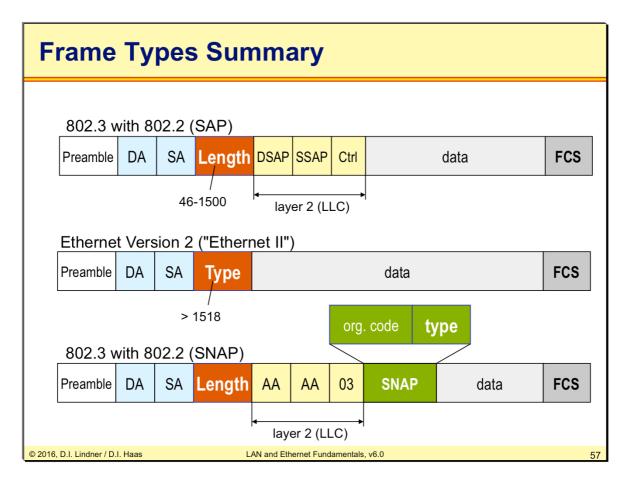
IEEE 802.3 relies on LLC (802.2) and SAPs -> the protocol-type is indicated by SSAP and DSAP and the LLC control field can provide connectionless and connection-oriented services to the upper layers.

Ethernet Version 2 uses a protocol-type-field instead of the length field and lacks from any kind of HDLC like control field. Therefore only connectionless services can be provided by Ethernetv2 to the upper layers.



The IEEE had problems to address all necessary layer 3 processes, due to the short (8 bit) DSAP and SSAP fields in the IEEE header. So they introduced a new frame format which was called Subnetwork Access Protocol (SNAP). The SNAP format was simply importing the DIX Type field by the backdoor. This new header format was then also used for technologies like Token Ring, Token Bus, DQDB, etc.

In the SNAP format the DSAP and the SSAP is set to the hex value of AA. This indicates an five byte extension to the standard 802.2 header, which is made up of a three byte long field called Organization Unique Identifier (OUI) and the two byte Type field.



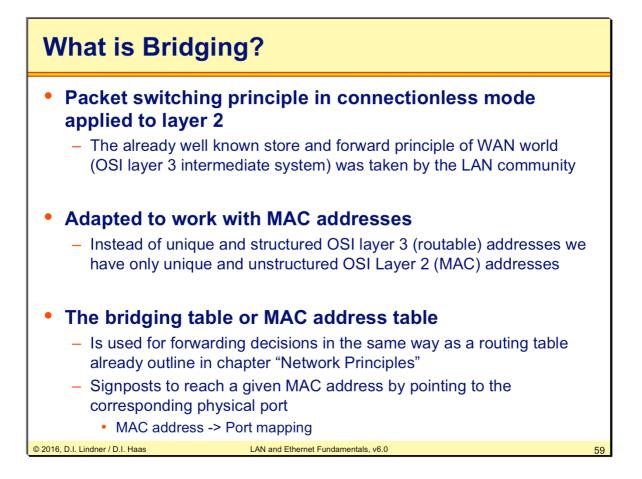
So we end up with three different frame formats used in Ethernet systems. The 802.3 without SNAP, the DIX Eth2 format and the 802.3 with SNAP.

The DIX Eth 2 frame format is mainly used for the data transport of protocols that have the functionality of error recovery and flow control implemented in their protocol stack e.g. IP.

The 802.3/802.2 without SNAP frame format is used for protocols that need the functions of error recovery and flow control on layer 2 e.g. NetBeui, SNA.

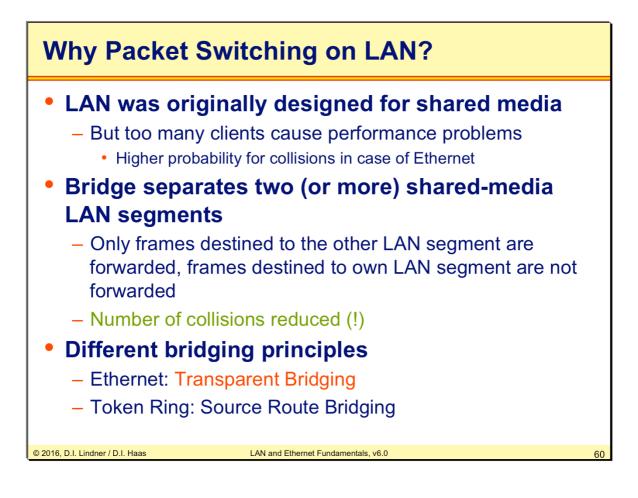
The 802.3/802.2 with SNAP frame format is used by vendors to implement proprietary protocols, for example Cisco's CDP, VTP, CGMP, etc. protocols. For such purposes the OUI field is used to indicate the vendor and the type field value is chosen vendor specific.

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Remember: Packet switching in connectionless service mode relies on unique, structured addresses and routing table. The content of a routing table is used as "signposts" for reaching a given destination address.

The bridging table contains information about which port to be used to reach a certain MAC address.



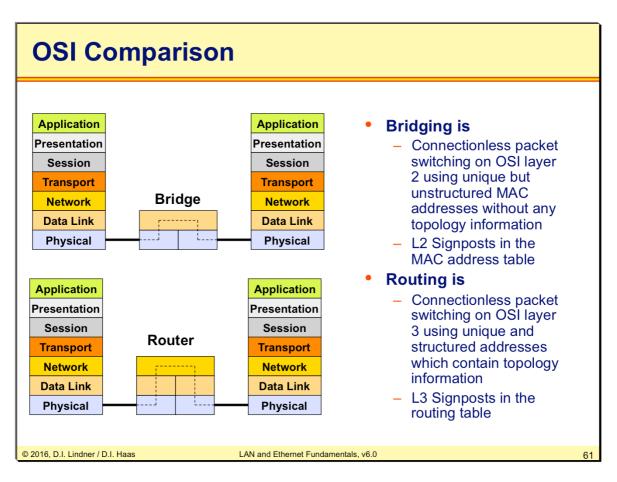
Bridges forward layer 2 packets (frames) according to their destination address. Hereby, those frames are filtered whose destination is not reachable on another port of the bridge. This filtering capability significantly enhances the total performance of a LAN as it is divided into multiple segments—multiple broadcast domains: The number of collisions is reduced!

IEEE defined bridges for all kind of LAN technologies. For example a Token Ring network relies on so-called source route bridging, while Ethernet uses "Transparent Bridging".

Transparent Bridging (Ethernet world) is easy for end systems but there are much more complex transferring-decisions (compared to source route bridging) done by a bridge -> dedicated hardware. Today's L2 switching technology (= Ethernet switch) is just a <u>fast</u> transparent bridge. This chapter only discusses Transparent Bridging.

Source Routing Bridging (Token Ring world, IBM) means more overhead for end systems (path finding) but source route bridges are less complex (task of such a bridge could be done e.g. by a PC with two network cards). We will not further cover this in this lecture.

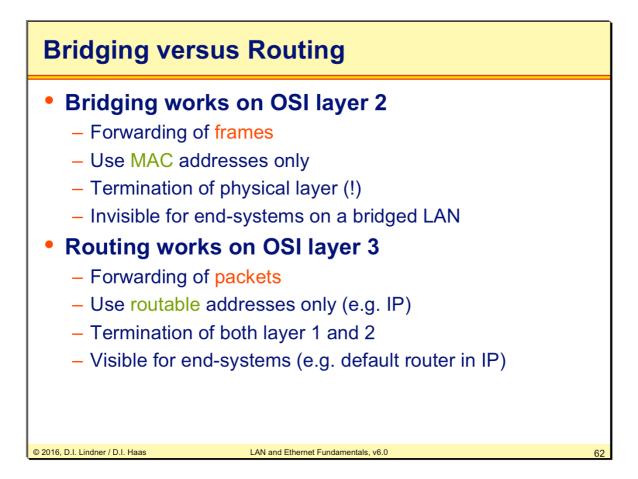
Partitioning of a local are network may additionally be used for error limitation, because of security reasons, increase the number of clients on A LAN or even to extend the geographical diameter of the LAN by placing a bridge every 2500m between two adjacent LAN segments (which have reached their maximum diameter by obeying the repeater rules).



It is very important to understand the differences between bridges and routers. There are many implications related to the operating layer these devices support. As a rule of thumb any device is able to terminate all layers below the highest layer implemented.

Bridge is a packet switch implemented on OSI layer 2. Forwarding is based on unstructured MAC addresses, signposts are stored in MAC bridging table (= routing table of L2 packet switch). Above OSI Layer 2 bridges are transparent for all higher layer protocol. For any two stations connected to a bridged Ethernet network the bridge is not even visible for them, hence transparent. No L2 address of a bridge has to be configured in an end-system in order to enjoy communication on a LAN.

A router is packet switch implemented on OSI layer 3. Forwarding is based on structured L3 addresses and any end system must speak the corresponding L3 "language" of the router, hence the router is a visible component the end system must know about (e.g. in IP you have to configure the IP address of the default router).

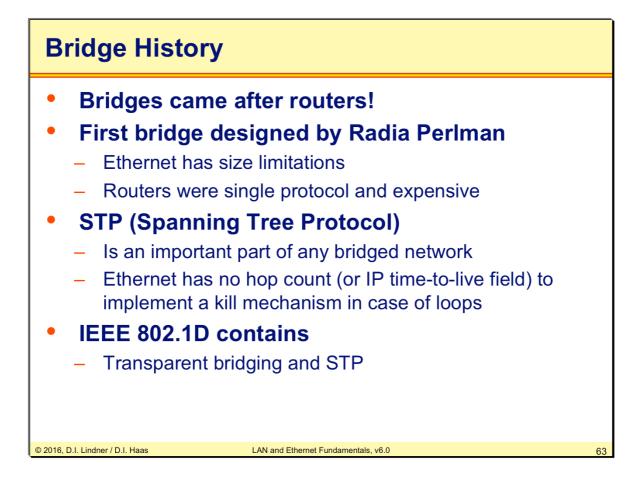


There are many differences between bridging and routing! The only thing in common is the store and forwarding principle, based on some sort of destination address.

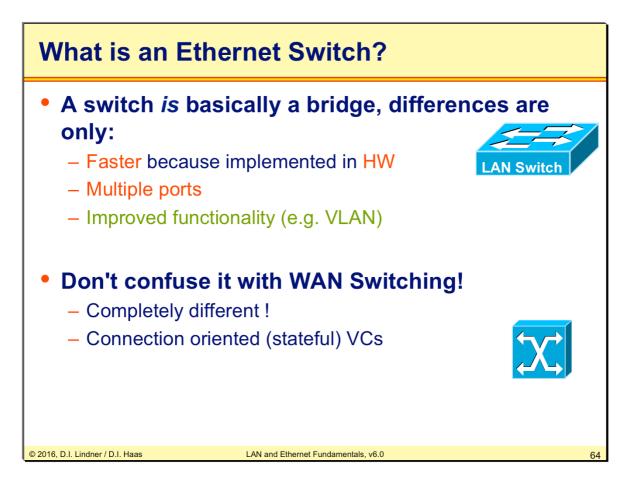
But a bridge forwards layer 2 frames while a router forwards layer 3 packets. Layer 2 frames use simple MAC addresses, having no logical structure, while layer 3 packets use structured addresses, revealing topology information. Only layer 3 addresses are routable. In order to understand the latter statement, it is important to understand the principles of routing and how a routing table works. We will discuss this soon.

Bridges terminate physical links. Thus, one port of the same bridge might support optical fiber transmission and another port might support twisted pair copper cabling.

On the other hand, routers terminate layer 2 links. That is, one interface might utilize Ethernet as link layer technology, another interface Frame Relay, and a third interface might run ATM. A router only forwards the packet—the layer 3 information—carried inside a frame.

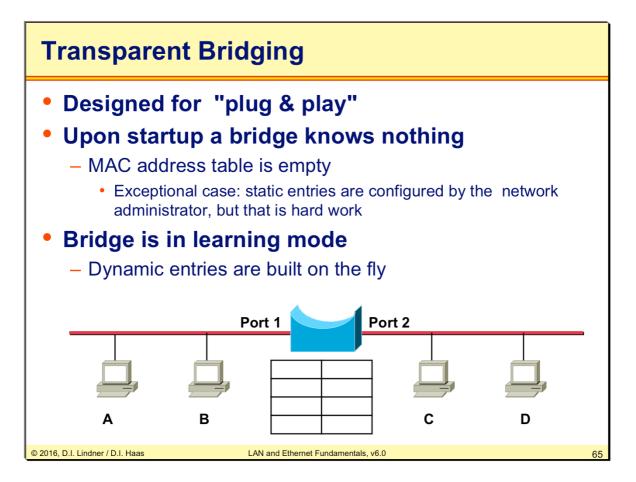


Bridging is a fundamental part of the IEEE LAN standard. Actually bridges were invented relatively late—routers were invented a bit earlier. Radia Perlman, a pioneer in data communication designed the first bridge. The main reason was to extend the total network diameter of Ethernet and to provide a transport technique which supports multiple layer 3 technologies. She also invented the Spanning Tree Protocol (STP) because Ethernet had no hop count, thus any store and forwarding technology would suffer from broadcast storms, when broadcast destination addresses are used. But this issue is discussed in more detail in the following chapter. The IEEE standard 802.1D specifies bridging and spanning tree (and more).



Now what is the difference between a bridge and a switch? Logically there is no difference. Ethernet switching is much more a marketing term to express something new to the customers but basically it is the same as a transparent bridge. An Ethernet switch is just faster and has much more ports than the good old bridge. Ethernet switches typically employ more than two ports, and the bridging functionality is implemented in hardware. Additionally other features like VLAN (Virtual LAN) support or NAC (Network Access Control) are added in modern Ethernet switches, depending on the vendor

Note: Don't confuse LAN switching with WAN switching. Unfortunately modern bridging is called switching but logically it is still bridging. The term "bridging" was originally defined to differentiate this technique strictly from WAN switching. The main characteristic of WAN switching is its connection oriented behavior—WAN switches are never transparent! In order to connect to a WAN switch the end system must comply to some specific User to Network Interface (UNI).



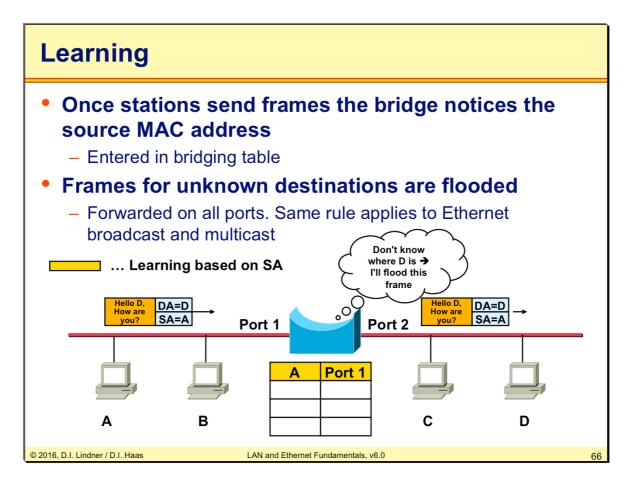
The main advantage of transparent bridging over source route bridging (token ring) is the transparency or "plug & play" capability. No end station notices the presence of bridges. Bridge is invisible for end stations. LAN Left and LAN Right appear to the end systems like one single, logical, big LAN. But because of this transparency a bridge must receive and process every frame on a LAN. This means much more performance is needed for a bridge than for a router which is explicitly addressed. Also flow control between end systems and bridges was not defined in the original implementation.

Transparent bridge uses layer 2 MAC-addresses to decide if a given frame must be a forwarded or not -> destination-address of a frame is used for this decision.

But in order to be invisible, bridges must also learn somehow where end stations are located.

MAC-addresses of all stations are registered in a bridging table either statically done by administrator e.g. for security reasons or dynamically done by a self-learning mechanism.

Following the self-learning mechanism upon startup, a bridge knows nothing and the bridging table is empty. At this time the bridge is in learning mode. For learning the source-address of a frame will be used.



Assume we have a bridge with only two ports, each attached at one Ethernet segment. Assume the left station "A" sends one frame to "D" on the right side. Obviously the bridge learns the location of A but has no idea where D is. Thus the MAC address of A is entered in the bridging table and also the port number "1", on which A is reachable. Since the location of D is unknown, the bridge loods this frame over all ports, in our case only to port two (as there are no other ports).

This way, connectivity is granted even if there is no entry in the bridging table.

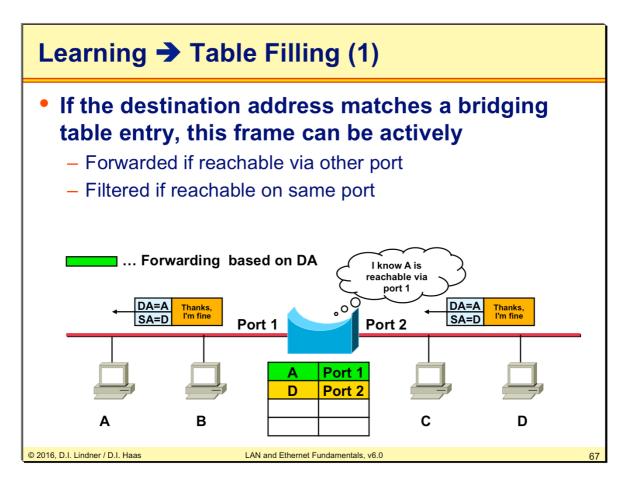
Destination address of a frame is used for MAC address table look up in order to decide what have to be done with the received frame. The following actions are possible:

<u>Filtering</u>: frame will be rejected if destination's home is on the LAN segment of the receiving port

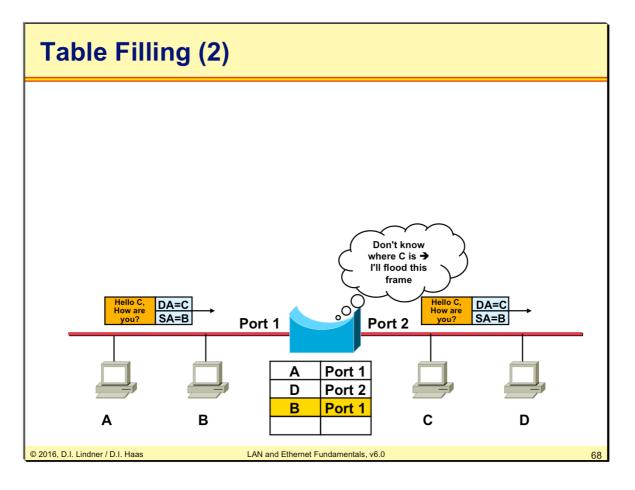
Forwarding: a duplicate of the frame will be forwarded to the appropriate port if destination's home is registered in the table of another port

Flooding: during learning time; frame will be forwarded to all other ports (multiport-bridge) if there is no entry in the table (unknown destination).

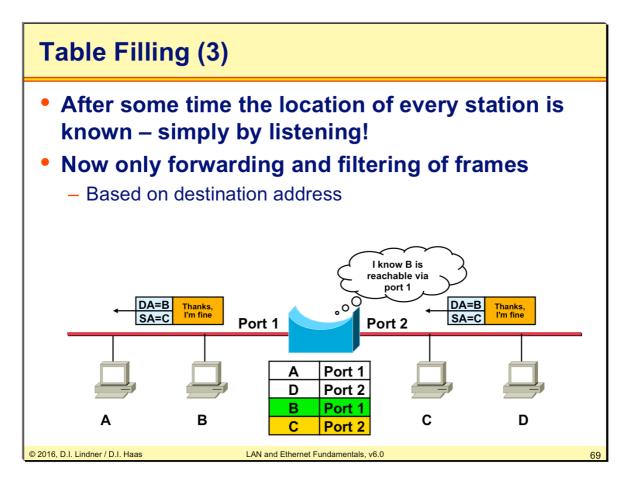
Frames with broadcast/multicast-address are always flooded.



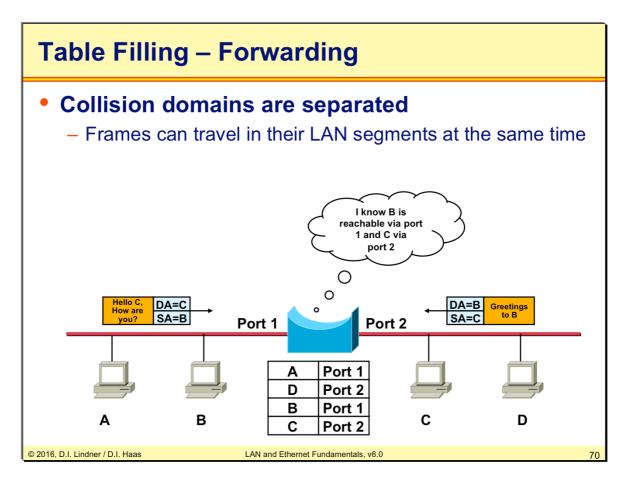
Now assume D replies to the message which has been received from A. The bridge knows already the port number over which A can be reached and forwards the frame accordingly. If A would be located on the same port as D then this frame would be filtered.



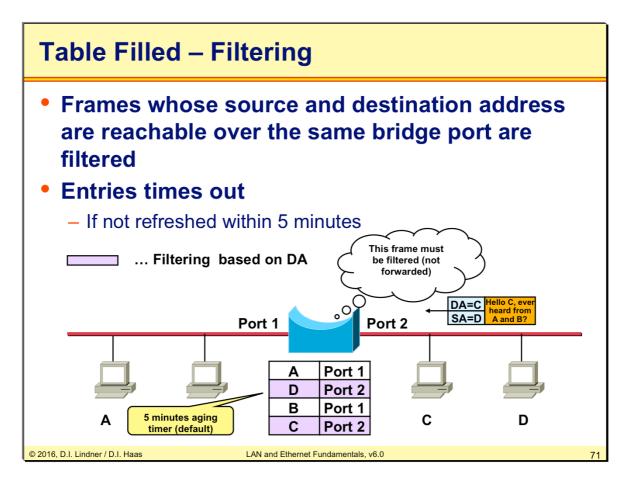




After some traffic observing time, the bridging table contains all host locations (addresses and port numbers). At this time the bridge enters the forwarding and filtering mode.

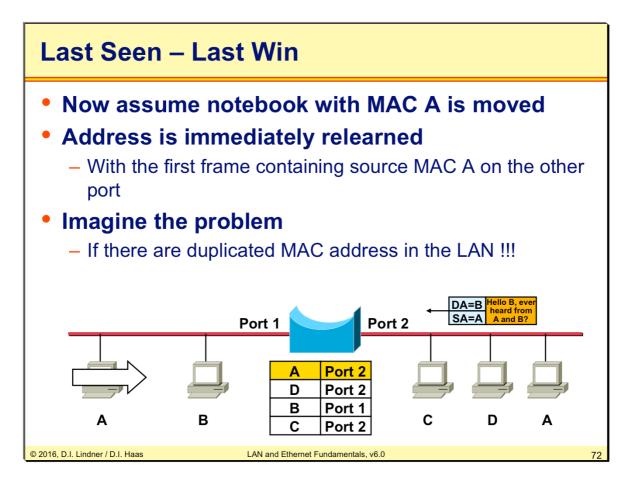


Since only frames are forwarded to other ports whose destination is really located there, the LAN is separated into as many collision domains as ports are available (and attached to a LAN segment).

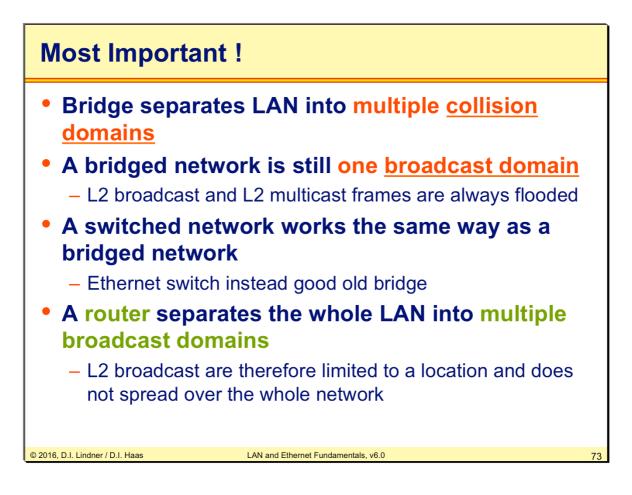


What if a host is removed from its location and attached at another place in the LAN? Obviously frames could be forwarded to the wrong port. Therefore each entry in the bridging table ages out after some time. The default aging time is 300 seconds or 5 minutes.

In case of a dynamic bridging table an aging mechanism allows for changes of MAC addresses in the network which may caused either by change of network card or by location change of end system. If an already registered MAC address is not seen within e.g. 5 minutes as source address of a frame the corresponding bridging table entry is deleted.



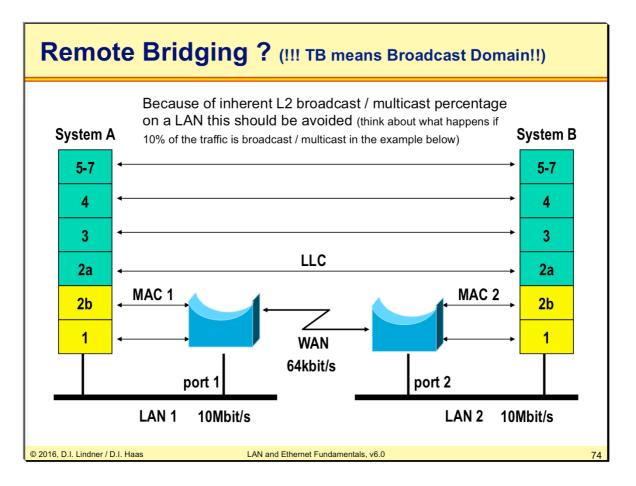
Duplicated MAC addresses would cause continuous table rewriting on a last seen – last win base.



It is very important to understand the basic message which is given here:

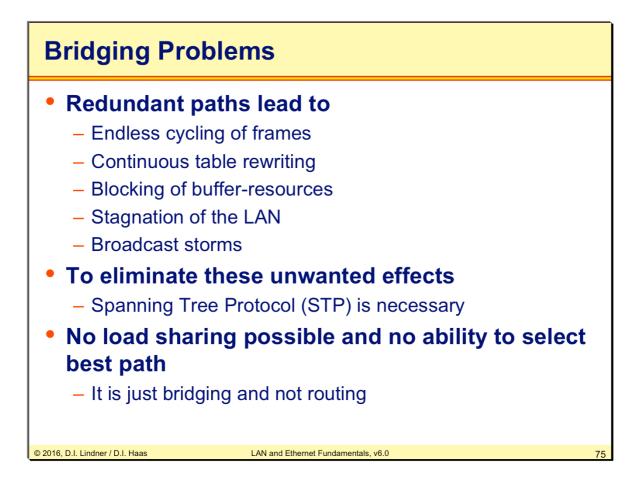
The use of bridges results in a separation of multiple collision domains of the LAN. Still we have one single broadcast domain! That is, broadcast frames are always flooded throughout the network.

Only the use of routers results in a separation of multiple (layer 2) broadcast domains—or the use of VLANs, which will be discussed soon in this chapter.



Relay function of local bridge can be split in two half-bridges. Coupling of the half-bridges via slow WAN-connection is a problem in case of high amount of broadcast on a LAN. The mismatch of bit rate can cause a buffer overflow in the bridge and frames will get lost in this case.

Therefore transparent bridging over WAN or any other Ethernet tunneling technique should be avoided !!!

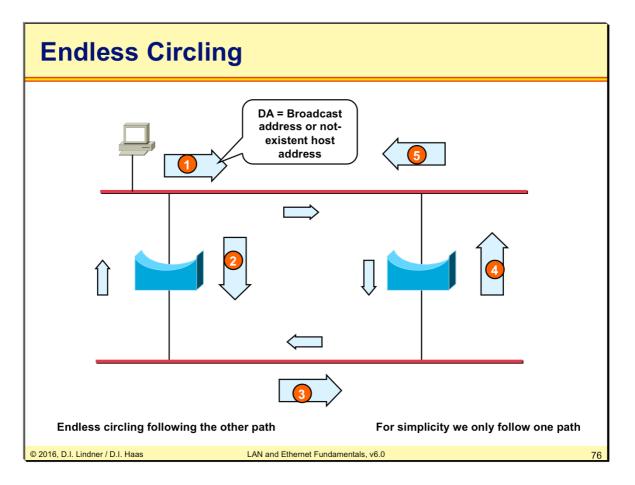


You might have noticed that bridges do not really learn the network topology. They only learn a simple destination to port association! Because of this there is no means to determine the best path, and furthermore frames might be caught in a loop.

Especially broadcast frames have no defined destination and would be forwarded over all parallel paths—endlessly! This results in endless circling of frames, or more dangerous, in a so-called "broadcast storm".

Also a continuous table rewriting might occur (this is not so widely known but also explained in the next pages).

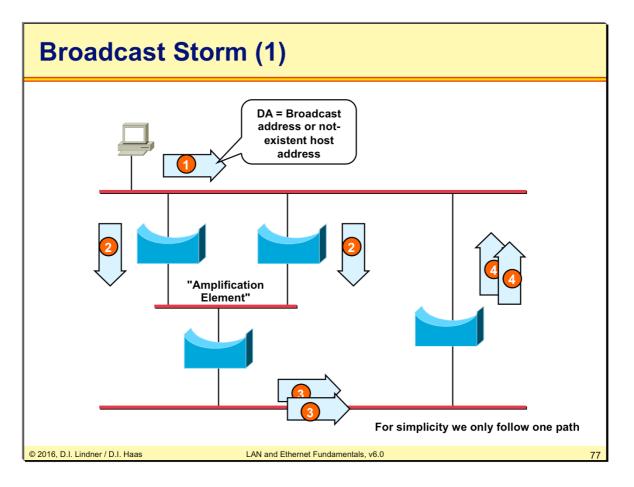
Most people are not aware that frames might be stored up to 4 seconds inside the buffer of a switch—and it still complies to the IEEE standard. Although this would happen only in rare cases of congestion, transparent bridging is not suitable for hard realtime applications. Today the situation has changed, QoS features are included to assure bounded delays.



The picture above illustrates the endless circling phenomena. Assume a network with parallel paths between two LAN segments, realized by two bridges. Any frame with a broadcast destination address would be forwarded by both bridges to the other segment and back and forth and so on.

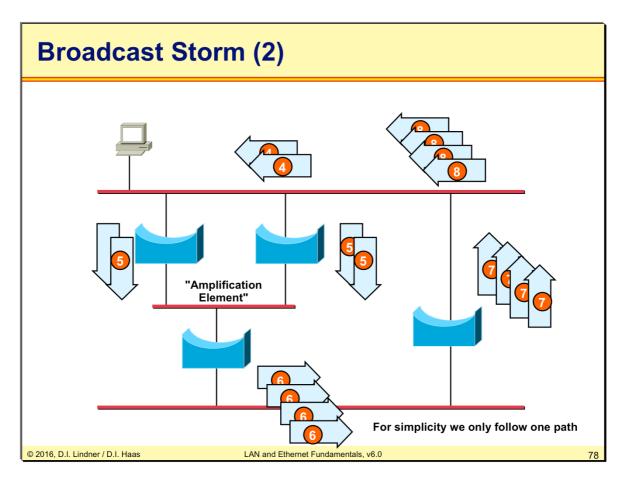
Obviously endless circling leads to congestion problems an is not desired. Remember that there is not hop count or time-to-live number within the Ethernet header.

But endless circling is not the main problem... (see next slide)

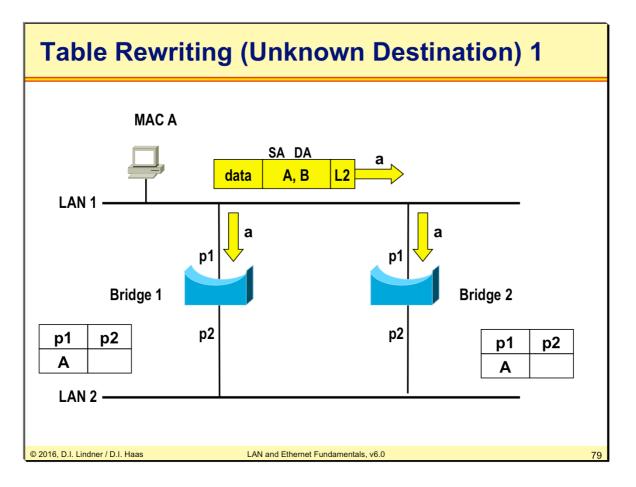


The most feared issue with bridging are broadcast storms. Broadcast storms can be considered as a dramatically "enhanced" endless circling problem. Broadcast storms appear when there is an "amplification" element within the network, such as those threefold parallel paths in the diagram above.

Within a very short time (e.g. 1 second) the whole LAN is overloaded with broadcast frames and nobody could transmit any useful frame anymore.

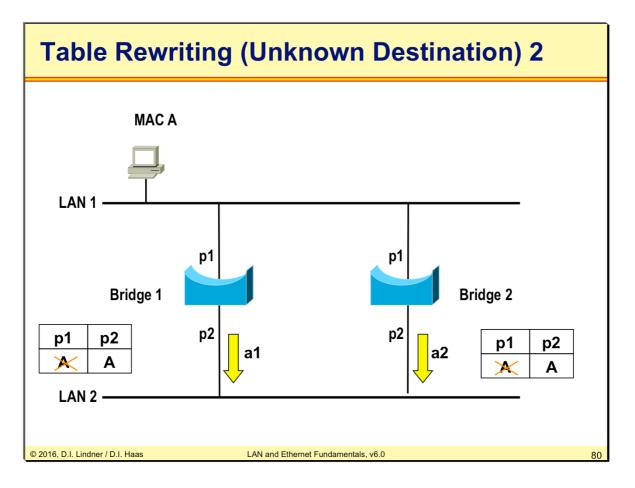


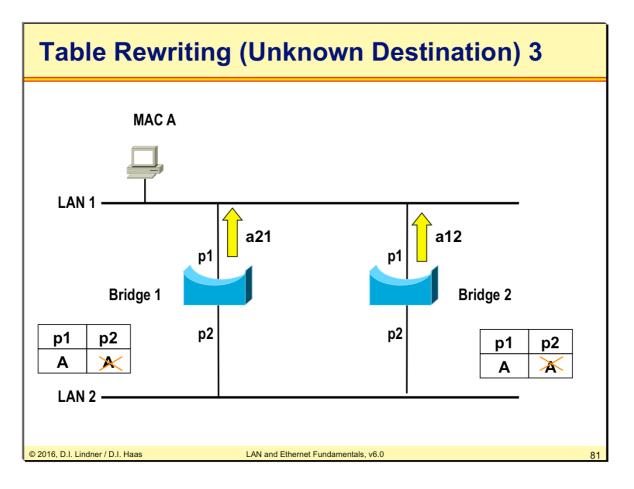
The picture above shows the amplification effect mentioned on the previous page.

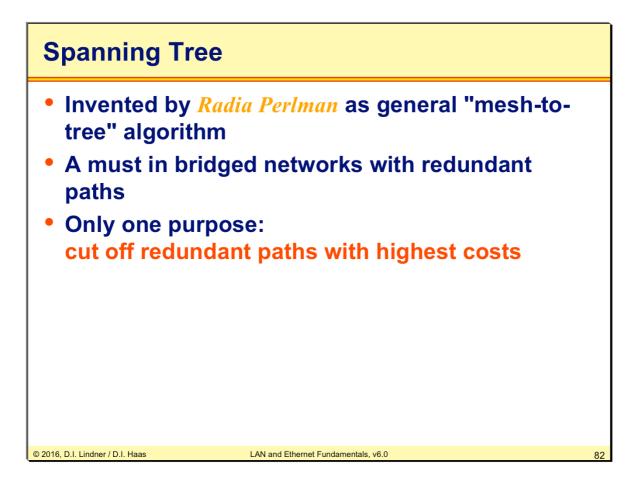


A relatively seldom known problem is the mutual table rewriting phenomena. This problem occurs with unicast frames and broadcast frames!

Assume that host A sends an unicast frame to an unknown destination B, both bridges learn the location of host A but B is unknown and hence must be flooded. If the other bridge receives this flooded frame it will change the table entry for MAC to be seen on the other port (last seen last win!). But again this frame has to be flooded and the game just go on ... ad infinitum!



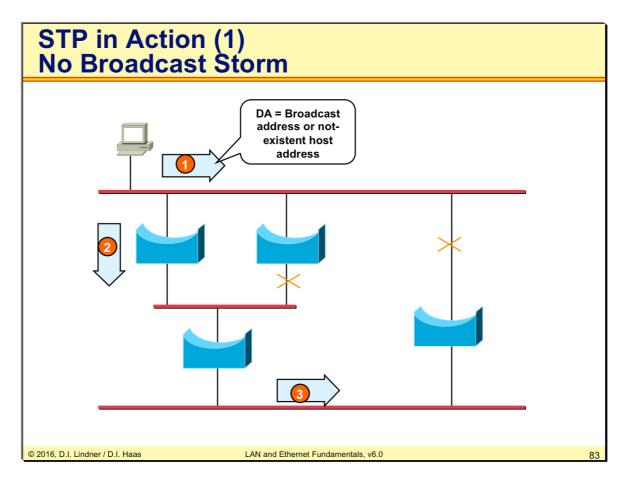




Now we have learned that active parallel paths lead to severe problems in a switched (i.e. bridged) network. Therefore we can only overcome this problem by deactivating any redundant path. This should be performed automatically in order to call Ethernet bridging still "Transparent" bridging.

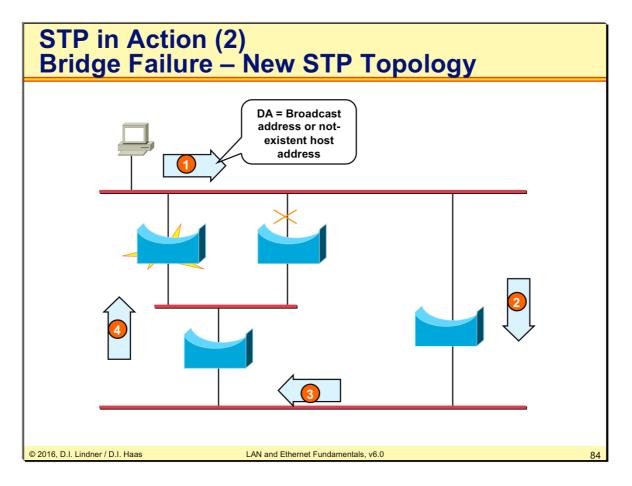
The inventor of bridging, Radia Perlman, also created an easy solution for the redundancy problem: The Spanning Tree Protocol (STP).

The STP is implemented in bridges only (not in hosts) and has only one purpose: To determine any redundant paths and cut them off! Hereby cost values are considered for each path in order to maintain the best paths.



STP eliminates redundancy in a LAN bridged environment by cutting of certain paths which are determined by the STP parameters Bridge ID, Bridge Priority and interface Port Costs. An easy way to achieve this is built a tree topology. A tree has per default no redundancy or have you ever seen leafs of a tree which are connected via two or more branches to the same tree?

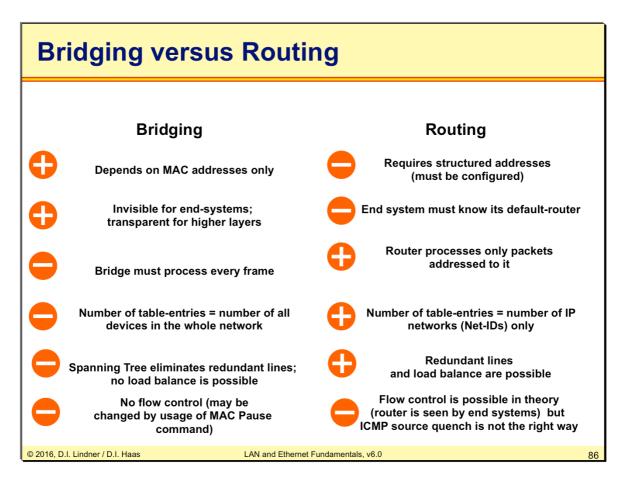
Spanning Tree Protocol (STP) takes care that there is always exact only one active path between any 2 stations implemented by a special communication protocol between the bridges using BPDU (Bridge Protocol Data Unit) frames with MAC-multicast address. The failure of an active path causes activation of a new redundant path resulting in new tree topology.



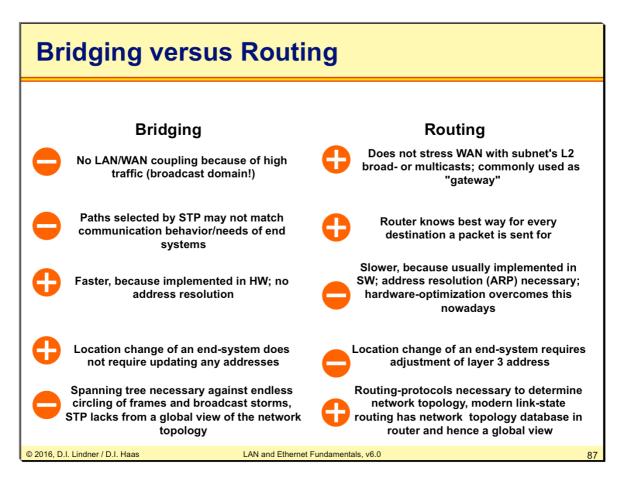
Additional task of STP is to recognizes any failures of bridges and to automatically build a new STP topology allowing any-to-any communication again.

Here you can also see one main disadvantage of STP: Redundant lines or redundant network components cannot be used for load balancing. Redundant lines and components come only into action if something goes wrong with the current active tree.

Agenda		
 Introduction IEEE 802 		
Logical Link		
 Legacy Ethe Introduction CSMA/CD Reporter Li 		
 Repeater, Li Framing 	ink Segments	
Transparent	Bridging	
• <u>Bridging ver</u>	<u>rsus Routing</u>	
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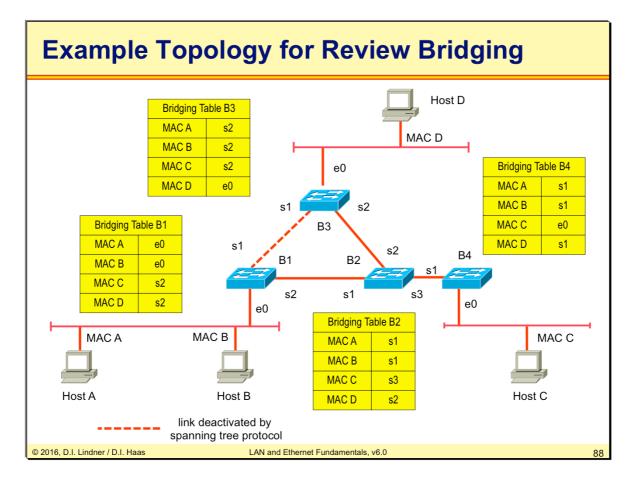


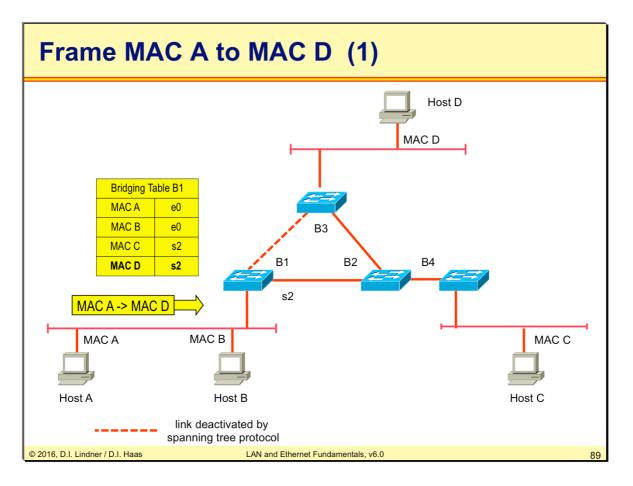
The list shown above summaries all pro and cons of bridging (switching) and routing.

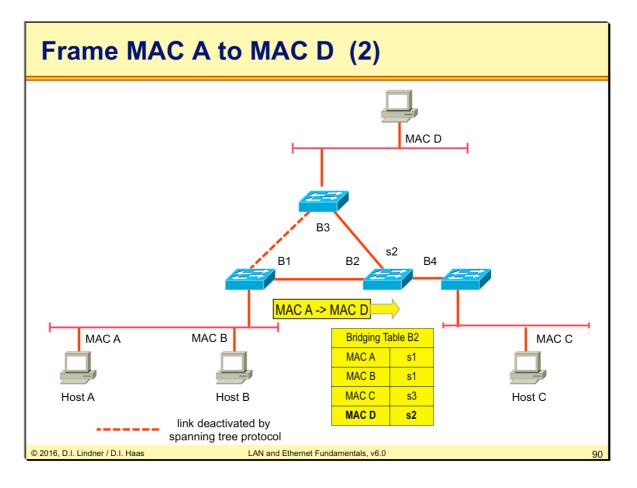


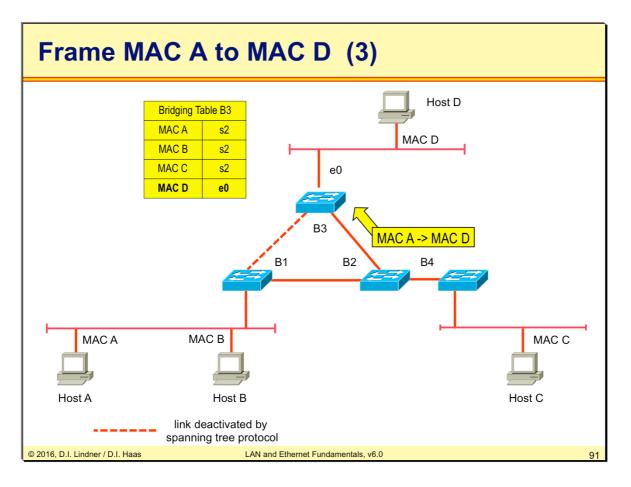
The list shown above summaries all pro and cons of bridging (switching) and routing (continued from previous slide).



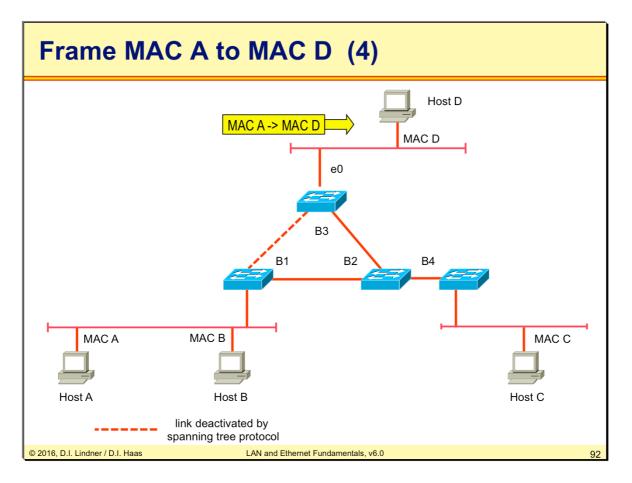




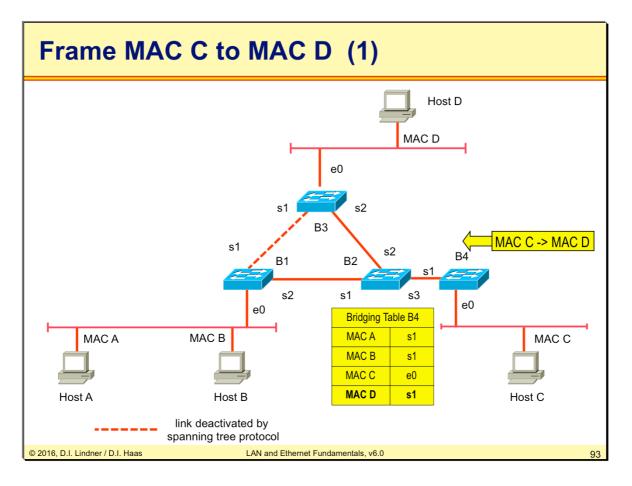


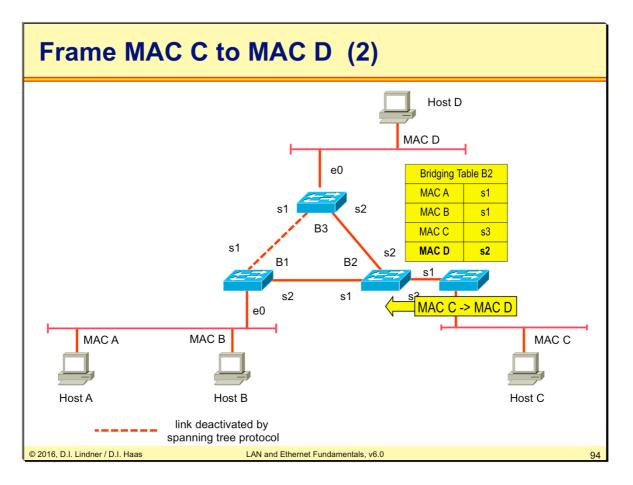


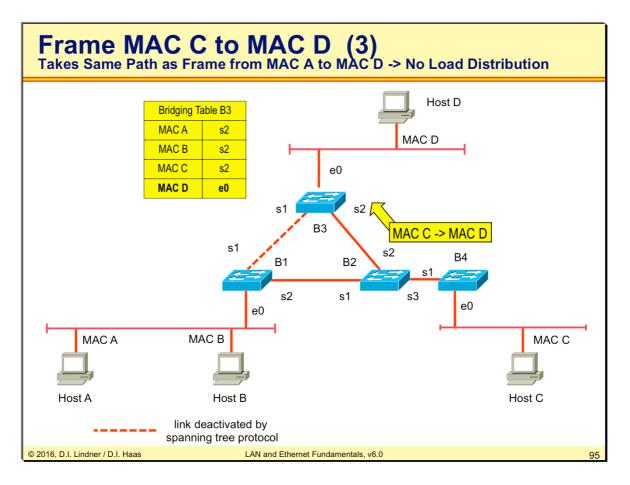




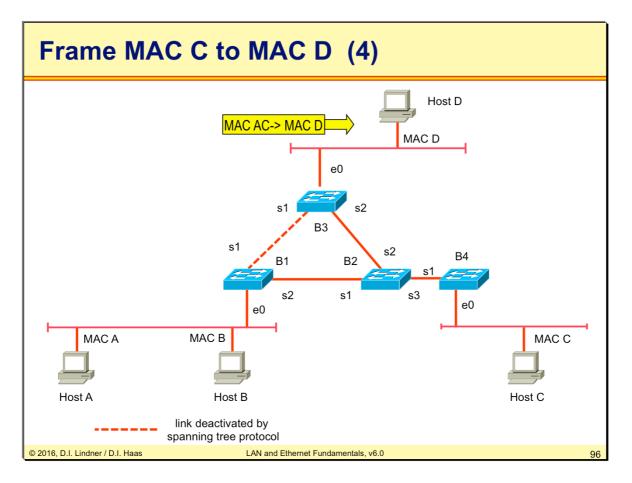












Requirements for Routing

Consistent layer-3 functionality

- For entire transport system
- From one end-system over all routers in between to the other end-system
- Hence routing is not protocol-transparent
 - all elements must speak the same "language"
- End-system
 - Must know about default router
 - On location change, end-system must adjust its layer 3 address

To keep the routing tables consistent

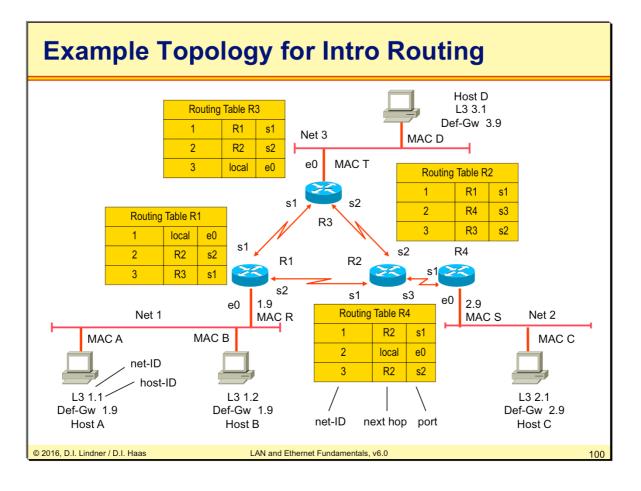
 Routers must exchange information about the network topology by using <u>routing-protocols</u> or network administrator has to configure static routes in all routers

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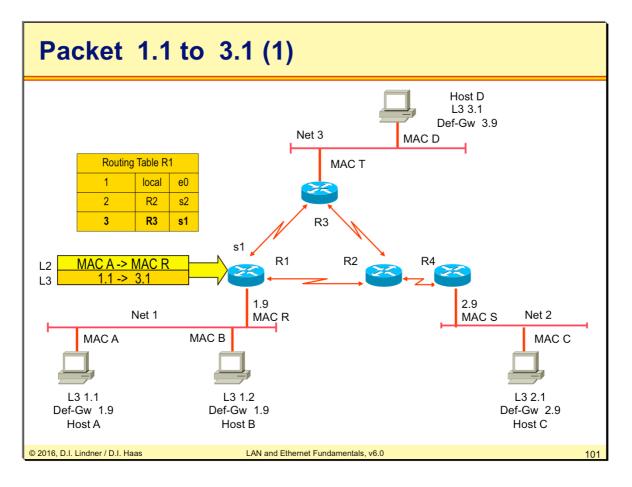
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Routing Facts 1		
 In contrast to bridges 		
 Router maintains only the network of the layer 3 addresses in its routing table 		
 The routing table size is <u>direct proportional to the number</u> of networks and not to the number of end-systems 		
 Transport on a given subnet 		
 Still relies on layer 2 addresses 		
 End systems forward data packets for remote destinations 		
 To a selected router (default gateway, default router) using the router's MAC-address as destination 		
 Only these (unicast MAC addressed) packets must be processed by the router 		
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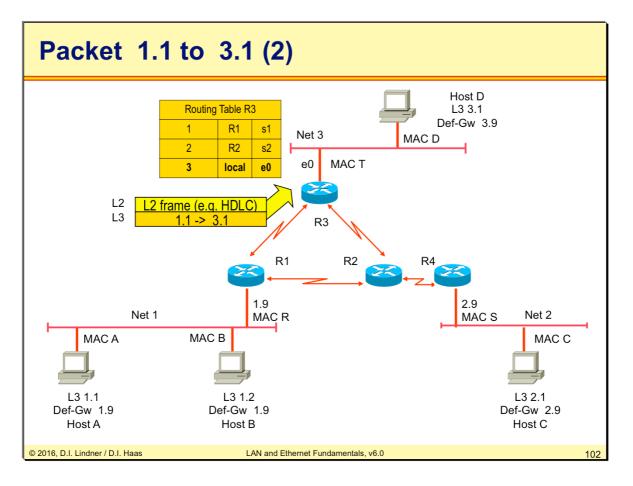
Routing Fact	ts	2
 Flow control principally p 	I between router and end syster	n is
 End systems 	s knows about the local router	
 L2 Broadcas subnet 	st/multicast-packets in the partic	cular
	by the router so L2 broad/multicast traff doesn't stress WAN connections	fic on
Independent	t of layer 1, 2	
- so coupling	of heterogeneous networks is possible	
	u se redundant paths ologies are usual	
 Routers can 	use parallel paths for load bala	ncing
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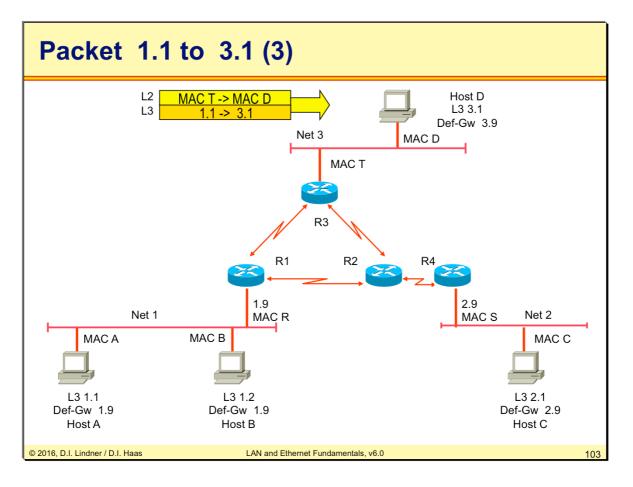




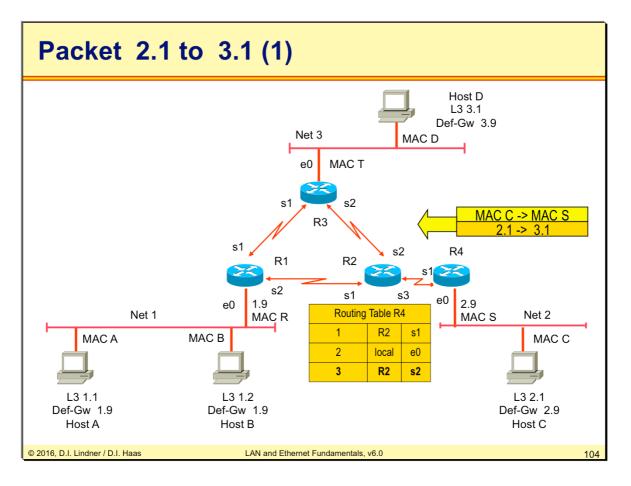




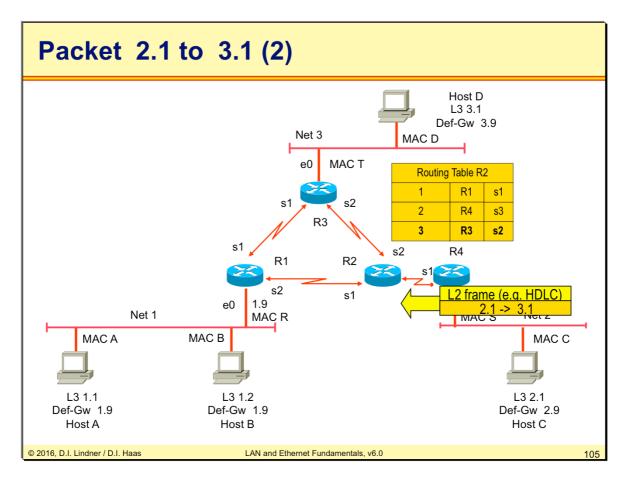


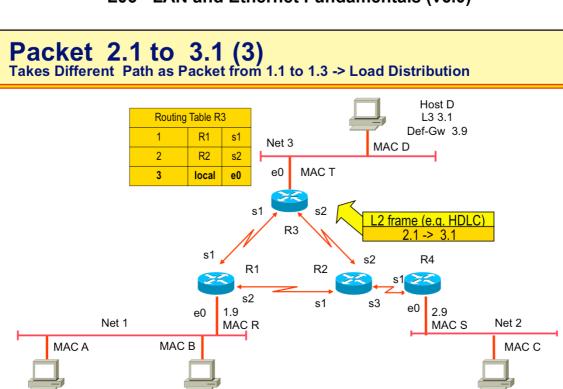












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L3 2.1

Def-Gw 2.9

Host C

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L3 1.2

Def-Gw 1.9

Host B

L3 1.1

Def-Gw 1.9

Host A

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