

Changes to version 2.0:

Chapter Multicasting was extended with new topics. IP multicast routing principles PIM-DM and PIM-SM are explained and multicast routing convergence is now covered.

Changes to version 2.1:

Pages 22, 23: additional content on slide

Changes to version 2.2:

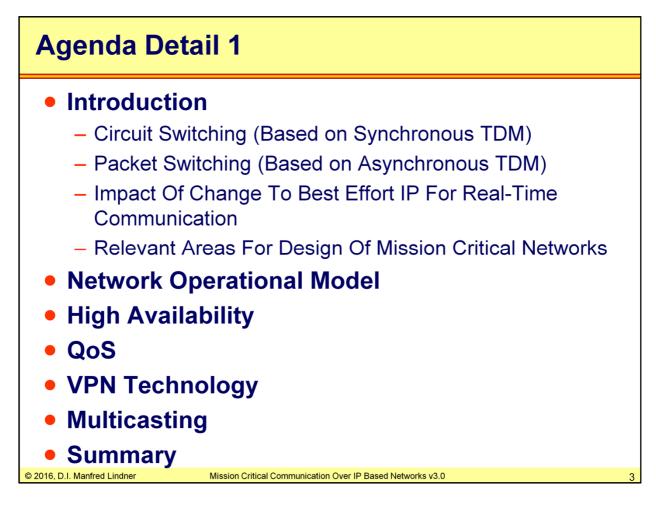
Some enhancements in the QoS subchapter: new slides at the end of the chapter Some typos removed and some text in the handout part improved.

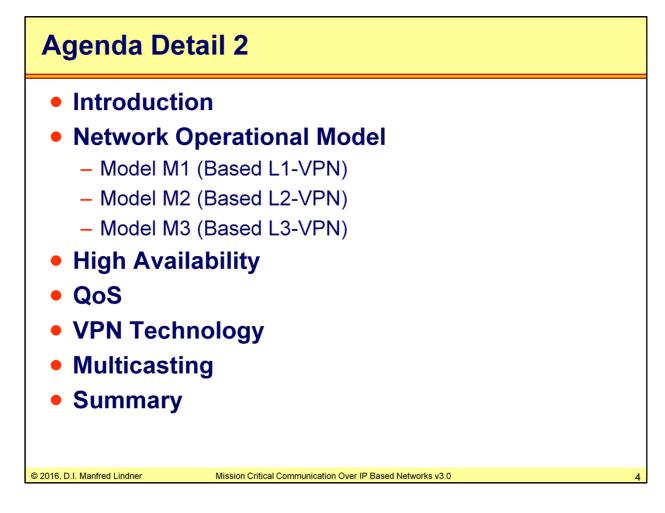
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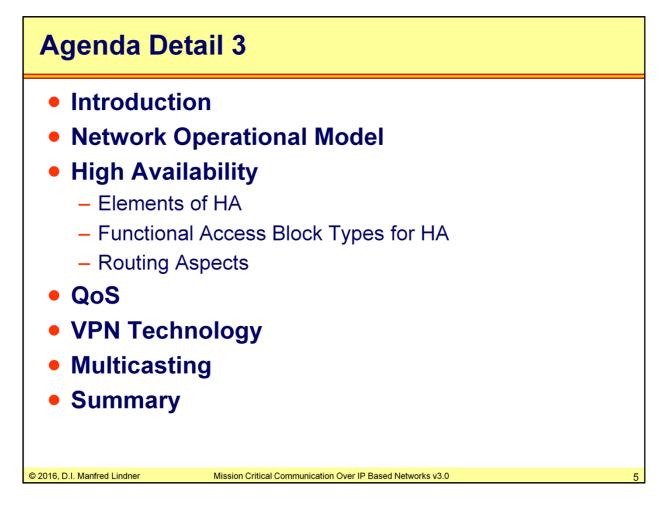
- Introduction
- Network Operational Model
- High Availability
- QoS
- VPN Technology
- Multicasting
- Summary

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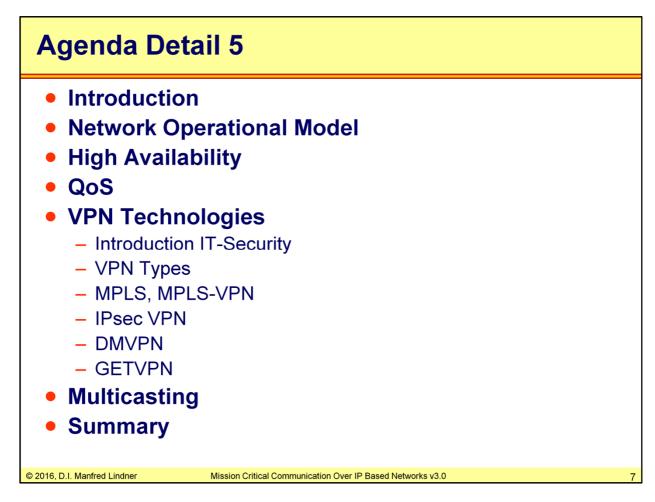
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Agenda Detail 4 • Introduction • Network Operational Model • High Availability • QoS • Introduction QoS • IP QoS Mechanism • QoS Handling M1, M2 or M3 Environment • VPN Technology • Multicasting • Summary



Agenda Detail 6 • Introduction • Operational Model • High Availability • QoS • VPN Technologies • Multicasting • Introduction • Multicast Routing Overview • Multicast & HA • Multicast & VPN / Security • Summary

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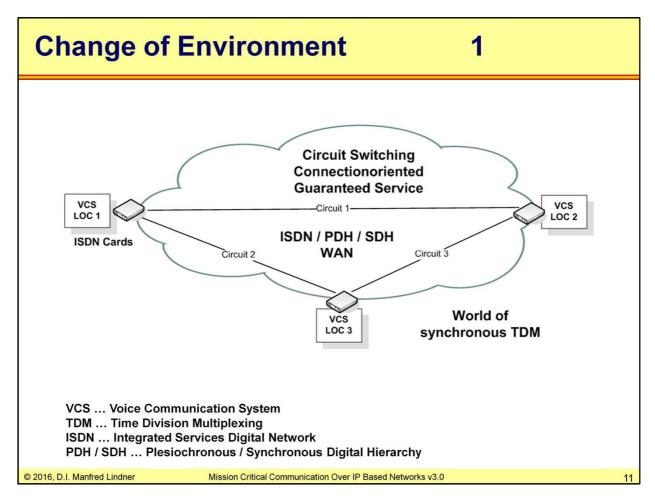
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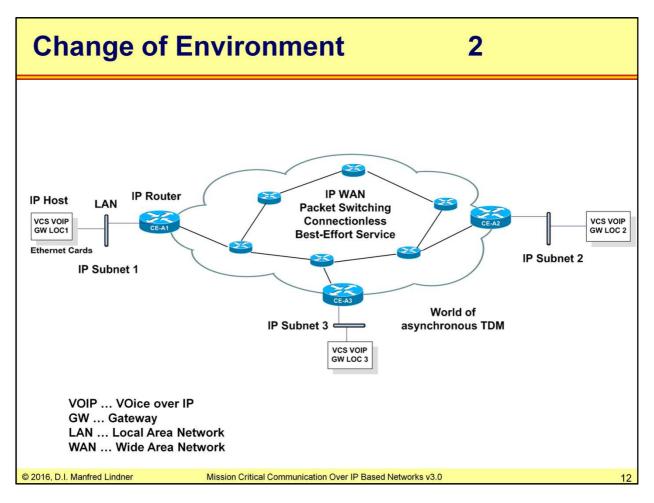
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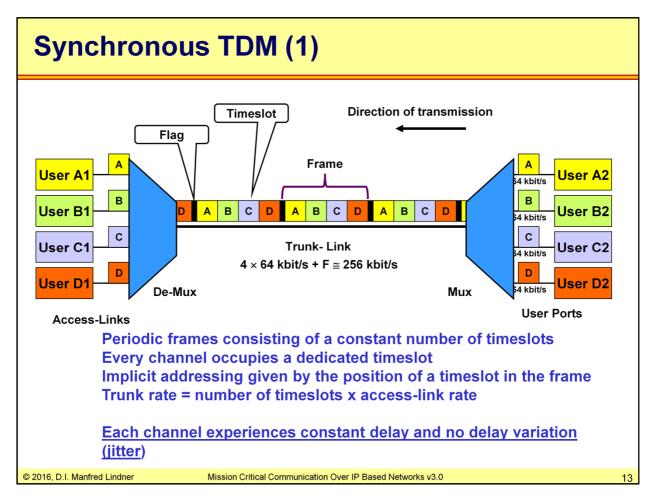


In the past and even nowadays mission critical communication very often bases on real-time voice transmission. Examples are voice communication in ATC (Air-Traffic-Control) area between controller in the tower and pilot of an airplane or in public safety area between dispatcher and rescue forces (fire brigade, police, ambulance). Special designed voice communication systems (VCS) based on real-time telephony switching in conjunction with radio communication were and are still used to satisfy the special needs of that community.

In the communication network part legacy circuit switching technology based on synchronous TDM is used to cover the traditional real-time aspects of voice communication.



Nowadays a change of environment to IP networks has taken place which is a fundamental change for VCS systems. IP network uses packet-switching based on asynchronous TDM which – as best-effort system - was not built to cover real-time aspects of voice communication under all circumstances. The next pages show the basic features of synchronous and asynchronous TDM.



Time division multiplexer allocates each input channel a period of time (timeslot) and controls bandwidth of the trunk line among input channels. Individual time slots are assembled into frames to form a single high-speed digital data stream. The available transmission capacity of the trunk is time shared between various channels. At the destination a demultiplexer reconstructs individual channel data streams.

Synchronous TDM periodically generates a frame consisting of a constant number of timeslots each timeslot of constant length. A starting delimiter (Flag) is used for frame synchronization, which is needed to differentiate one frame from the next frame. Because of the "Flag" the individual timeslots can be identified by position within a frame (timeslot 1, timeslot 2, and so on). In our example we have four timeslots 1 - 4. Every input channel is assigned a dedicated timeslot e.g. data of port P1 will be carried in timeslot 1 for the A1 to A2 communication, data of port P2 will be carried in timeslot 2 for the B1 to B2 communication and son on. In our example we use "Byte-interleaving" that means a single timeslot carries 8 bit of the corresponding channel per frame.

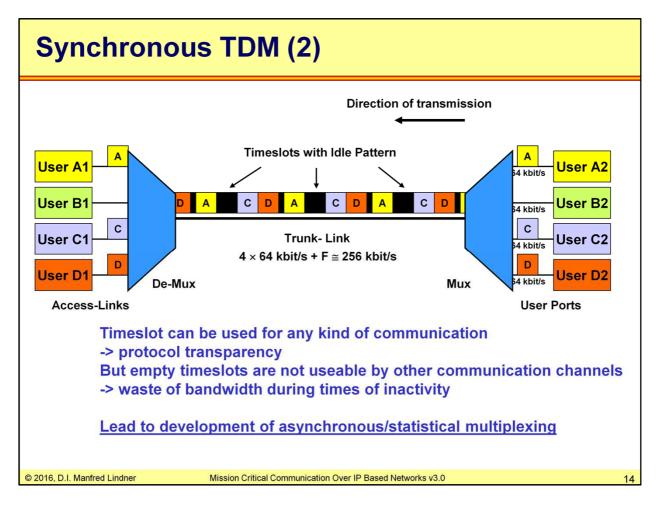
Synchronous TDM framing on the trunk line can be vendor dependent which was used by proprietary TDM products or can be standard based.

Two main architectures for standard based synchronous TDM on trunk lines for carrying PCM-coded digital telephony were established in the past:

PDH - Plesiochronous Digital Hierarchy developed in the 1960's (e.g. E1 (2Mbit/s), E3 (34Mbit/s), E4, T1 (1,544Mbit/s), T3)

SDH - Synchronous Digital Hierarchy developed in the 1980's (e.g. STM-1 (155Mbit/s), STM-4 (622Mbit/s), STM-16)

The bandwidth needed on a deterministic TDM trunk is always determined by the sum of all communication channels on the trunk plus some administrative overhead, because of the fixed correlation between communication channel and timeslot. In our example we find four communication channels with a capacity of 64Kbits/s each, so the transport capacity of the trunk needs to be 256 Kbits/s.



Compared to pure point-to-point physical link synchronous multiplexing adds only minimal delays: Time necessary to packetize and depacketize a byte and transmission/propagation delay on trunk

The end-to-end delay for transporting a byte is constant and the time between two bytes to be transported is constant, hence optimal for isochronous transmission requirements like traditional digital voice

Any line protocol could be used between devices, method is protocol-transparent. To endsystems such a channel looks like a single physical point-to-point line.

The major disadvantage of deterministic TDM systems is the fixed correlation between communication channel and time slot position. This means if one communication channel is not used it still occupies the time slot capacity by sending some kind of idle pattern. Bad trunk utilization could occur if only a few of the reserved timeslots are in use. That leads to development of asynchronous / statistical TDM.

In synchronous (deterministic) TDM systems the order of the data packets is maintained, no packet overtake or time slot position change is possible. The frames need to have always the same size because the timeslots in deterministic TDM systems have a constant length.

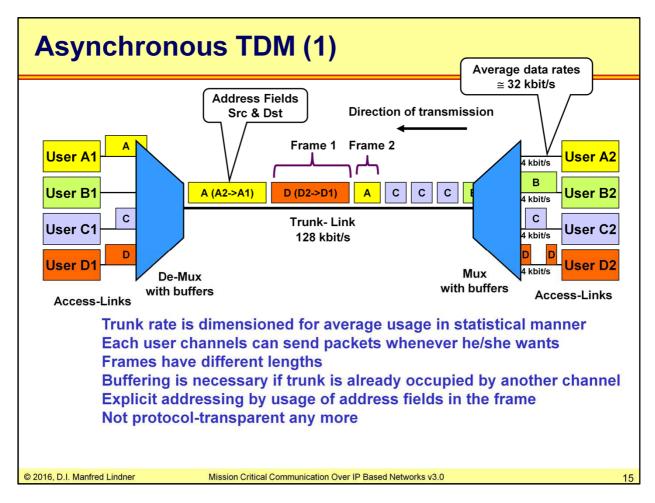
Address information is not required, because the destination is determined by the time slot position.

Deterministic TDM is connection-oriented because a point to point connection is typically setup by usage of SC (switched circuit) techniques like ISDN or permanently established by usage of PC (permanent circuit = leased line) techniques like PDH/SDH.

Buffers are not needed because the data stream is sent out with exactly the same speed as it is received.

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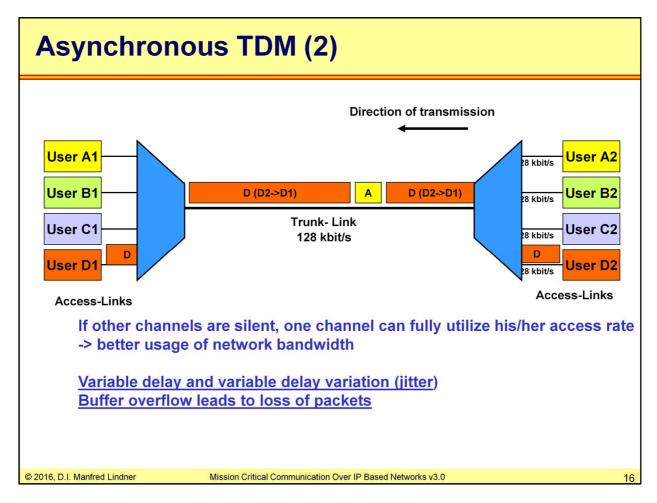


Usually computer devices communicate in a statistical manner because not all devices have data to transmit at the same time. Therefore it is sufficient to calculate necessary bitrate of the multiplexer trunk line according to the average bitrates caused by device communication. The speed of the trunk could be chosen according to the average statistical transport needs of the users. Any user is allowed to send data at any time.

Now a asynchronous multiplexer generates a transmission frame only if data bytes are present at input ports. The source of data must be explicitly identified in transmission frames so we need addressing because there is no fixed correlation between timeslot position and communication channel as it is with deterministic TDM systems.

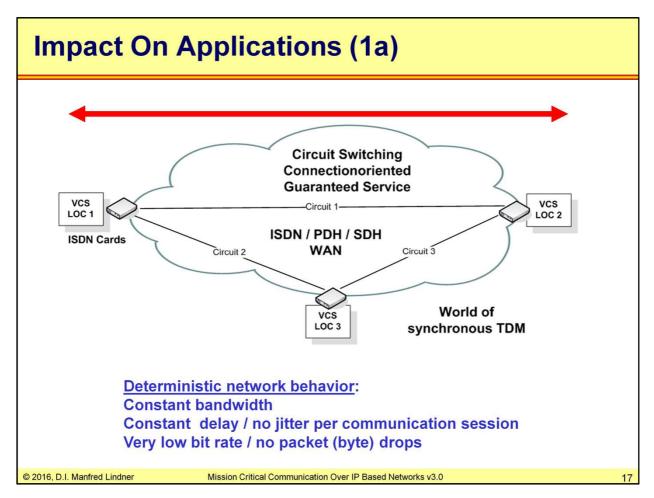
But if devices transmit simultaneously only one channel can occupy trunk line at a given time, data of other channels must be buffered inside the multiplexer until trunk is available again <u>(store and forward principle)</u>. Hopefully statistics is such that the trunk will not be monopolized by just a single channel. Otherwise a buffer overflow will occur in the multiplexer, leading to transmission errors seen by the individual channels.

In case of congestion buffering helps but causes additional delays compared to synchronous TDM. Delays are variable because of statistical behavior hence not optimal for synchronous transmission requirements like traditional digital voice but still sufficient for transmission requirements like bursty data transfer between computers.



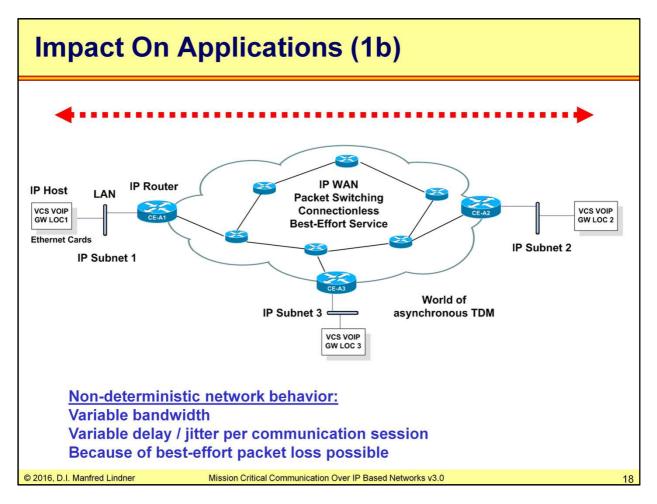
One of the major advantages of statistical TDM systems compared to deterministic TDM systems is the following fact: If the trunk is empty one user may use the complete transport capacity of the trunk. On the other hand it may occur that all users want to use the trunk at the same time. Because of the statistical dimensioning of the trunk capacity it may happen that more data is fed in by the users than the trunk capacity allows. For such cases buffers are needed by the statistical TDM devices to compensate the speed differences. In case of buffer overflow conditions it may even happen that data is lost.

Statistical TDM allows a good utilization of the trunk because there is no waste of bandwidth by the use of idle patterns and the capacity is determined by the average needs of the users. The frame size may vary depending on the need of the users. Buffering is required under trunk overload conditions. The delay is variable because of buffering. Statistical TDM is not protocol transparent because a separate packing as well as addresses are needed. End system and ADTM multiplexer have to speak the same protocol language and hence not anymore protocol transparent.

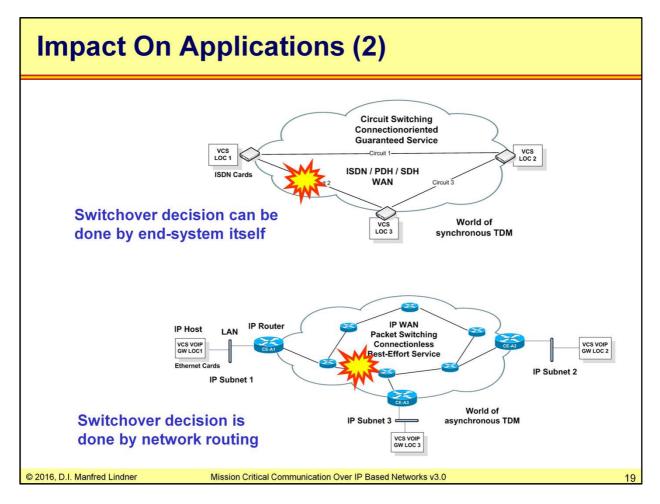


The change from synchronous TDM world to asynchronous TDM world has impacts on the applications implementing mission critical communication.

In the synchronous TDM world there is a deterministic behavior concerning delay, bandwidth. The red arrow in the slide should express that.

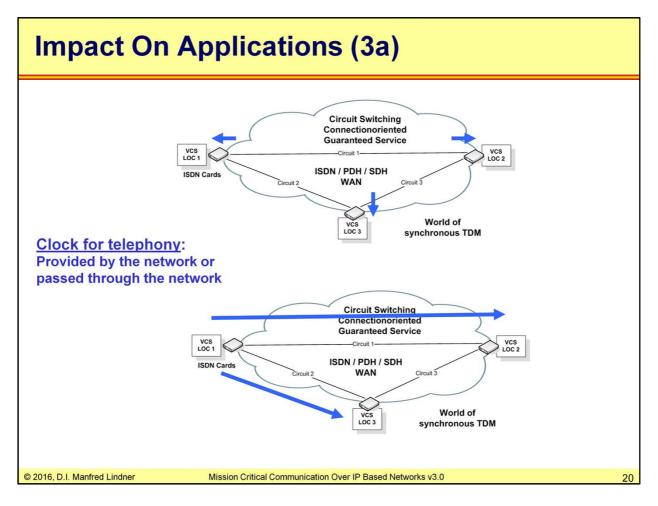


In the asynchronous TDM world there is a statistic behavior concerning delay, bandwidth and loss. The dashed red arrow in the slide should express that.

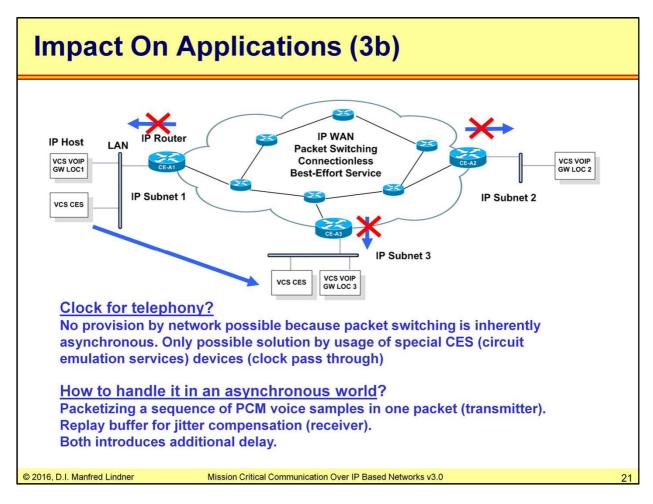


In the synchronous TDM world - because of the inherent connection-oriented behavior - the application knows about the status of a circuit either by presence of physics or by signaling information from the network.

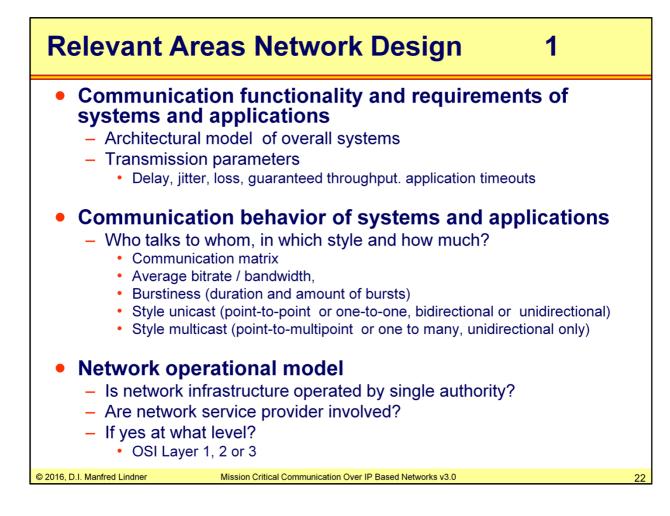
In the asynchronous TDM world the application can not concluded the status of a communication session from the presence of local physics. IP network with the connectionless behavior has no signaling information to the end-system about the status of the network or network parts.



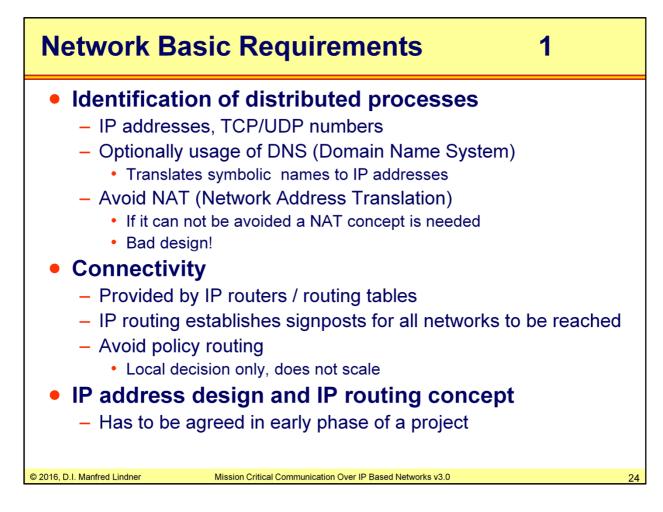
In the synchronous TDM world clock can be given by the network or even transported over the network.



In the asynchronous TDM world clock there is no clock information available from the network.



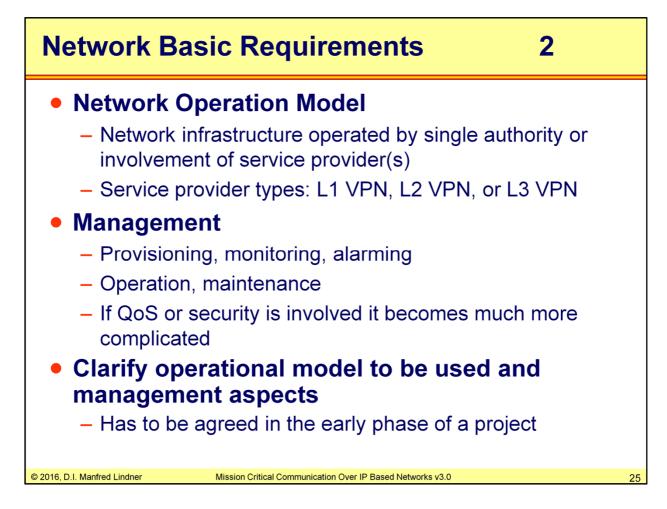
Relevant Areas Network Design 2	
 High Availability (HA) How to continue communication in case of failures or during time of planned service intervals by automatic switchover techniques? Note: 99,99% means 52,56 minutes/year, 4,32 minutes/month, 1,01 minutes/week 	
 QoS (Quality of Service) How to achieve (some kind) of guarantees for mission-critical traffic over a bes effort based technology like IP? 	t-
 Security How to separate traffic of different domains (customers) ? Base VPN (Virtual Private Network) 	
 How to protect traffic and systems against attacks? Advanced VPN techniques (protection based on crypto-graphical methods) Firewall techniques 	
 Management How to manage all that? Organizational aspects Technical aspects 	
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For every IP network there are some basic requirements to be fulfilled in order to enable communication among systems.

First of all systems have to be identified in order to enable IP based communication. The identification is a combination of an IP address or symbolic DNS hostname and UDP|TCP port number. Additionally the IP address represents the location of the system in the network topology in a structured way (Net-ID, Host-ID). If systems are addressed by different authorities or administrative domains coordination between these authorities / domains is necessary because IP address have to be unique within an IP domain. If coordination is not done at the very first beginning the usual overcome is usage of NAT (Network Address Translation). A good address design will avoid NAT because a lot of troubles may arise by using NAT, which often are not foreseeable if NAT is introduced during the project. Typical NAT is implemented on firewalls and IP routers. Stateful NAT has quite some severe implications on redundancy which might be necessary because of request for high availability. One example for such implications is a tight and very close coupling of the components of a firewall cluster which forbids placing the components in different IP subnets (L2 only), hence physically distributing them becomes a problem

Net-IDs (in the following named IP routes) of involved systems have to be known by the IP routing system - especially in the routing table of an IP router - in order to forward IP datagrams to the destination network. The normal behavior of an IP router is "destination based routing" hence source address of an IP datagram is not involved in the forwarding decision. Involvement of IP source address in the forwarding decision is possible (IP policy routing) but leads to a local decision of such a policy-enabled IP router only. Therefore what will be happen by routers downstream cannot be enforced by a router applying IP policy routing ("hop-by-hop routing principle" of IP). IP policy routing maybe used in special situation to overcome a problem but should not be a rule of design because any change of network topology needs careful reconfiguration which may not scale in most topologies. Identification and connectivity both need IP address planning (IP address concept) and routing protocol coordination (IP routing concept).

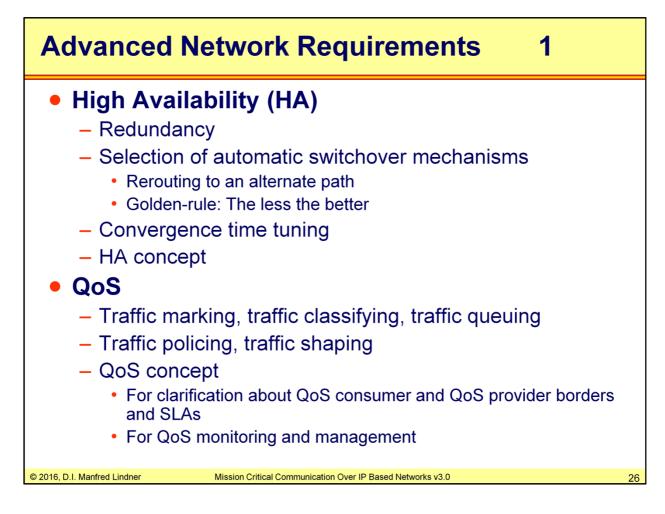


Any IP network can be built based on different operational models. The complete network infrastructure might be owned and operated by one unique authority (customer) or parts of the network infrastructure might be operated by another authority (e.g. out-sourced to service provider).

In case of usage of a service provider the network layers covered by this service provider may vary. Usually the service provided is a kind of VPN (Virtual Private Network) which allows the provider to share a common infrastructure among several customers guaranteeing at least separation of the customers among each other. Optionally dedicated performance to the customers may be guaranteed by usage of either any kind of circuit-technology (PDH, SDH) or of IP QoS mechanism.

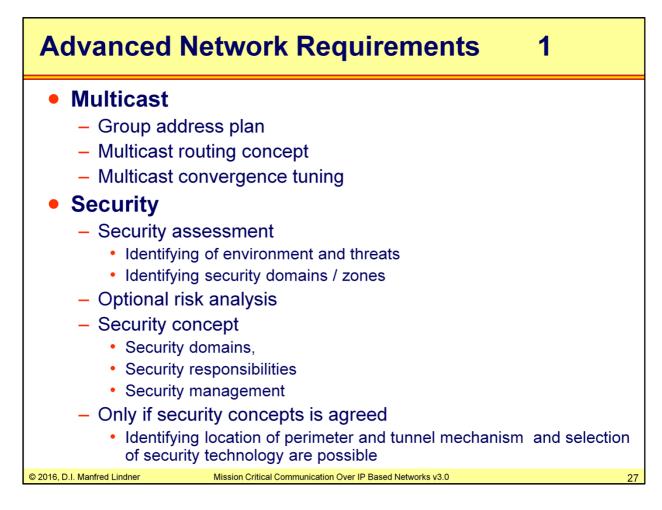
Service providers could be of type L1-VPN provider, L2-VPN provider or L3-VPN provider.

Network management includes activities, methods, procedures and tools that pertain to operation, administration, maintenance and provisioning of IP networked systems. Topics covered are FCAPS (Fault, Configuration, Accounting, Performance and Security). Depth of each individual FCAPS topic depends on the actual business requirements. It can start from the easy going into complexity. It is mentioned here in the basic requirements because often ignored or overseen judged as being from less importance. In reality it turns out to have a huge impact on the overall performance of your solution involving not only technology but also human operators.

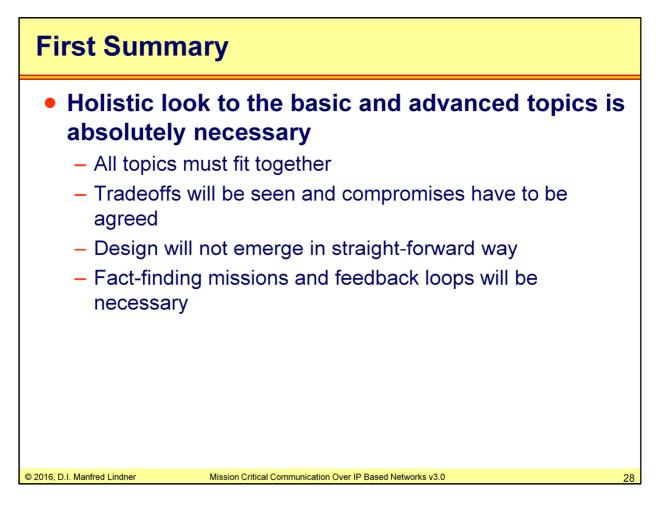


In case of mission critical communication advanced requirements have to be fulfilled by an IP network. These are high availability (HA), quality of service (QoS) , multicasting and security aspects.

HA and QoS issues will be discussed in the following sections of this lecture in sufficient detail.



Multicast and security issues will be discussed in the following sections of this lecture in sufficient detail.



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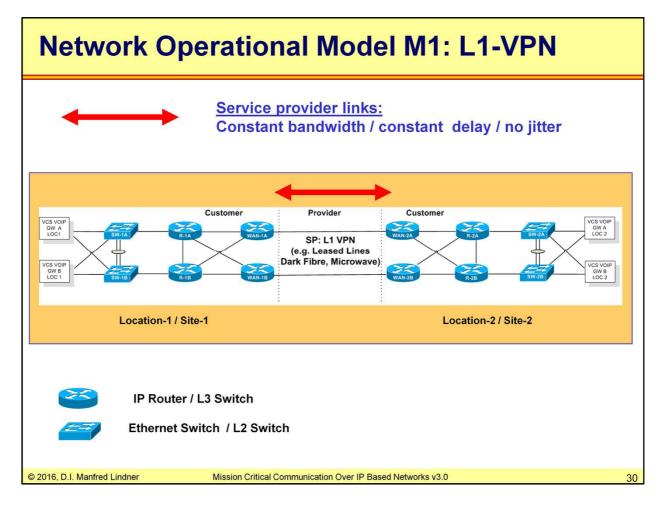
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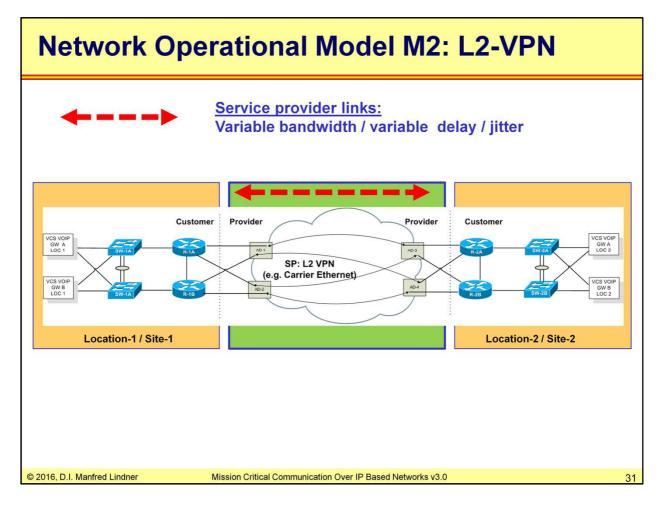


Model M1 (L1-VPN) shows that all IP routers are under control of the customer. L1-VPN SP provides link with dedicated bandwidth and constant delay, which is not shared by other customers. Customer has full control regarding IP addressing, IP routing and QoS implementation.

Examples for L1-VPN are leased line (based on circuit switching PDH/SDH infrastructure), dark fiber or microwave radio. In case of microwave the bandwidth may vary based on environment influences such as weather but the network operator can calculate at least with a minimum (fallback) bandwidth available all the time as long the microwave modems are in operation and synchronized.

Even if it looks like that the end-systems of a location need six elements (e.g. Ethernet switches SW-1A, SW-1B and IP routers R-1A, R-1B, WAN-1A, WAN-1B) in order to connect to the IP WAN, depending on the actual situation concerning the number of end-systems and the kind of provider equipment the elements may be reduced to such two elements incorporating all the necessary functionality (Ethernet switch, IP router and WAN access) in just one single component. The reason for the six (logical) elements will be explained in chapter about HA (High Availability).

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Model M2 (L2-VPN) shows that all IP routers are under control of the customer but the connectivity between customer routers is based on just L2 link technology. In the past examples for L2-VPN were legacy X.25 virtual circuits or FR (Frame Relay) virtual circuits both based on a connection-oriented packet switching infrastructure.

Nowadays VLANs (= multiplexing of LANs across a shared L2 Ethernet switching infrastructure), Carrier-Ethernet or VPLS (Virtual Private LAN Service) are typical examples. In such a case the customer sees just (virtual) Ethernet links. Nevertheless these Ethernet links are provided by the SP on top of another - for the customer not visible - connectionless packet switching technology. For example both Carrier-Ethernet and VPLS are based on pseudo-wires implemented on top of IP-MPLS packet switching operated by the L2-VPN provider.

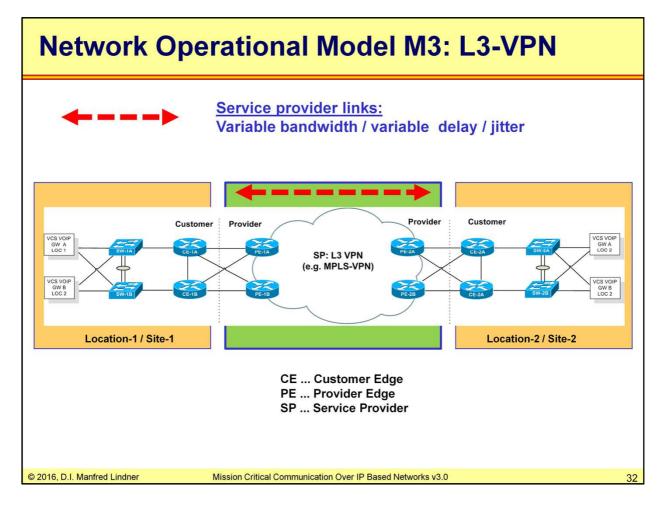
A Carrier-Ethernet or VPLS service will support different customers based on the common infrastructure of the service provider. Therefore even with dedicated physical bandwidth for every Ethernet link a variable delay will be experienced on such a virtual Ethernet link end-to-end depending on the traffic statistics of all the customers sharing the sane SP. Customer has full control regarding IP addressing, IP routing but QoS is still inherited from the characteristics/statistics of the service provider.

Other examples for such L2-VPNs are microwave/SAT modems or SDH-AD (Add/Drop) multiplexers offering their service on a corresponding Ethernet link to the customer routers. Usually there is speed mismatch between the Ethernet link and the microwave-link or SDH circuit (e.g. 100 Mbps Ethernet should use a 34 Mbps circuit). In such a case the provider equipment acts as (transparent aka hidden to the customer) Ethernet switch performing packet switching between the different physical technologies. In case of packet bursts it can happen that buffering is not possible anymore and some packets get lost. So it looks like a Ethernet link, but some weird things can get on in such a constellation.

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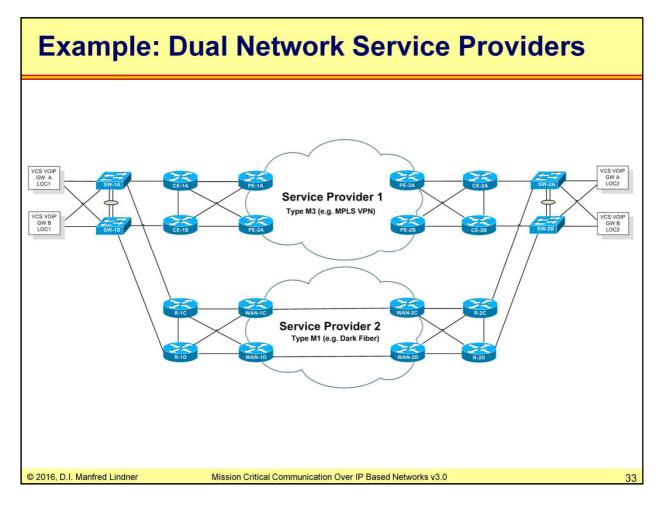
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Model M3 L3-VPN shows that only CE (Customer Edge) IP routers are under control of the customer. The PE (Provider Edge) IP router and the WAN links are under the control of the service provider. L3 VPN SP provides separated IP connectivity for each customer but all customers shares the same infrastructure. That results in variable bandwidth and variable delay depending on the traffic statistics of all the customers sharing the same SP. Customer and provider only control IP addressing, IP routing and QoS in their own domain. Interaction, coordination and supervision are necessary at the border in between. IP routing convergence and QoS characteristics are inherited from the service provider.

Examples for L3-VPNs are MPLS-VPNs (=multiplexing of IP nets across a shared L3 IP/MPLS infrastructure) or IPsec Site-Site-VPNs (=tunneling of over a given network infrastructure with inherent crypto-graphical support for encryption and integrity). L3-VPNs are also called overlay VPNs to express that routing within a service provider network is separated from the routing of the customer.



A single service provider can give you a certain kind of availability (amount of "Nines"). For achieving an overall higher availability sending duplicated data on parallel paths is an option. Selection of "better" stream can be done by the receiving application.

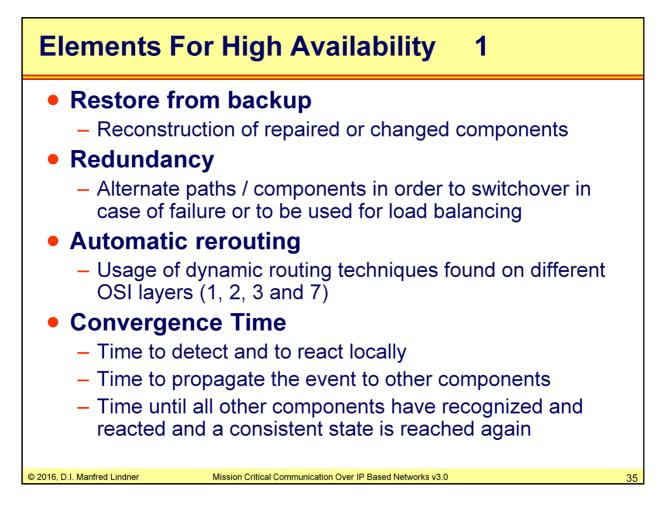
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HA mechanisms ensure communication in case of failures or during time of planed service intervals by usage of automatic switchover mechanism in case of single point of failures. Typical elements are redundancy (alternate paths, alternate components), automatic rerouting and restore from backup.

Dynamic IP routing protocols like will consistently create routing table entries by exchanging information about IP routes among routers. These dynamic routing protocols can detect and overcome a network failure in a certain time - convergence time. Network failures detectable are local link down (fastest possible convergence) or neighbor down (timeout based convergence). Dynamic IP routing protocols will not include traffic statistics like usage of link bandwidth, delay of buffering or bit-errors on links to initiate a routing convergence.

Convergence time involves the following elements which sum up: First time to detect a failure and to react locally, second time to propagate the failure to other components and third time until all other components have recognized the failure and react on it to achieve a consistent state again. During convergence time inconsistent states are possible. Such inconsistency should not lead to an overall system crash or deadlock hence complexity shall be reduced to a minimum as far as possible. Unfortunately routing convergence (selection and switchover to an alternate path) can and will happen on different levels.

Examples o	f rerouting techniques
– L2 LACP, L	inux-Bonding, Intel-Teaming
 L2 Rapid S 	panning Tree
 L2 BFD Bid 	irectional Forwarding Detection
 L3 dynamic 	: IP routing protocols (OSPF, IS-IS, BGP, MPLS-LDP),
 L3 First-hop 	o routing (HSRP/VRRP)
 L3 Equal Co 	ost Multiple Path (ECMP)
_ .	
	routing techniques
-	essary to achieve (sub)second convergence time
	ferent techniques used the better
 Needs to be 	e harmonized
 Failure reparent 	air may also lead to interruption until convergence
• Traditional I	IP mechanism
	ack-Outs" (e.g. link down, router down)
	wn-Outs" (e.g. packet loss increases)
- Dati at Dio	wil-Outs (e.g. packet loss increases)
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For example some standardized mechanism are:

On Layer 1 (e.g. SDH): Link Fast Reroute

On Layer 2 (e.g. Ethernet): BFD (Bidirectional Forwarding Detection), LACP (Link Aggregation Control Protocol), Teaming, Bonding

On Layer 2 (e.g. Ethernet Switching): STP (Spanning Tree Protocol), Rapid-Spanning Tree

On Layer 3 (e.g. IP routing): HSRP (Hot Standby Routing Protocol) and OSPF Fast (subsecond) Hello

On Layer 7 (e.g. Application): Switchover triggered by supervision done by the application it selves.

Timeouts of these mechanisms need to be harmonized and their standard behavior has to be tuned.

Golden rules: The less convergence mechanisms are used the better. Fast reaction is the enemy of stability. Burst of failures need a dampening mechanism in order to avoid a network meltdown. Summarization of IP routes following the physical topology of the network relieves administration/operation, keeps changes of routing table entries in case of network topology events local, minimize amount of routing table entries in the core network and may accelerate routing convergence in case of a network failure Last but not least effects on failure repair (rerouting back to failure free operation) should be analyzed and tuned to an acceptable level (e.g. done during service time interval) because this may lead to connectivity outage for some time, too.

Keep in mind: IP routing protocols are excellent on "black-outs" (something get lost) but bad on "brown-outs" (something becomes weaker and weaker).

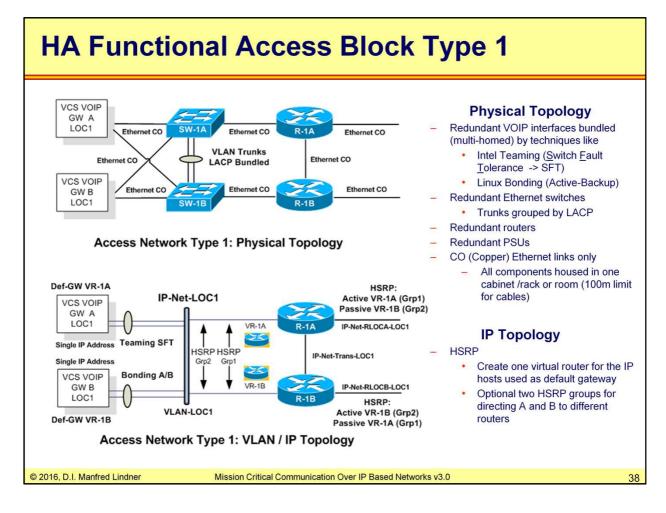
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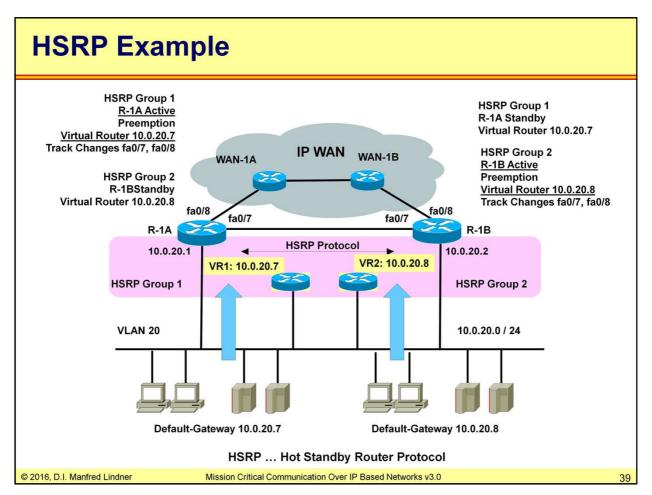


First let us have a look into more detail how end-systems (VCS - Voice communication systems) can be connected to the Ethernet / IP infrastructure.

HA Access type 1 shows a basic access method based on two Ethernet switches and two IP routers. On the left side there is the physical topology representing the cable plan. On the right side there is the (logical) VLAN/IP topology representing the VLAN-IDs, IP Subnets and HSRP aspects.

Physical part of network access type 1: Each VCS is connected via copper Ethernet to two different Ethernet switches. Switches are trunked together by two copper Ethernet links. Each Ethernet switch is connected with a single copper Ethernet link to an IP router. The routers are connected together and to the IP WAN using one copper Ethernet link per connection. The Ethernet link between the two routers will keep a failure local in some failure situations, which will be explained a little bit later in this chapter. So a failure of one physical link or component will not create a problem because of overall redundancy.

Logical part of network access type 1: The Ethernet switches are using LACP (Link Aggregation Control Protocol) for bundling the trunks in between to create just one logical trunk seen from the Spanning-Tree protocol, hence only one STP path is in between and no STP convergence has to take place in case of a failure. Both VCS shares the same VLAN and IP subnet. The two physical interfaces of a VCS are bundled to one logical interface representing a single IP address and single Ethernet (MAC) address. Following bundling methods are possible: Either Intel teaming in SFT (Switch Fault Tolerance) mode in case of Microsoft environment or LINUX/UNIX bonding in A/B (Active/Backup) mode. In both cases just one link (the active) is used and a switch over to the other link (the standby) is performed in case of a failure. Direct failures (link cable broken) are easy to detect. Indirect failures (like Ethernet switch failure but link to Ethernet switch still active) need additional methods to be implemented. These methods are periodical ARP checks of the default-gateway performed by the VCS and periodical HSRP hellos performed by the corresponding virtual IP address, which is represented by the corresponding virtual IP address of the HSRP group. Two different HSRP groups are used to direct traffic from the VCSs to different physical routers during normal operation and to disturb only one VCS by the HSRP convergence time in case of a failure. The other VCS will not experience any disturbance. During normal operation one router (e.g. R1-A) will be active for a virtual IP address VR-1A and the other router (R1-B) will be standby. In case of a failure the other will take over. After failure repair R1-A again will become the active router. By applying the same schema for VR-1B but with opposite logic the overall decoupling of VCS-A and VCS-B concerning single-point of failures can be achieved.

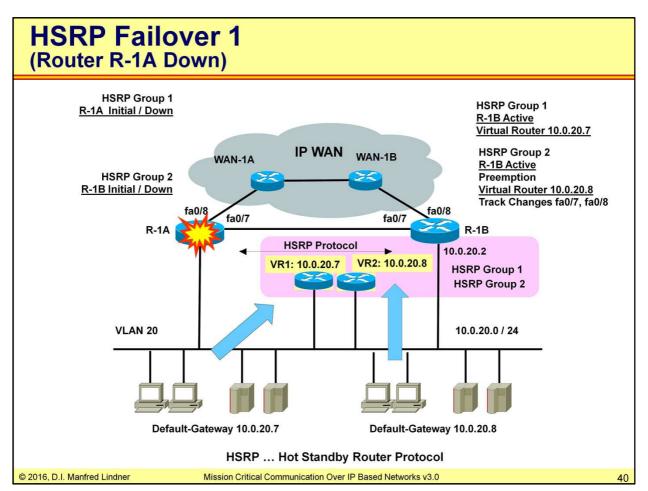


Basics of HSRP:

A group of routers forms a HSRP group. The group is represented by a virtual router with a virtual IP address and virtual MAC address for that group. IP hosts are configured with the virtual IP address as default gateway. One router is elected by HSRP as the active router, one router is elected as the standby router of that group.

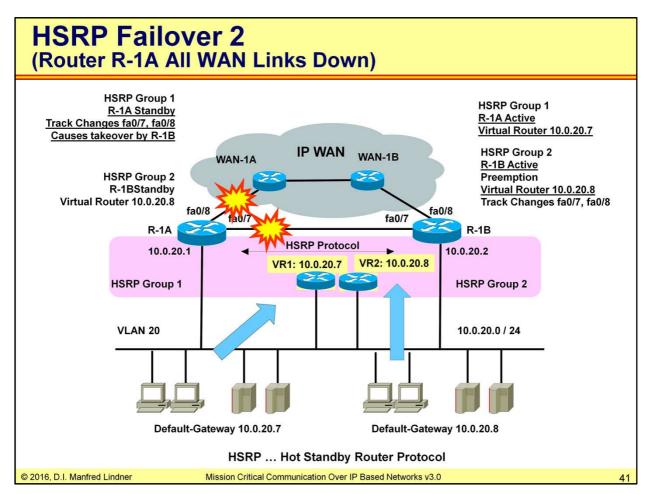
HSRP messages are UDP messages to port 1985, addressed to IP multicast 224.0.0.2 using Ethernet multicast frames (HSRP version 1; IP multicast 224.0.0.102 is used for HSRP version 2). Active router responds to ARP request directed to the virtual IP address with the virtual MAC address. Standby router supervises if the active router is alive by listening to HSRP messages sent by the active.

Active and standby is defined by HSRP priority. Priority value can be configured. The higher the better. Preemption allows to give up the role of the active router when a router with higher priority is reported by HSRP messages. Preemption happens either when the failed router comes back, a better router has been activated or tracking has changed priority.



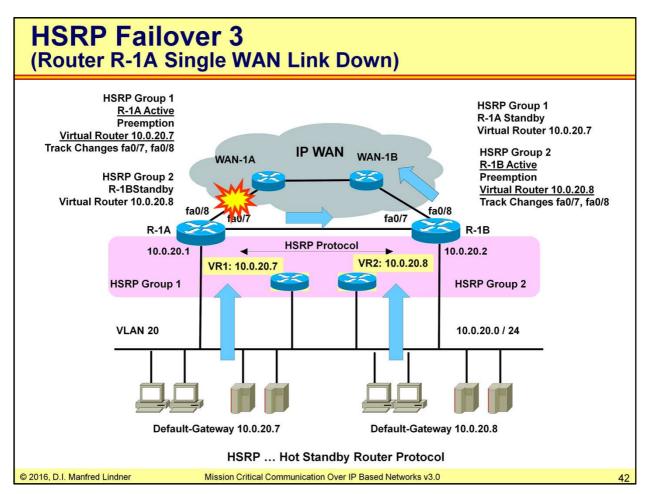
Failover scenario 1:

Active router is not reachable via LAN. Standby router will take over active role. Timing depends on HSRP hello message interval and hold-time (default hello-time = 3 seconds, default hold-time = 10 seconds, HSRP version 1; for HSRP version 2 hello-time is configurable between 15 - 999 milliseconds and hold-time is configurable up to 3000 milliseconds).



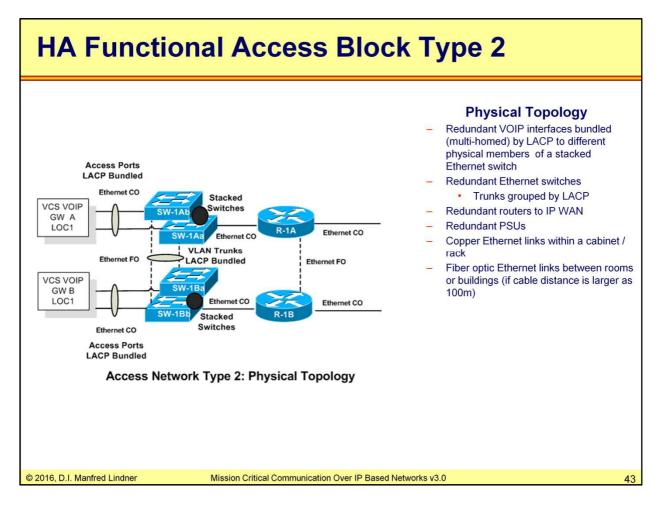
Failover scenario 2:

Active router losses connectivity to both WAN interfaces. Tracking will lower the priority of the active router. The standby router will take over even the current active router is still reachable via LAN.



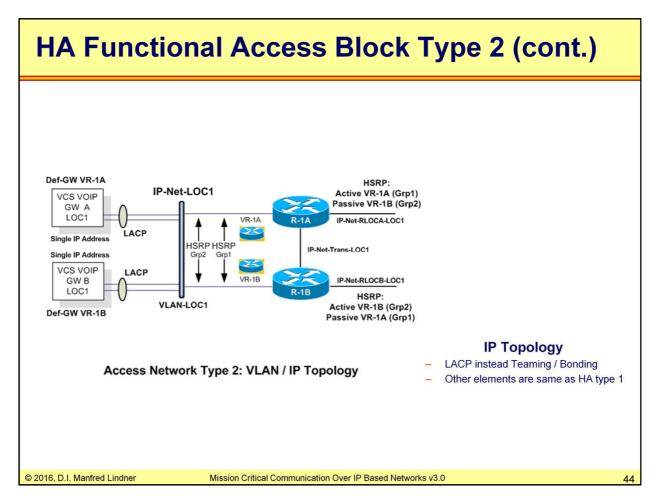
Failover scenario 3:

Active router losses connectivity to single WAN interface. Tracking will lower the priority of the active router. But resulting priority still higher than priority of standby router. Therefore no switchover will take place. Routing will forward packets using the cross link to R-1B (of course an appropriate routing have to be established meaning running a dynamic routing protocol across the link R-1A to R1-B with a lower routing metric compared to vlan 20.)

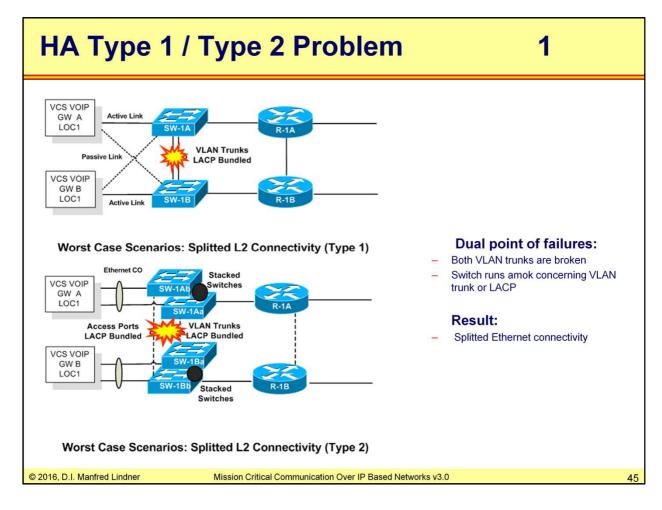


HA Access type 2 shows a modified access method following the same principle as access type-1 which is eligible for in two cases: Either more Ethernet ports for end-systems are necessary than a single Ethernet switch can provide. Or all components of part A should be separated from all components of pars B by usage of fiber optic Ethernet links because equipment should be housed in different cabinets or buildings.

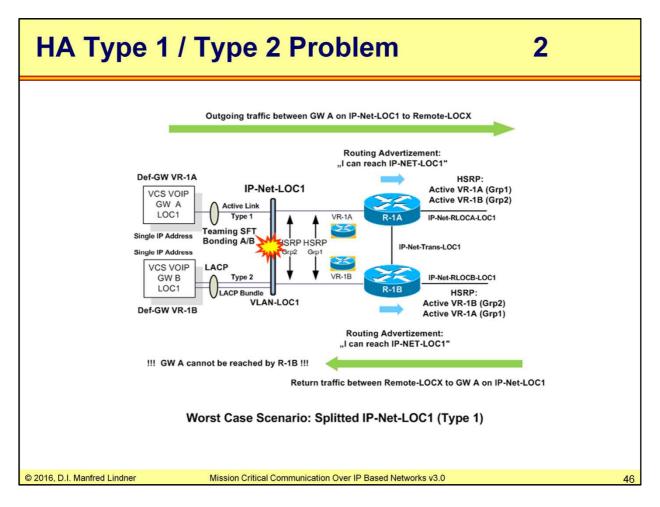
Physical part of network access type 2: Ethernet switches are stacked in order to provide just one single logical Ethernet switch regarding Spanning-Tree protocol and management. Typical stacks allow forming a single logical switch out of up to 8 physical switches. Each VCS is connected via copper Ethernet to two different Ethernet switches of the same stack by using LACP instead of Teaming/SFT or Linux Bonding Active/Backup. Switches are trunked together using two fiber optic Ethernet links with LACP as in block type 1. Also the Ethernet link between the two routers is based on fiber optic Ethernet.



Logical part of network access type 2: It is pretty much the same as for type 1. Both VCS shares the same VLAN and IP subnet and HSRP works in the same style. The only difference is the usage of LACP to bundle the two physical interfaces of a VCS together to just one logical link which now allows load balancing and avoids any teaming-SFT or bonding-A/B convergence to take place in case of a failure.



Now let us look what can happen to access type 1 or 2 in a worst case scenario where parts are getting separated by applying dual point of failures. Splitted L2 connectivity shows such a worst case scenario. The interconnection of the Ethernet switches - although robust against single point of failures by usage of two separated Ethernet links – can lead to splitting the L2 into separated parts. Either if both links are broken or the LACP logic in the switches has a problem the result is a catastrophe for the IP view of the network. Next slide explains why.

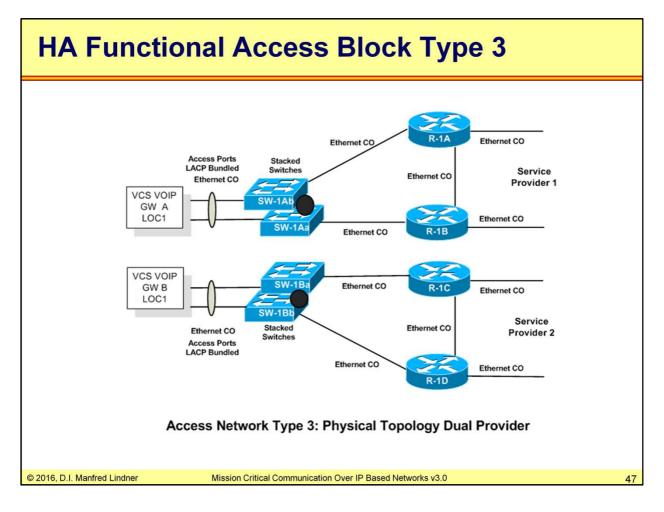


An IP subnet never ever is allowed to be splitted in two separated parts because separated parts must have different IP Net-ID. Both routers still announce reachability of IP-Net-LOC1 in such a failure scenario. From the outside world both routers are valid entry points to reach IP-Net-LOC1. The summary routing metric seen from foreign routers in order to reach IP-NET-LOC1 will decide which entry should be used.

For example traffic still leaving VCS-A can reach a foreign location but return traffic for VCS-A may be received on the wrong entry point. So bidirectional communication will die. More badly it could happen that for some communication it still works. Or what works and what not depends on other operational parameters like routing metric changes. So fixing the problem based on symptoms is not so easy.

Another effect is that on both routers now both HSRP groups are active which is not a problem in the moment but will cause a longer convergence time in case of failure repair. Why? Because consistency in any active/active scenario of cluster needs some additional care in case the two systems see each other again after failure repair.

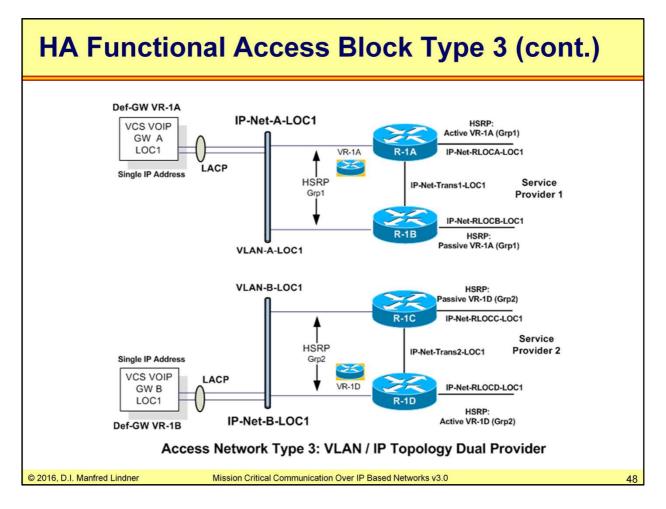
Unfortunately there are no automatic mechanisms available to overcome such situation. One possible approach is to perform OSPF locally between the two routers on IP-NET-LOC1 and to detect if HSRP is active for a group on both routers (SYSLOG). By correlation with a missing OSPF peer but still seeing the IP-NET-LOC1 in the OSPF topology database twice (router-LSA of R-1A and router-LSA of R-1B both shows the same IP network) a configuration script may be written to deactivate one of the router but that needs careful design and testing in order to automate.



Now let us show some possibilities to overcome the splitted L2 connectivity problem.

One possible approach is usage of separate L2 domains for VCS-A and VCS-B resulting in different IP Subnet -> IP-Net-A-LOC1 and IP-Net-B-LOC1. VCS-A and VCS-B have no L2 connectivity (VLAN) anymore. Together by usage of separated IP WAN service providers for each of the VCSs the problem is solved.

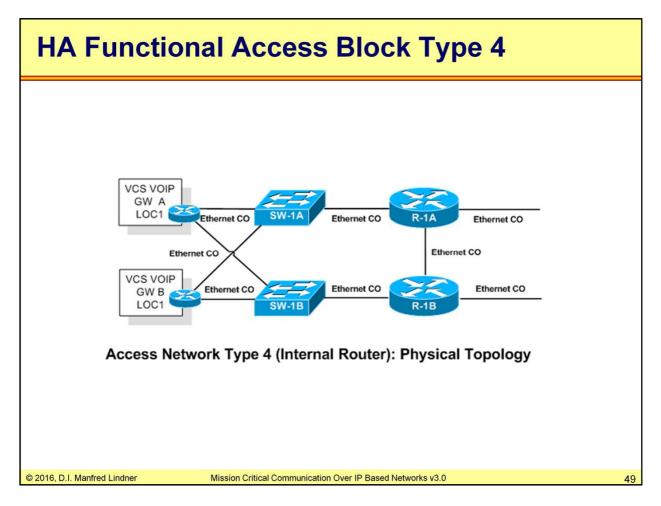
HA access network type 3 shows such an approach. Type 3 access takes the principle of type 2 access (stacked switches, LACP from VCS to stacked switches) concerning physical topology.



Type 3 access uses HSRP with only one HSRP group per VCS, feed the IP-WAN with dual IP routers per VCS and use a dedicated service provider per VCS. Service providers 1 and 2 have no visibility of each other and perform independently.

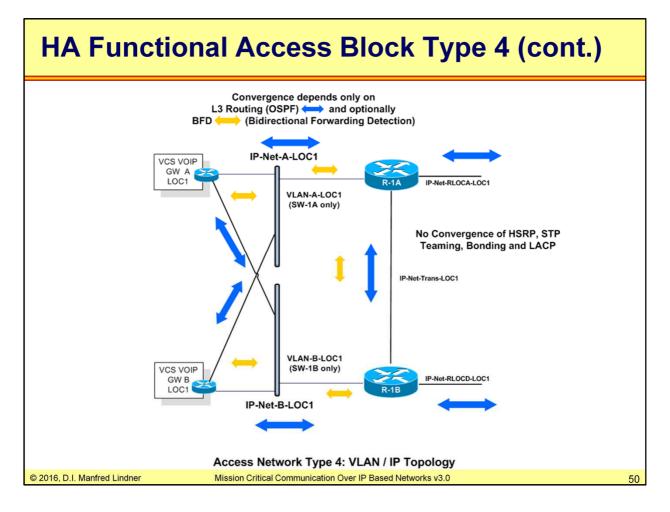
Alternative approach is usage of just one Ethernet link from the VCS to just one Ethernet switch connected to just one router leading to dedicated service provider in order to minimize number of components.

This follows either the philosophy of dual data transport over the IP-WAN and selected the better signal at the receiving end or just reduces the distance of any single point of failure to just one VCS system.



The next possible approach is introduction of L3 routing functionality in the end-systems. The big advantage of such an approach is that knowledge about the network topology is brought to the end-system and number of convergence mechanism is reduced to a minimum. If you are afraid that end-systems are burdened in case of a huge network topology, the view of the network topology for the end-systems might be suppressed to the local environment only. For example running two routing processes on R-1A (one for WAN, one for LAN) and redistributing local IP network via static routes into WAN and installing default-routes into LAN are a possible way of decoupling.

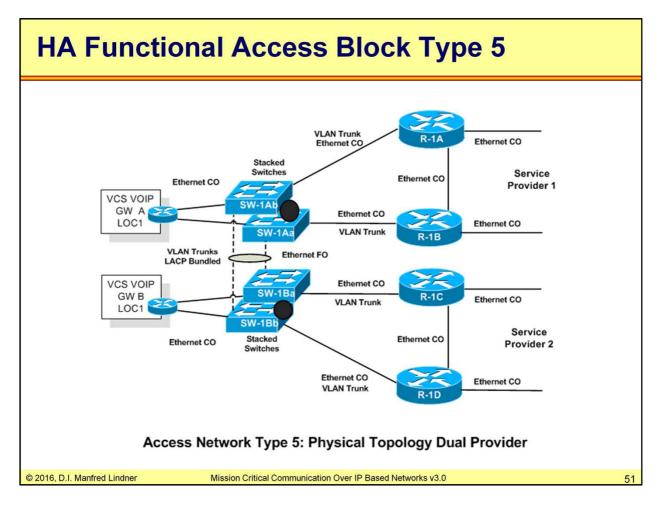
HA Access type 4 shows end-systems with internal IP router connected to two Ethernet switches. Every Ethernet switch just represents a single VLAN and is used to connect the three corresponding routers together of an IP subnet together (e.g. VLAN-A-LOC1 connecting VCS A, VCS-B and R-1A in IP-NET-A-LOC1 -> see next slide).



No more Spanning-Tree, no more teaming/bonding/LACP, and no more HSRP are necessary. Convergence time in case of failure depends on detection of direct failures (link down) or indirect failures (OSPF or BFD) timeouts.

An end-system is identified either by the two IP interface addresses or by an internal loopback address which is independent from the IP interface addresses. Hence the internal router advertize reachability of the loopback network address to the IP routers by usage of a routing protocol.

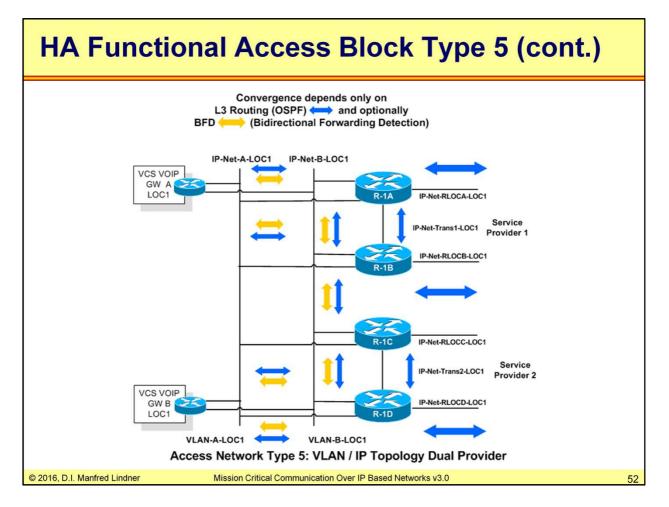
If the number of VCS interfaces (systems) increases on a location, routing scalability might become a problem. In order to keep failures local and separate routing at the location from the routing towards IP-WAN, OSPF areas can be used as alternate method to that mentioned on last page. So the IP WAN would become OSPF area 0 (OSPF backbone) and location 1 represents OSPF area 1. R-1A and R-1B become OSPF area border router between area 0 and area 1. VCS routers are just internal OSPF routers in area 1, hence any changes in the internal topology will not results in performance-greedy OSPF recalculations in OSPF area 0.



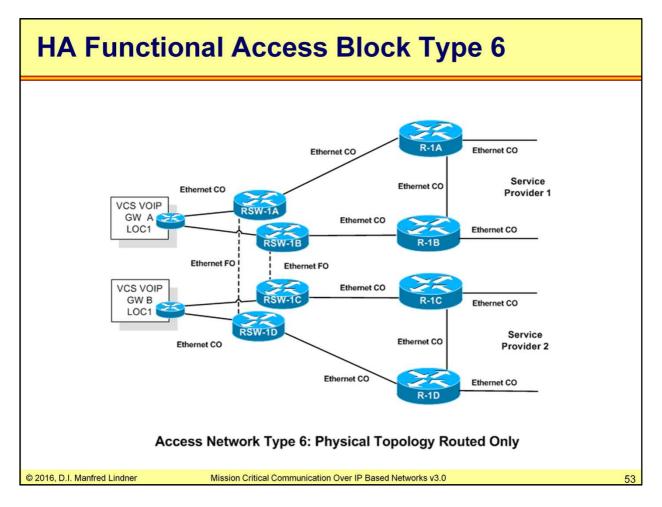
In case of dual service providers access type 5 may be used instead of access-type 4. HA access network type 5 shows usage of stacked switches to increase either Ethernet port number or minimize numbers of FO Ethernet links.

Further the service providers are interconnected at the customer location.

Now an end-system can select among four possible exit points to the IP- WAN depending either on IP routing only (best or available paths) or on a local policy decision.



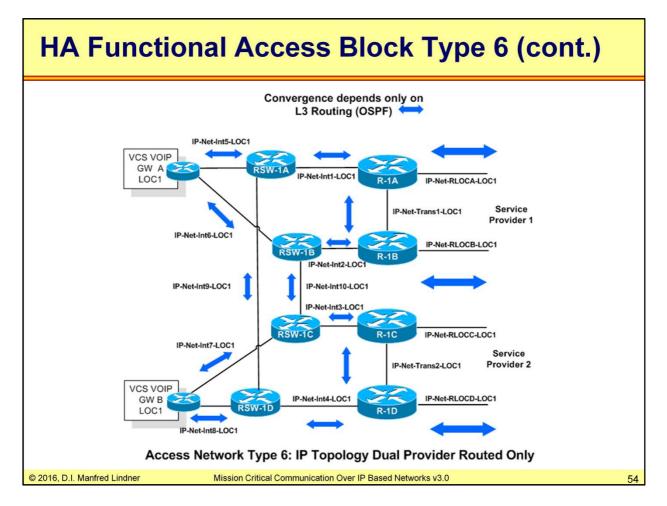
Of course this approach suffers from a splitted L2 connectivity in a similar way as already described in the worst case scenario.



The ultimate approach is an IP router only approach. HA access network type 6 shows usage of L3 switches instead of L2 Ethernet switches, which is a fundamental trend seen in future datacenter infrastructure network solutions (routing to the access layer).

No VLANs and no Ethernet switching anymore. The physical topology and IP topology are completely aligned. Only point-to-point Ethernet links are used and routing convergence depends on OSPF only.

Again in order to keep failures local and separate routing at the location from the routing towards IP-WAN, OSPF areas can be used as already described in elaborations about access type 4.



Now the IP topology and physical topology are the same. Only number of necessary IP subnets per location has increased to address the point-to-point links.

We have introduced several advanced HA mechanisms (type 3, 4, 5 and 6) to overcome situations where more than a single point of failure happens and network is splitted in separate domains. Often overseen or ignored this can lead to real weird situations with often unpredictable consequences.

Therefore if methods types 1 or 2 are applied they should be analyzed thoroughly and systems designed such as that they get into a stable state even if consistency cannot be guaranteed during all times of separation.

Last but not least effects on failure repair (rerouting back to failure free operation) should be analyzed and tuned to an acceptable level (e.g. postponed to service time interval) because this may lead to connectivity outage for some time, too.

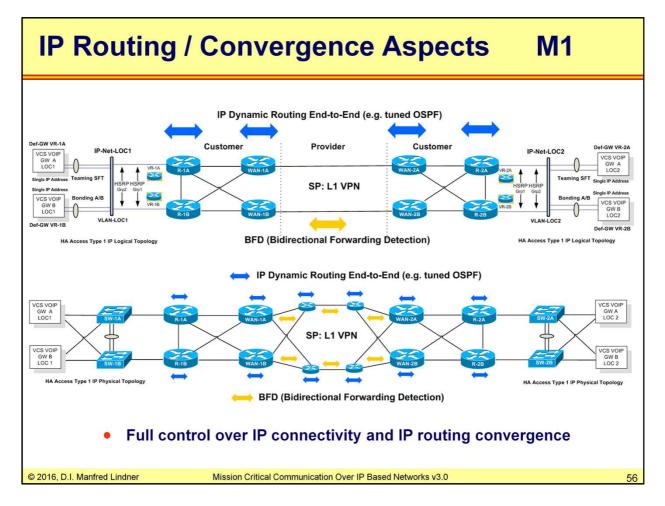
Agenda

- Introduction
- Network Operational Model
- High Availability
 - Elements of HA
 - Functional Access Block Types for HA
 - Routing Aspects
- QoS
- VPN Technology
- Multicasting
- Summary

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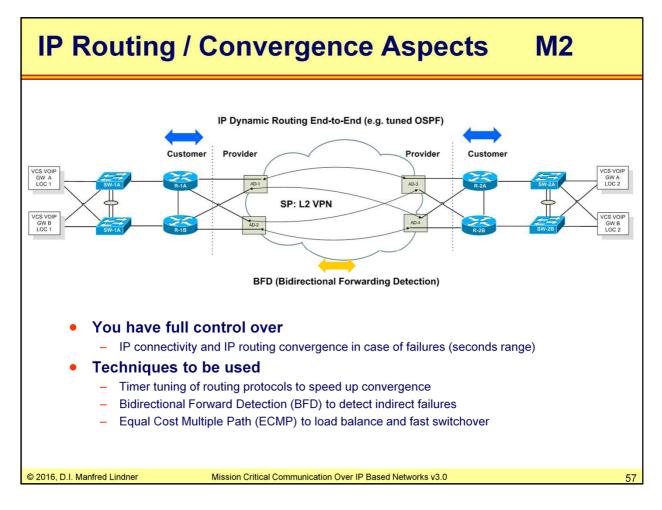
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Now after introduction of possible HA mechanism useable in the access part we can deal with the IP WAN concerning routing and routing convergence. Of course the network operational model has an important impact on what can be achieved and what problems may arise and need to been solved. For the following discussions we use just HA access type 1 for reasons of simplicity but the conclusions are valid for all other access types too.

Routing aspects for operational model M1:

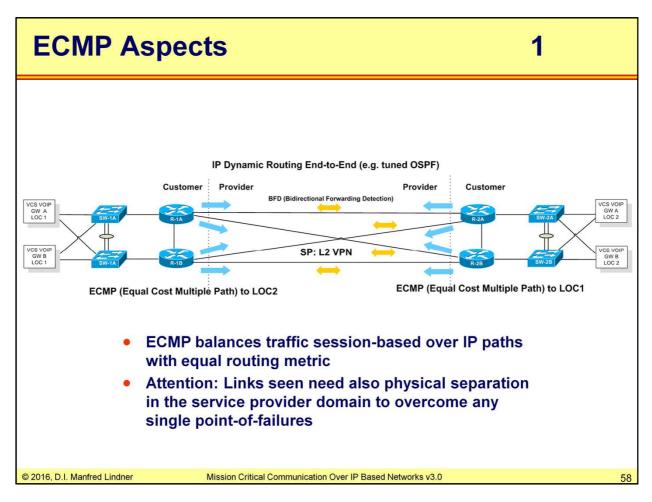
In this case all IP routers are under control of the customer. L1 VPN provider just provides L1 links which are used to interconnect the IP routers. Hence dynamic OSPF routing (tuned OSPF to reach convergence with in a second) and BFD (to detect any indirect failures caused by the L1 VPN provider) can be applied straight forward. The first picture just shows a redundant topology between two locations. The second picture expands this principle to an overall redundant topology supporting any amount of locations by usage of partial meshed topologies or ring structures. The separation of the WAN access from location access LAN by usage of two routers (e.g. R-1A and WAN-1A) may be caused by operational aspects (e.g. WAN team to operate the WAN infrastructure and LAN team responsible for security) or by interface aspects of the to be used routers (e.g. R-1A has Ethernet only interfaces and WAN-1A is capable of supporting special serial interfaces (E1/PRI, SDH or microwave/SAT).



Routing aspects for operational model M2:

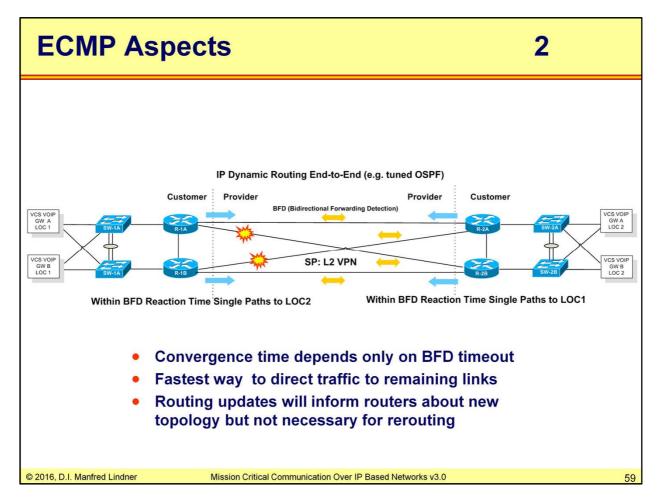
In this case again all IP routers are under control of the customer. L2 VPN provider just provides L2 (nowadays Ethernet) links which are used to interconnect the IP routers. Remember that these Ethernet links are just a kind of virtual links because L2-VPN providers put their service on top of a packet-switching infrastructure (e.g. IP-MPLS) shared among different customers, hence statistics concerning delay and throughput will be experienced on such links. Again dynamic OSPF routing (tuned OSPF to reach convergence with in a second) and BFD (to detect any indirect failures caused by the L2 VPN provider) can be applied straight forward.

The advantage of such a model is that a customer can build any point-to-point topology between locations by using just L2 links of the provider. The picture shows a redundant topology between two locations.

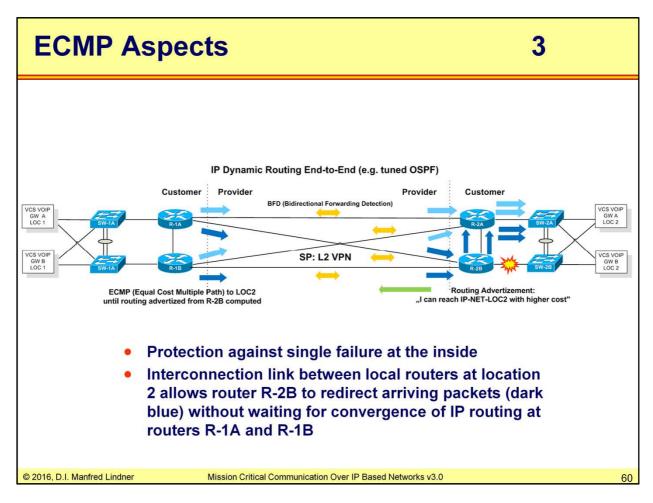


The following picture shows usage of ECMP (Equal Cost Multiple Paths) which provides the fastest convergence time which can be achieved with IP network technology. With ECMP traffic is load balanced session/flow-based across all available paths showing the same routing metric. For example R-1A will sent traffic of one session to R-2A and traffic of another session to R-2B. In Cisco routers this is done by hardware friendly CEF switching per default. Even if the two Ethernet links are coming from different service providers using different provider-internal base technologies from the point of IP routing there are equal. By forcing a session to one of the links the session will experience only the statistics of one provider over time which is in any case better than load-balancing on an individual packet base (without any knowledge of sessions).

Attention: Now we see just point-to-point virtual links between our IP routers on the last picture pretending to have four separated links between the two locations. It is always a challenge to clarify or to agree with the L2 VPN provider that these four links should be using separated physical paths and separated provider internal components (AD1, AD2, AD3, AD4 -> e.g. Add/Drop SDH multiplexers).



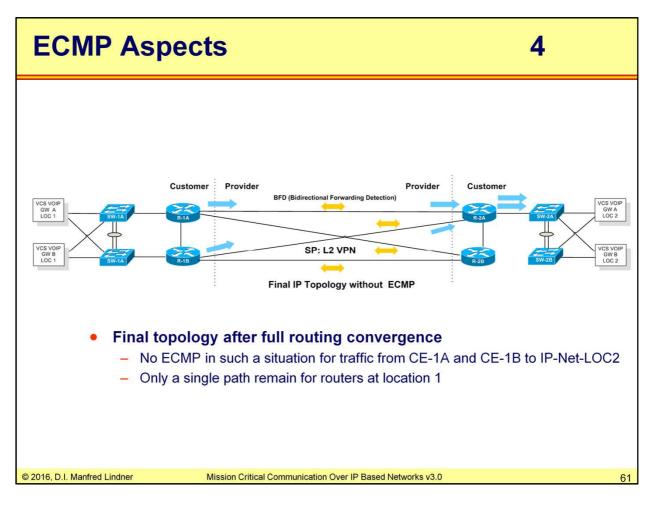
In case of failure on a WAN Ethernet link the following will occur: Packet in transmit will of course be destroyed, but just at the moment when the routers recognize the link failure (directly by disappearance of physics or indirectly by timeout of BFD) the next and all following packets will be forced to use the other path without any need to wait for convergence time of an IP routing protocol. The picture shows a double failure which forces the traffic to flow on the remaining links. Of course the routing protocol will produce an update sent to all other routers to inform about break of links, but the affected routers need not to wait for such routing updates in order to react (reroute the traffic).

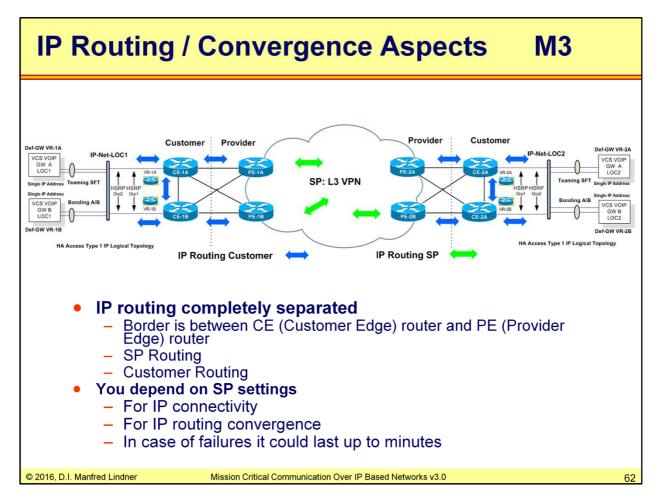


Finally this picture shows one reason for interconnection of routers on one location.

Assume R-2B loses the Ethernet connection to the systems of location 2. For convergence of outgoing traffic HSRP will do the job. For redirecting incoming traffic to router R-2A a routing update to the other site will force all traffic to router R-2A because we have no equal cost paths anymore. But this takes some time. Still packets for VCSA/B-LOC2 will arrive at R-2B and of course R-2B will forward them towards the alternate router R-2A using the interconnection link (which is a local fast decision based on the physical failure). So again only the packet in transmit across the erroneous link will be destroyed. All the next packets can flow without any disturbance. Traffic successfully transmitted over the WAN needs not to be discarded because one link at the location goes down. The interconnection link keeps the failure concerning convergence time local and sessions will experience minimal disturbance only for the time to discover the failure which is not avoidable per se in any case.

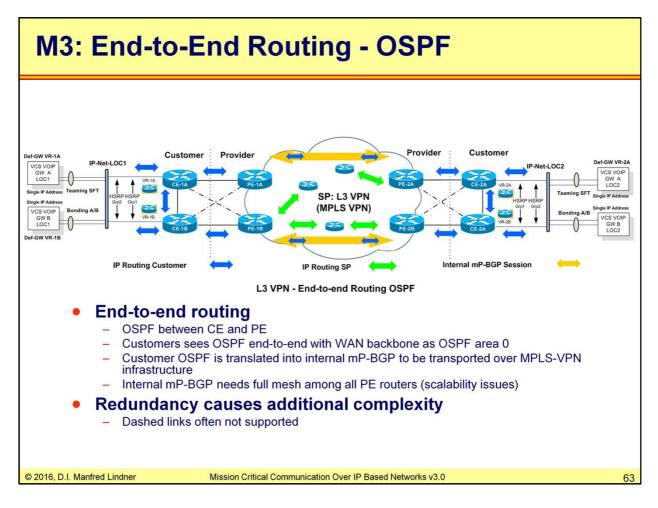
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Routing aspects for operational model M3:

In this case IP routing within the service provider is completely separated from the IP routing in the customer domain. The separation can be seen by differentiation of CE (customer edge) routers and PE (provider edge) routers. That clarifies who is responsible for operation of the router devices.

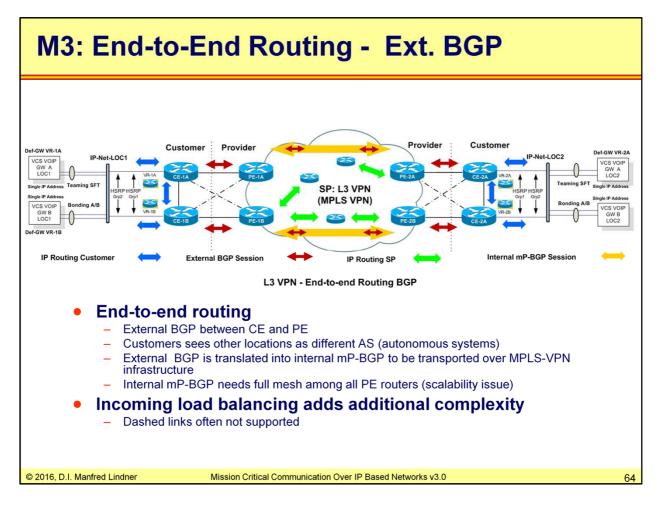


One of the basic questions to be answered is, if customer needs end-to-end IP routing in order to select different paths/providers or if customer can use default routing to all remote locations.

End-to-end IP routing can be achieved by L3-VPN service providers by usage of MPLS-VPN technology. For example IP OSPF customer routing can be transported end-to-end over provider internal mP-BGP sessions of MPLS-VPN technology.

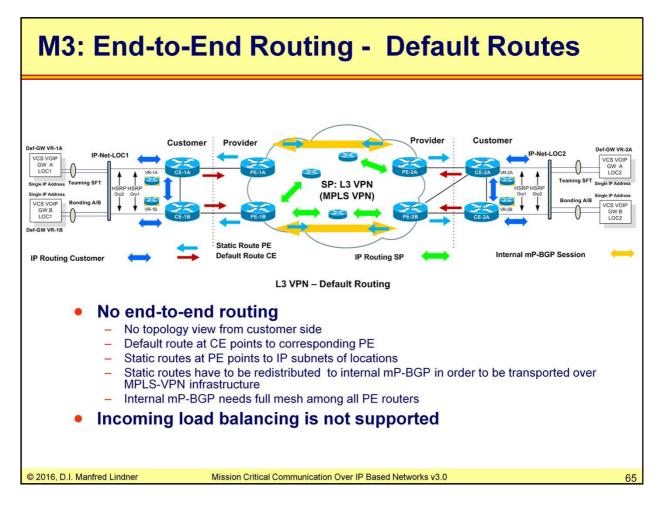
In case of redundancy that is a real challenge for the service provider. So the cross-links between CE and PE routers are drawn as dashed lines or even omitted in the following pictures to indicate that MPLS VPN providers usually do not support such topologies.

A single link between a CE and PE router is the preferred way from the viewpoint of the provider. You can see that such a redundancy makes sense from the viewpoint of physical topology but it will not supported by the providers with their routing techniques. So how many links from CE to PE are really useful depends on the operational model you choose.



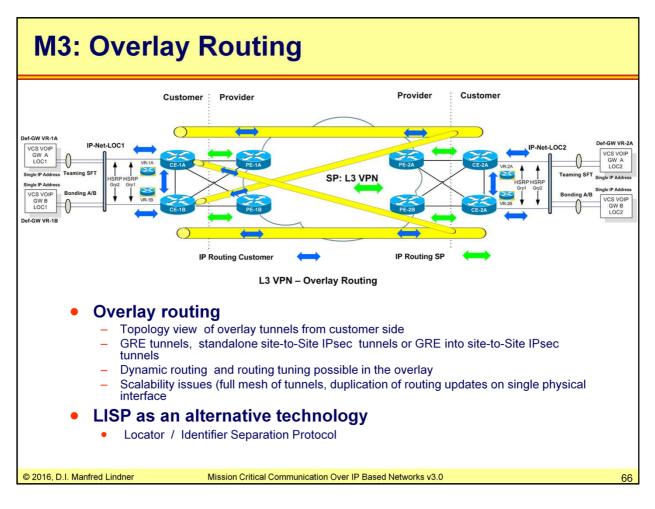
Another approach for end-to-end IP customer routing is to terminate OSPF at the CE router of a location and interact with the PE router via external BGP.

You need to design end-to-end routing, configure all the corresponding routing protocols, try to tune them for low convergence time and test it for all failure scenarios.



Default routing at the CE routers together with static routes configured at the PE routers is much simpler, but because of the static nature not so flexible in case changes have to be implemented fast.

In any case of MPLS-VPN IP addressing and IP routing has to be harmonized between the customer and the service provider. Also SLAs have to be defined on the borders to settle down responsibilities and procedures for interaction of involved parties.



Another approach when dealing with L3 VPN service providers or even with the Internet as IP WAN is to implement an overlay network starting at the CE routers on top of any given L3 connectivity offered by service providers or ISPs. Now the challenge is at the customer side to implement IP connectivity and tuning routing convergence across the overlay.

The benefit for the customer is to get control over these topics back from the provider. Examples for such overlay networks are GRE, LISP as separation techniques controlled by the customer or site-to-site VPNs based on IPsec or SSL if security issues for integrity and privacy are involved. In all these cases the provider acts just as simple IP connectivity enabler transporting encapsulated IP messages between PEs in the provider controlled IP address space. Hence no interference with IP addresses of customers or complex NAT solutions are necessary.

Attention: There are issues concerning scalability with L3 VPN based on MPLS-VPN or legacy overlay techniques (site-to-site IPsec VPN, SSL VPN). MPLS-VPN suffers from internal mP-BGP (fully meshed or usage of route reflectors) and number of customer injected into MPLS-VPN for customer end-to-end routing. Site-to-site IPsec/SSL VPN suffers from number of point-to-point security associations (configuration and performance) and from duplication of routing broadcast (hello, updates) into each logical tunnel to which the CE router is connected (performance and congestion point on the physical interface to the PE router).

LISP (Locator / Identifier Separation Protocol) - as possible future provider independent network technology - seems to be interesting candidate for VPN networks. LISP does not suffer from scalability issues because of a tunnel-free, configuration friendly and self-deploying approach to build the overlay. LISP enables customer to build a basic VPN over any service provider infrastructure, which separates the customer traffic from all other traffic in the service provider in the same way as MPLS-VPN does. LISP together with GETVPN (Group Encrypted Transport VPN) enhance this basic VPN with security (integrity, privacy) maintained by GETVPN. GETVPN is IPsec based on group keys distributed by key servers, needs no point-to-point security associations and hence scales much better than traditional site-to-site IPsec VPN.

If you want to get more information on LISP consult the correspondent lecture part.

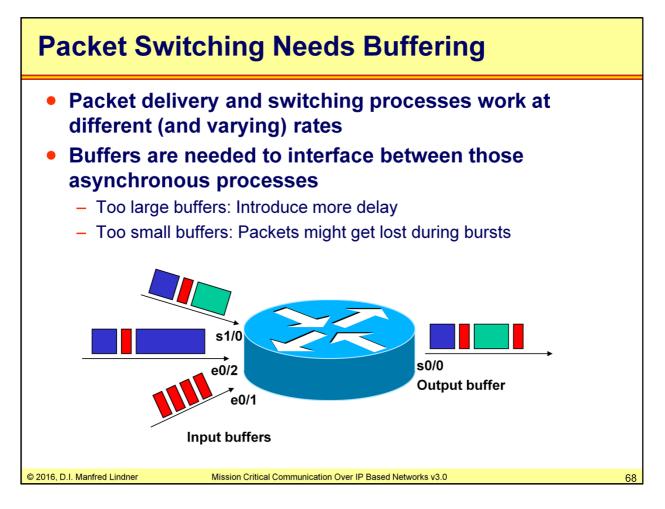
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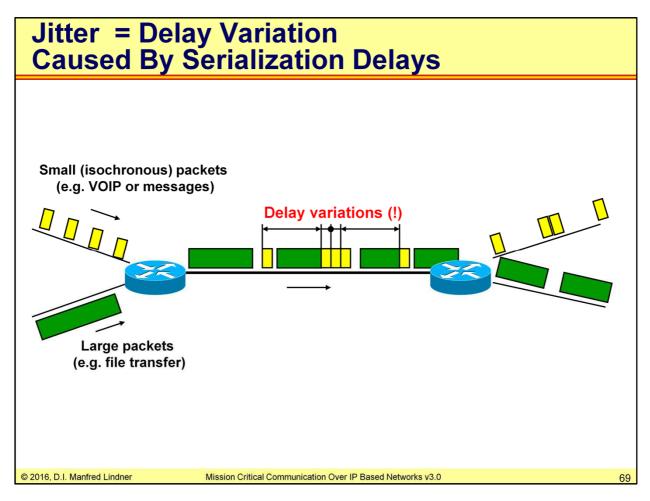
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It is a common misunderstanding to assume that queues are always filled at a certain percentage. If this would be the case then traffic bursts would occur too frequent and the probability of congestion is very high.

Note that queues should only smooth bursts! On average the traffic rate should be easily handled by the network devices (packet switches in general) without filling the queues considerably.



Delay in networks:

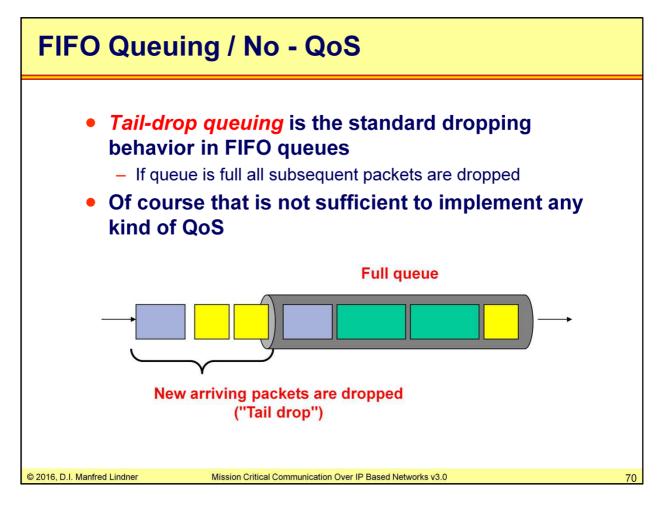
Serialization delay is the time which is necessary to put a block of bits on a serial line with a given bitrate.

Propagation delay is the time which is needed for a electrical signal to propagate along a given length of line / transmission path. The upper limit for velocity is of course the speed of light.

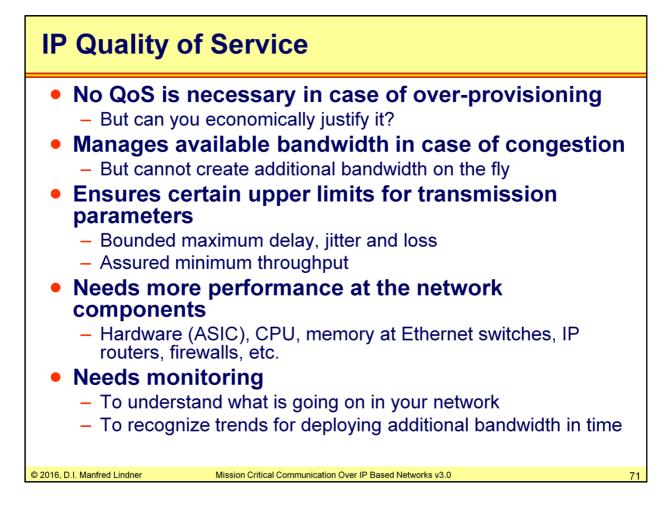
Switching delay additionally occurs in case of the presence of an active component in the transmission path.

If small packets can be forwarded without waiting for the link to be ready then delay variation will be small. If small packets cannot immediately be forwarded because link to be used is occupied by another ongoing transmission (especially if long packets are on the way) then delay variation will be large. Also you can see in the picture that isochronous traffic can lead to packet burst which happens if for a certain time a sequence of such small isochronous packets was buffered and then send out one packet after the other without any gap.

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"First In First Out " is the default behavior of all packet switching devices, Does a good job, if network is not saturated and is easy to be implemented.



Synchronous networks (also called "isochronous" networks) have no problem with quality of service: Each piece of data is transmitted in equal times and there are no "bursts" of data that would lead to sudden congestion. Real synchronous clocking of all network components means no need of any buffers.

The Internet on the other hand is an extremely inhomogeneous and asynchronous kind of network. It is a network of networks and the prevalent type of traffic is data traffic. Data traffic is bursty by nature.

What is meant by "Quality of Service" (QoS) actually? The total network bandwidth is shared by many users and applications. We demand for QoS in that some specific type of traffic should be handled "nicer" than others. When buffers in routers and switches are congested then delays and packet-drops occur. One solution is to over-provision the network, but this is expensive and the behavior is still unpredictable.

Thus QoS mechanisms are thought to **manage** the network resources in terms of bandwidth and queuing behavior, so delays can be limited.

IP QoS mechanisms ensure that the most important IP datagrams will get their sufficient traffic characteristic behavior (e.g. bounded maximum delay but still variable, bounded maximum jitter, zero loss or loss below certain percentage, assured minimum throughput) during times of congestions. Of course quality of service is determined by the weakest link between each two points of communications.

Important to know is that QoS cannot create additional bandwidth. You are still limited to the given physical bit-rate / bandwidth on the weakest network link between source and destination of traffic. QoS mechanisms can only manage the available bandwidth according to a QoS policy during time of congestion.

The negative side of these mechanisms is that less important traffic will suffer (= higher delay) or even will be killed (= loss because of no buffer resources are available). Hence it can be conducted that QoS can overcome only short-time temporary congestion but no long-time congestion. During long-time-congestion less important traffic will get into starvation so either this traffic has no real importance to the overall system or the bandwidth has to be increased anyway to keep such traffic flowing again.

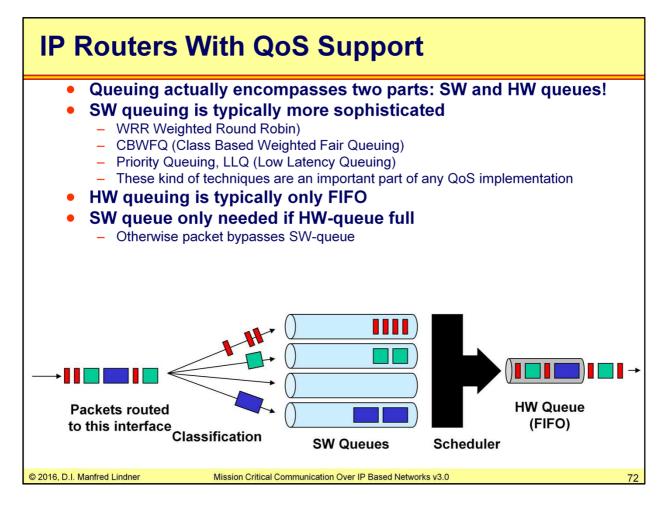
QoS mechanisms need to be supported by the network components, hence such QoS enabled components need more performance (CPU) and in case of higher speed links hardware support (ASICS) especially for queuing. Software queuing may be sufficient up to 2-10 Mbps speed. Hardware queuing is a must for Fast Ethernet (100 Mbps) and higher.

QoS monitoring helps verifying the communication matrix and real behavior of distributed communication. It also allows base-lining and forecasts. Hence network performance can be increased by adding more bandwidth to the corresponding links in time in a proactive way.

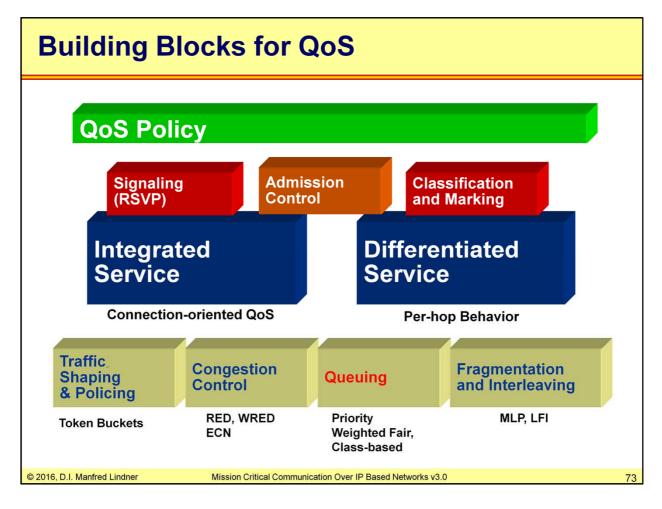
Golden rule is to have more bandwidth as needed in the network (over-provisioning) and usage of the QoS system just to overcome temporary traffic bursts.

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Ethernet switches with QoS support are a little bit different. They often support advanced queuing techniques in hardware.



The diagram above shows the main building blocks of a QoS design. Let's discuss it from the bottom to the top:

The first layer represents important tools which are almost always present in a QoS architecture:

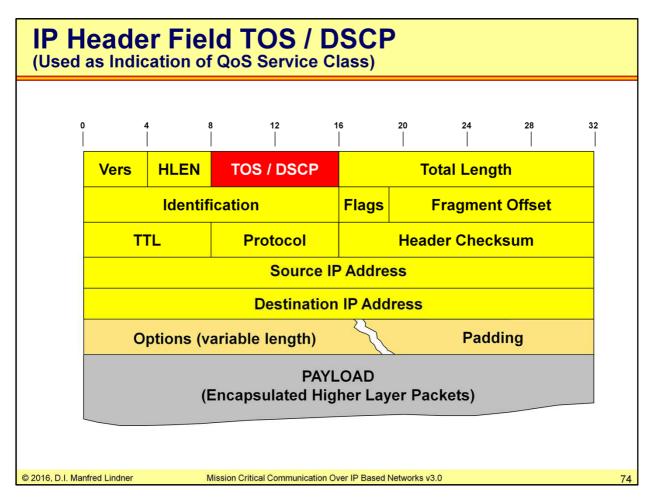
Traffic Shaping (smooth bursts), **Congestion Control** (avoid bottlenecks and denial of service), **Queuing** are the most fundamental parts of QoS. **RED** (Random Early Discard) randomly drops segments before queue is full by utilizing TCP specific behavior of dynamically adjusting traffic throughput by reducing TCP window size. **WRED** (Weighted Random Early Discard) drops less important packets more aggressively than more important packets based on ToS/DSCP value. **ECN** (Early Congestion Notification) allows ECN capable routers to inform TCP sessions to reduce TCP window size before a packet drop occurs. **MLP** (Multilink PPP) and **LFI** (Link Fragment Interleaving) are techniques to provides load balancing functionality over multiple WAN links, while providing packet fragmentation and proper sequencing. MLP allows packets to be fragmented and the fragments to be sent at the same time over multiple point-to-point links to the same packets to be multilink encapsulated and fragmented into a small enough size to satisfy the delay requirements of real-time traffic. Small real-time packets are not multilink encapsulated and are sent between fragments of the large packets. The interleaving feature also provides a special transmit queue for the smaller, delay-sensitive packets, enabling them to be sent earlier than other flows.

The next layer represents two totally different QoS architecture principles: **Integrated Service** ("**IntServ**") and **Differentiated Services** ("**DiffServ**"). IntServ (RFC 1633) is a connection-oriented approach but seems not to be scalable for large networks. DiffServ (RFC 2475) is connectionless and more scalable but QoS is difficult to control. Both technologies adjust the queuing parameters.

We will concentrate on DiffServ principle for our discussion of IP QoS.

On the next layer, the diagram presents the instances that are used to implement QoS: IntServ uses a signaling protocol called **RSVP** (Resource ReSerVation Protocol, RFC 2205) and DiffServ uses a **Classification** and **Marking** engine in the packet switches (routers). **Admission Control** assign QoS to dedicated users (dynamic on demand by usage of signaling for IntServ and static in a provisioning phase for DiffServ).

Finally on the top layer the **QoS Policy** constitutes a fundament for the whole QoS concept. Here all desires and rules are specified.



The IP header supports classification of service classes in the TOS (Type of Service, 8 bits.) or DSCP (Differentiated Services Code Point, 6 bits) field. Usage of original ToS (RFC 1430, 1349) was seldom implemented in the applications and only partly supported by routers. DSCP (RFC 2474) is the current way to implement DiffServ in the IP world by classifying IP datagrams to belong to a certain QoS class, which is handled by the routers according to the QoS policy.

ToS (old meaning):

Tells the priority of a datagram (3 precedence bits) and the preferred network characteristics (4 bits, low delay D, high throughput T, high reliability R, low monetary cost B). Precedence bits define the handling of a datagram within the router e.g. priority within the input / output queues. D, T, R and C bits can be used to take a path decision for routing if multiple paths with different characteristics exist to the destination. That needs one routing table per characteristic which is not supported by current routing protocols anymore. TOS bits may be ignored by routers but may never lead to discarding a packet if the preferred service cannot be provided.

DSCP (current meaning for DiffServ):

Bits 0,1,2 – Class Selector: Again carries the 0-7 IP ToS precedence value. However there is a new definition of these values. See next slide.

Bits 3,4 – Drop Precedence: Carry the drop precedence which allows a further differentiation of traffic within the same class level. Note that this requires bit 5 to be zero.

Bits 6,7 – Currently Unused (or ECN...)

DSCP Values Overview

Code Point Name	DSCP		Whole IP TOS by		yte	
Code Folin Name	hex	dec	binary	hex	dec	
EF	0x2e	46	10111000	0xb8	184	
AF41	0x22	34	10001000	0x88	136	
AF42	0x24	36	10010000	0x90	144	
AF43	0x26	38	10011000	0x98	152	
AF31	0x1a	26	01101000	0x68	104	
AF32	0x1c	28	01110000	0x70	112	
AF33	0x1e	30	01111000	0x78	120	
AF21	0x12	18	01001000	0x48	72	
AF22	0x14	20	01010000	0x50	80	
AF23	0x16	22	01011000	0x18	24	
AF11	0x0a	10	00101000	0x28	40	
AF12	0x0c	12	00110000	0x30	48	
AF13	0x0e	14	00111000	0x38	56	
CS7	0x38	56	11100000	0xe0	224	
CS6	0x30	48	11000000	0xc0	192	
CS5	0x28	40	10100000	0xa0	160	
CS4	0x20	32	10000000	0x80	128	
CS3	0x18	24	01100000	0x60	96	
CS2	0x10	16	0100000	0x40	64	
CS1	0x08	8	00100000	0x20	32	
CS0 = BE	0x00	0	00000000	0x00	0	

Expedited Forwarding (EF): DSCP 46 = 101 110 binary For low delay, low loss, and low jitter Defined in RFC 3246

Assured Forwarding (AF):

12 codepoints: 4 classes and 3 drop precedence each

Defined in RFC 2597

Guarantees a certain bandwidth to a traffic class.

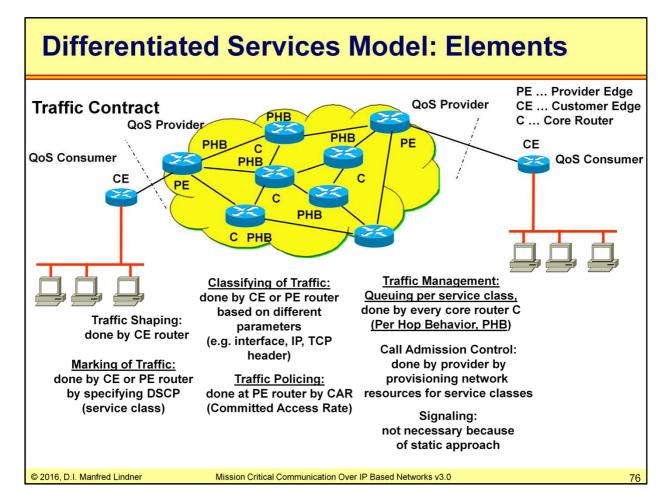
If the traffic exceeds the committed bandwidth the drop probability is raised according to the specified drop precedence.

There are 12 different AF behavior code points consisting of 4 classes (AF1y to AF4y) and 3 drop probabilities (AFx1 to AFx3) for each class (low/med/hi)

Best Effort (BE): 000000 binary

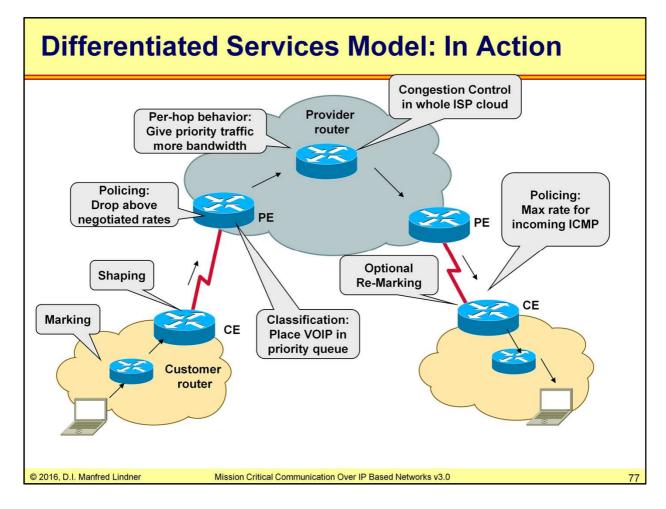
The legacy ToS IP Precedence values (0-3) can be directly mapped into the three Class Selector bits (0,1,2) with the three LSBs (3,4,5) set to zero This results in the seven CSx values CS0 = DSCP 00 = 000000... CS7 = DSCP 56 = 111000

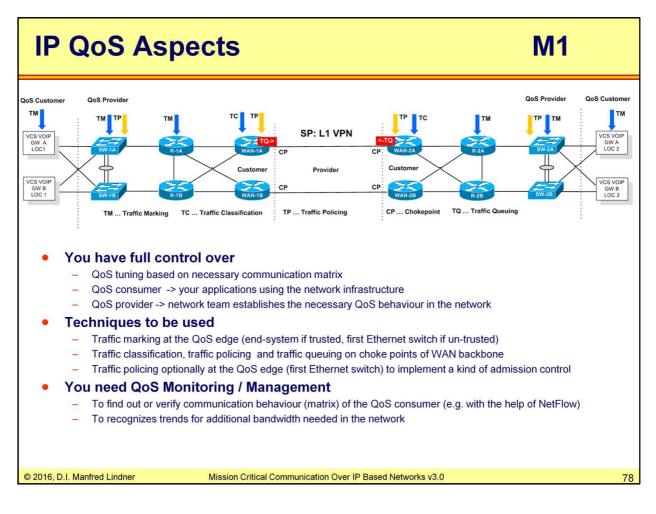
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QoS mechanism are traffic marking (TM, assigning an IP packet to a QoS service class), traffic classification (TC, assigning traffic into different queues of a router/switch), traffic policing (TP, controlling amount of traffic of a given service class and acting on violation of traffic contract for this service class), traffic shaping (TS, reforming traffic characteristics regarding burstiness and average throughput to fulfill a given traffic contract) and finally queuing strategy applied to queues maintained by a router (PHP, Per-Hop-Behavior). Typical queuing strategies are WFQ (Weighted Fair Queuing), PQ (Priority Queuing), FIFO (FirstInFirstOut Queuing), WRR (Weighted Round Robin), CBWFQ (Class Based WFQ) and LLQ (Low Latency Queuing - combination of PQ and CBWFQ).

Recommendation: Analyze the tradeoff between QoS management compared to over-provisioning in your solution. Think about if it is really worth to invest in technology and operational people instead of taking the more expensive wire. Especially testing is a challenge, because QoS comes only into action if there is congestion in the network. Producing of huge traffic may be a problem in a simple test-lab for verification of overall functionality and performance. Fixing it in the operational network might be not possible. A sound network monitoring is necessary in all cases.





Depending on the operational model QoS mechanism can implemented with reasonable effort in case you have full control over the network (e.g. only L1-VPNs are provided by external partners). In case part of the network is operated by a service provider (L2-VPN or L3-VPN) QoS management and supervision becomes much more complicated.

IP QoS aspects for operational model M1:

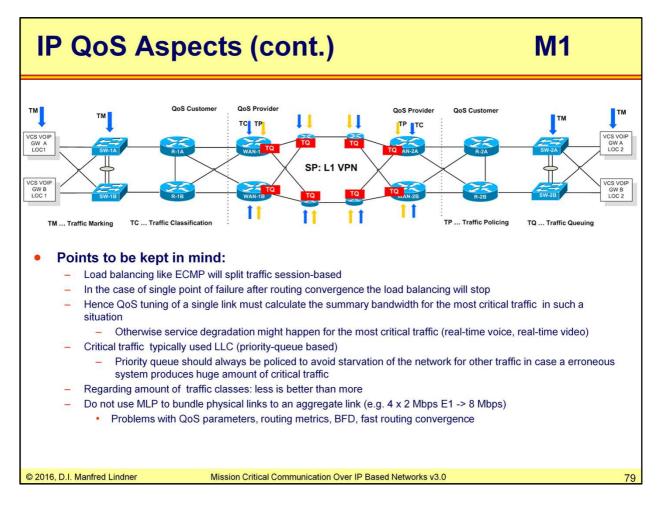
Model M1 is based on L1-VPN links with (dedicated) constant bandwidth and constant delay provided by an external service provider. Usually the bandwidth on the WAN links will be much slower (e.g. 1.5 to 8 Mbps) than the access speed at the location (Fast Ethernet, Gigabit Ethernet). So probability is very high that the WAN link becomes a real chokepoint.

The customer has full control over the network by managing all active L2 (Ethernet switches) and L3 components (IP routers). QoS mechanism can be implemented and tuned with reasonable effort based on the communication matrix of the distributed systems.

The communication matrix describes who is talking to whom (source and destination IP addresses, IP protocol type, TCP/UDP port numbers, and communication style such as unicast, multicast or broadcast) and the traffic statistics of the communication sessions (average bandwidth, burstiness). There is a (hidden) traffic contract between QoS consumers (the applications) and QoS provider (the overall network operated by the customer).

Traffic marking (TM) can be done either by the end-systems themselves or by the first Ethernet switch (preferred -> TM usually done in hardware) or IP router (second choice -> TM usually done in software) where end-systems are connected to. The decision where to do TM depends if end-system can be trusted or not. If they are not trusted the network should apply the service class in the IP DSCP field of bypassing IP packets. Optionally the first network component can apply also traffic policing (TP) to reduce amount of traffic of a given end-system to that what is agreed. Traffic classification (TC) and traffic queuing (TQ) is a must at the chokepoint (outgoing interface towards L1-VPN link at WAN-1x, WAN-2x routers).

Optionally traffic policing (TP) can be performed at the choke-point to eliminate any unwanted traffic during times of congestion without filling the queues of a service class. QoS monitoring (statistics about queue depths, dropped packets, average usage per QoS service class) can give you a feeling, what is really going on in your network either verifying the communication matrix or adjusting the knowledge about the communication behavior of your applications.



Attention: QoS monitoring gives you information about a service class. If more than one communication session is using a service class - that is the common approach - then you cannot see the details of a particular communication session. In such a case NetFlow monitoring performed on IP routers should additionally be used to see more details, which has to be correlated with QoS monitoring statistics. Depending on the quality of your network management system, that can be achieved with different effort. NetFlow allows you to see how many packets per communication session are passing across an IP router (routers R-1x or R-2x are candidates for NetFlow).

The pictures shows a typical distribution of QoS mechanism for supporting X locations and placing the border between QoS consumer and QoS provider on the border between LAN and IP WAN.

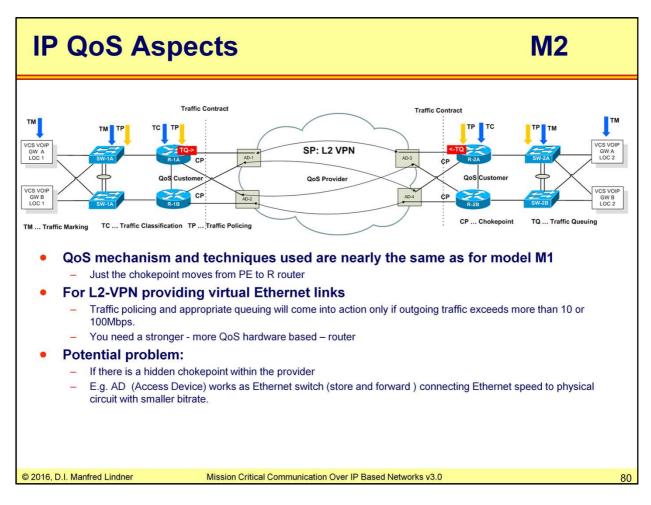
QoS tuning can become quite tricky in such a scenario. Remember ECMP where load balancing is performed on a session base. If one path fails the other will take over the traffic either immediately or after routing convergence succeeds. QoS tuning of a single link has to calculate such events. Therefore the summary bit rate at least for the most critical traffic (e.g. real-time voice) flowing between two locations has to be calculated and provisioned on such a link. Otherwise service degradation will happen in case of a failure. So load balancing sounds good for high availability but with from QoS point of view it is more complicated. Assure that your network has reasonable bandwidth in all possible scenarios of single point-of-failures independent from the physical network topology. That means that you have to support the sum of all critical traffic over all core physical links in the worst case.

Further critical traffic is typically priority queued to achieve low latency. If a device creates a huge amount of such traffic (either by a failure or part of a security attack) all other service classes will starved. Therefore priority queues and/or critical traffic should always be policed in order to avoid starvation of other traffic, which may be even not so critical but still important. In most cases you have only one priority queue available at IP routers. So splitting critical traffic (which needs low latency) into many service classes will not help.

Golden rule: Keep the amount of traffic classes low.

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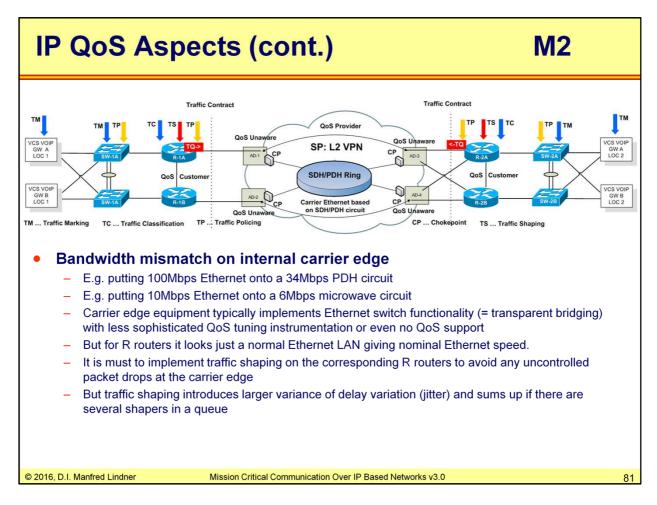
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IP QoS aspects for operational model M2:

Model M2 is based on L2-VPN links with constant access bandwidth but variable delay provided by an external service provider. One example is a VPLS service based on an IP-MPLS infrastructure with e.g. 10 or 100Mbps Ethernet links towards the customer. If outgoing traffic of a location can reach more than 10 or 100Mbps then QoS mechanism can be applied in nearly the same way as for model M1. Only traffic classification (TC) and traffic queuing will move from the WAN router to the R-1x, R2-x routers. Keep in mind that QoS mechanism applied for link speed higher than 10Mbps needs a stronger router (hardware based QoS).

Be careful if your traffic passes regions where no QoS support can be implemented. You will turn back to best-effort system over such region which may not satisfy your QoS requirements in case of congestion. Typically example are gateways between Ethernet and microwave or SDH circuits which behaves as transparent bridge (= Ethernet switch) store and forward packet switching device without knowing about L2 or L3 QoS hence doing best-effort FIFO queuing only. Next slide explains such a problem.



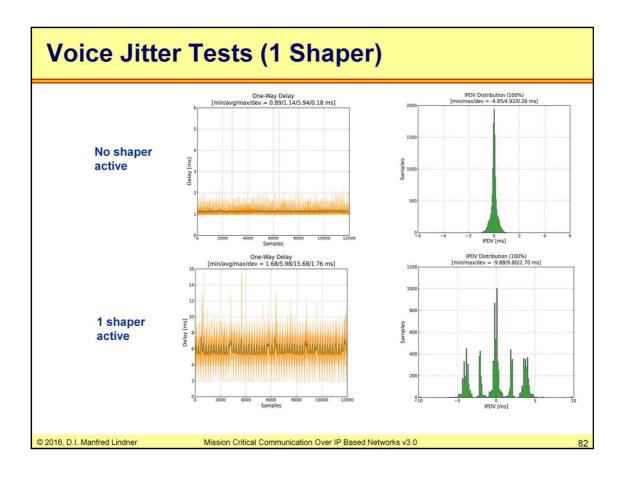
A L2-VPNs based on microwave/SAT modems or SDH-AD (Add/Drop) multiplexers offering their service on a corresponding Ethernet link to the customer routers can result in a speed mismatch between the Ethernet link and the microwave-link or SDH circuit (e.g. 100 Mbps Ethernet should use a 34 Mbps circuit).

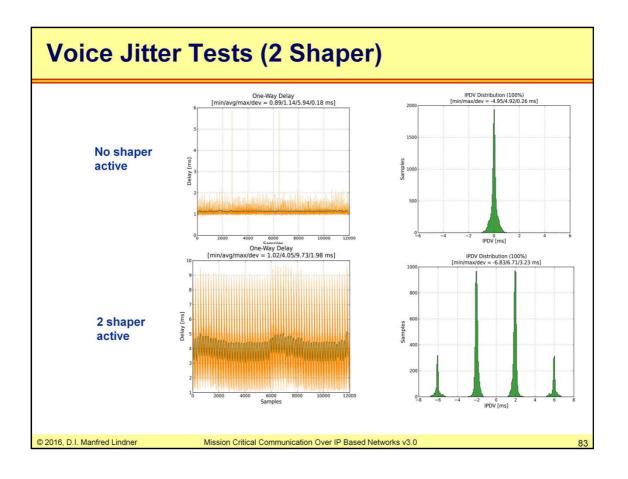
In such a case the provider equipment acts as Ethernet switch performing packet switching between the different physical technologies. In case of packet bursts it can happen that buffering is not possible anymore and some packets get lost. Usually such provider equipment does not support L3 QoS mechanism. So if for example only 34Mbps are possible for a 100Mbps Ethernet link between R-1A and R-2A then any TQ mechanism will not work, because they will come into action if the 100Mbps are overloaded.

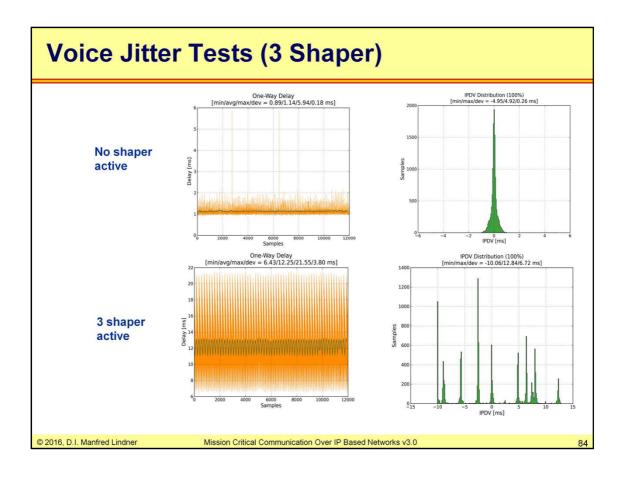
The only possible solution is usage of traffic shaping (TS) on R-1A and R-2A. Traffic shaping will configured in such a way that - whenever outgoing traffic exceeds 34 Mbps on the 100 Mbps Ethernet link - traffic shaping will backpressure this traffic allowing traffic queuing and traffic policing to act according the QoS policy. Of course traffic shaping - when active e.g. traffic above 34 Mbps - introduces additional delay and a more variable jitter. But it is the only possibility to deal with the QoS unaware provider equipment in between. The picture shows such a scenario.

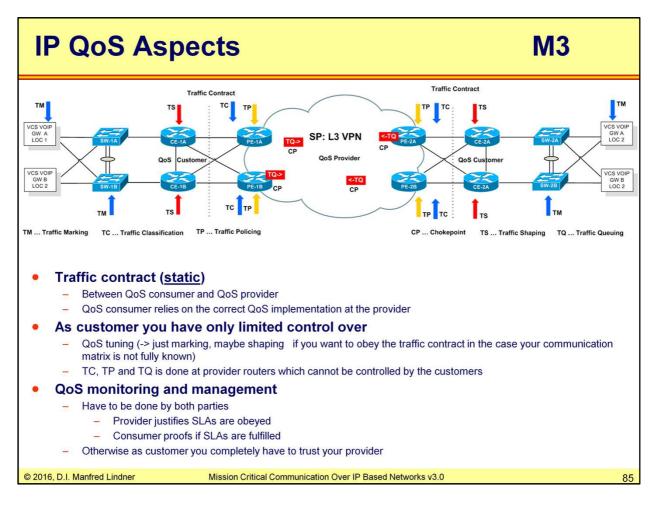
Please recognize that the real chokepoint has moved to the provider device which is QoS unaware. At the customer routers TS simulates these chokepoints to get QoS mechanism into action one step before.

Attention: Traffic shapers produce a more statistical distributed delay variation (jitter). Therefore be careful not to add too many of such shapers in a sequence between your distributed systems relying on critical communication sessions.









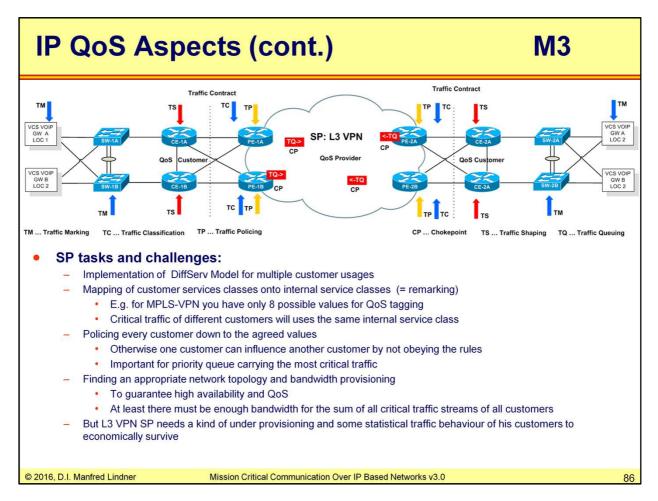
IP QoS aspects for operational model M3:

Model M3 is based on a L3-VPN provided by an external service provider. Nowadays such a L3-VPN is usually implemented by MPLS-VPN technology on top of an IP-MPLS packet switching network infrastructure. Without any IP QoS mechanism this is a best-effort network like the Internet (variable bandwidth or throughput and variable delay). Even if you are happy to find a provider offering IP QoS guarantees then this is still the most challenging approach.

First because a QoS contract has to be defined and implemented between QoS customer (network where the distributed processes reside) and QoS provider (network part which is controlled by a service provider and hence QoS statistics of provider part is not accessible for the customer or may not be trusted by the customer).

Second because either the customer has to fully trust the provider or has to perform QoS monitoring on its own to have a proof about the SLA to be guaranteed by the service provider. Obey that QoS traffic contract has static nature. So changes of the contract cannot be done in seconds. In needs some preliminary lead time especially to upgrade bandwidth in the network.

Third customer has only limited control over QoS tuning. Only traffic marking (TM) and optionally traffic shaping (TS) can be controlled by the customer in its domain. The chokepoints are somewhere within the provider network but technically supervised by traffic classification (TC) and traffic policing (TP) at the PE routers. The picture shows a typical scenario.



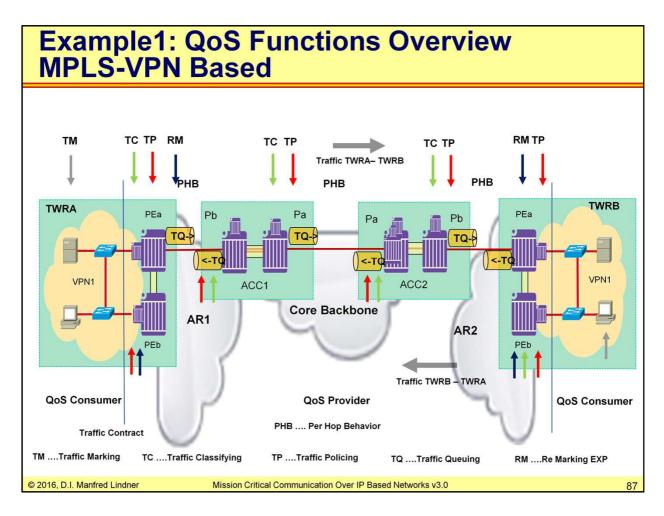
Also the service provider has a quite a challenge and a lot of tasks when offering IP QoS to customers. Why?

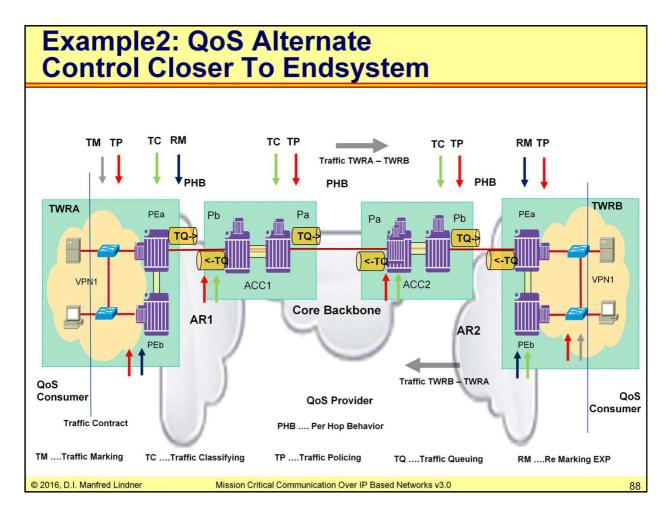
Implementation of payable IP QoS service based on Differentiated Services model for multiple customers is not so straight forward than implementing that model in a single domain such as our M1 network operational model. For example mapping of customer service classes agreed by the particular traffic contracts to only 8 QoS tags usable for MPLS (so called experimental Bits in the MPLS header) will lead to aggregation of a lot of critical customer traffic in just one service class used within the provider infrastructure. Remark: A service provider offering IP QoS based on LISP network technology would have 64 DSCP values instead of 8.

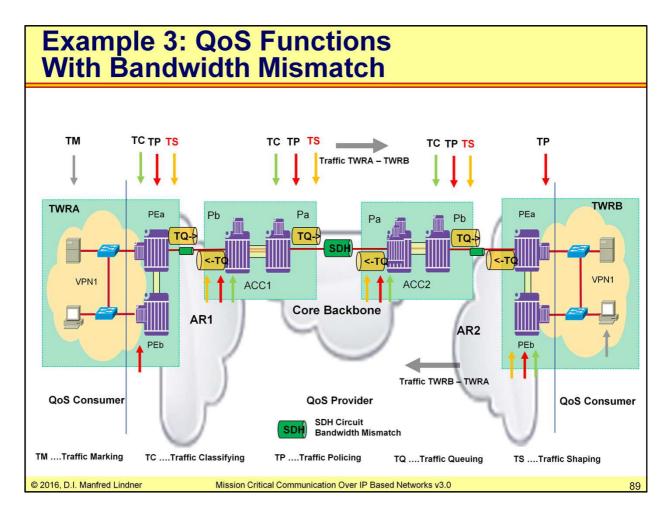
Policing every customer down to the agreed values is a must otherwise one misbehaving customer will influence other customers because of service class aggregation used within the provider. That is especially important for the priority queues carrying the most critical traffic.

Last but not least finding an appropriate network topology and bandwidth provisioning in order to guarantee high availability by usage of redundancy and automatic switchover together with QoS provisioning is not quite easy. Remember the discussion about ECMP and QoS in case of a failure. In the worst case every link in the core has to provide the sum of all bandwidth guarantees for all customers. But on the other side a service provider needs a kind of under-provisioning and some statistical traffic behavior of its customer (that means not all customers sending their guaranteed traffic all the time) to economically survive.

QoS monitoring is a must in order to proactively react by increasing bandwidth on the network links before customers complain about performance. QoS reports given to the customer for proofing SLAs need a certain kind of trust relationship between the customer and the provider. Trust is based on professional working and a real service oriented attitude. Both have its costs.







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Information Security (Definition ISO 27001:2005)

- Preservation of <u>confidentiality</u>, <u>integrity</u> and <u>availability</u> of information
 - In addition other properties such as authenticity, accountability, non-repudiation and reliability can also be involved
- Confidentiality (Privacy)
 - The property that information is not made available or disclosed to unauthorized individuals, entities or processes
 - Intuitive: the information can be read only by intended persons, field of "encryption"

• Integrity

- The property of safeguarding the accuracy and completeness of assets
- Intuitive: we can trust in the information, it is not changed unintentionally, field of "fingerprint and cryptographic checksum/hashes"

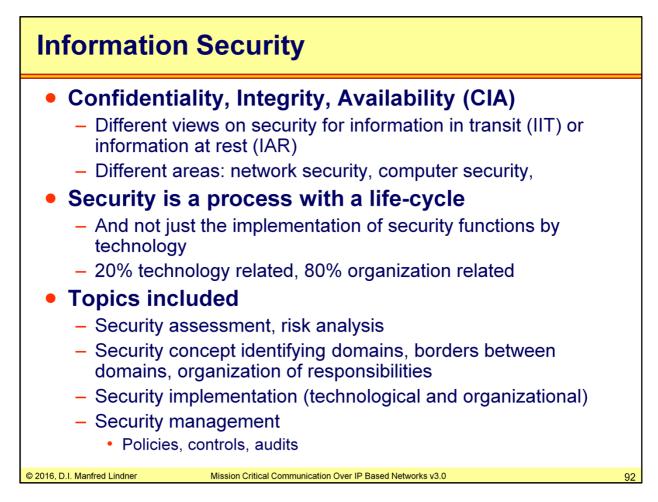
Availability

- The property of being accessible and usable on demand by an authorized entity
- Intuitive: the information is accessible when it is really needed

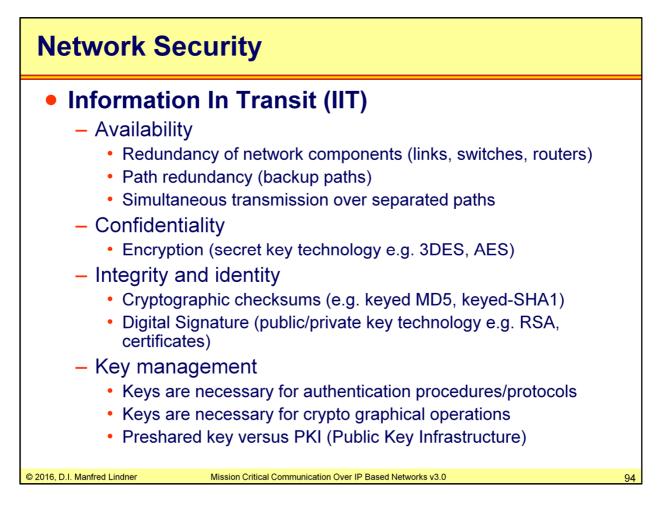
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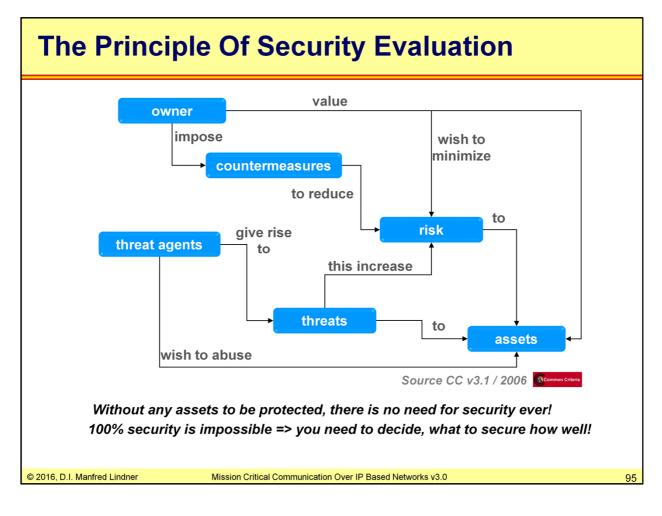
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Computer Security	
 Information At Rest (IAR) Availability 	
 Downsizing to required functionality Hardening and access control Redundancy Backup Confidentiality and integrity Access control (in most cases generic functionality of the OS) Authentication (e.g. username / password) Authorization (e.g. ACLs – access control list) (Encryption) 	
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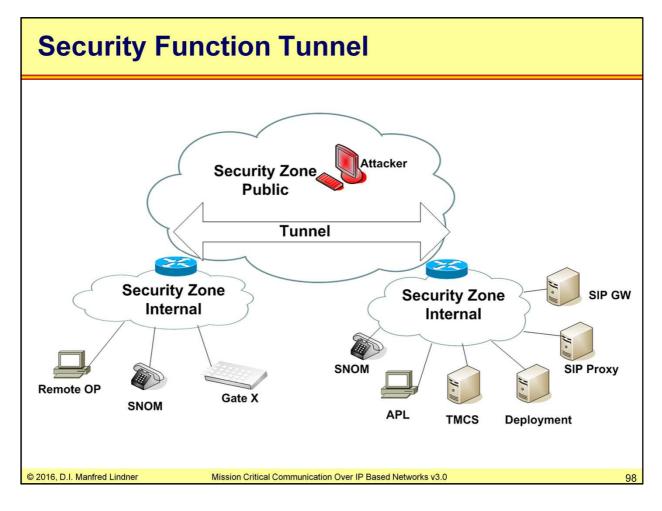


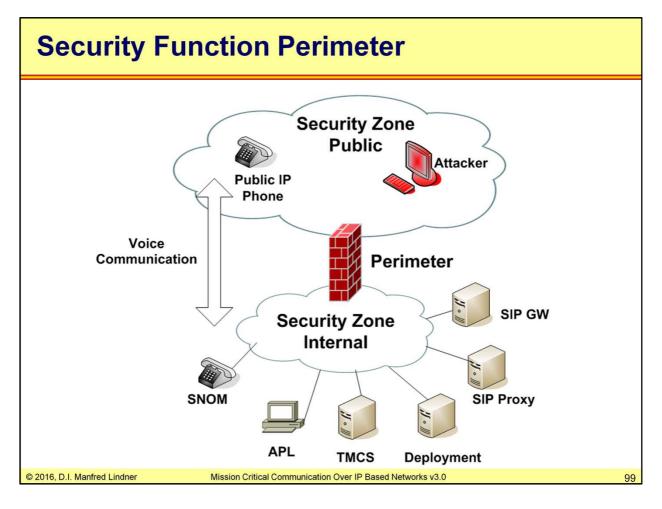
Security Assessment / Analysis					
	entassess security weaknesses in the product or system by dressing security risks in the system and in the system				
consolidation	critical devices or sensitive network connections are identified and the system structured in security zones	is			
requirements	confidentiality, availability, integrity , (access control, auditing, network separation, remote access)				
assumptions	Indicate requirements applicable only at the customer premises under his responsibility				
assets	Information or services be protected by the countermeasures of a system.				
threats	A potential cause of an incident , which may result in harm to a system or organization				
assess risk	Systematic use of information (assets, threats, assumptions, requirements) to identify and estimate the risk .				
objectives	Abstract statement of the intended solution to the security problem.				
measures	Technical, operative and procedural measures which support the objectives a lead to protection mechanism	nd			
remaining risk	Management of the residual risk so that the residual security risk is tolerab and as low as reasonably practicable.	e			
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IT-Security – Network Security Elements	
 "Security zones / domains" Definition of the environment systems or system parts are operating in 	
 Summarization of assumptions about Access to system physically protected Personal access to system protected by physical access control and strong authentication techniques 	
 "Multiple Barriers" In the network infrastructure and at the end system 	
 Generic security function "Tunnel" System parts are in the same security zone Ensures protected communication between dispersed system parts over non protected network infrastructure E.g. site-to-site IPsec VPN, client-to-site IPsec VPN, SSL-VPN 	
 Generic security function "Perimeter" System parts are in different security zones Ensures controlled communication between systems with different functionality and authorization rights E.g. firewall with stateful inspection 	
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Security mechanisms can protect communication between systems (information in transit, IIT) and control access to systems hence protect information at rest (IAR). The former is performed by "tunneling" techniques which use crypto-graphical methods to ensure integrity and privacy of IP datagrams on transit. Examples for that are IPsec-VPN, SSL-VPN, and HTTPS. The later (IAR) is performed by "perimeter" mechanism which use policies based on filters and authentication mechanism to decide if traffic is allowed to pass the perimeter. Examples for that are stateful firewalls, white-lists, and access-lists typically in cooperation with security servers like radius in case of larger deployments.

Based on security assessment and security policy typical topics to be covered by a security concept are clarification of security domains and the borders in between, clarification about organization of responsibilities, and finally agreement how security management should be established. Security implementation is always a combination of technological and procedural components. Only if all the initial work is done, finally the location of perimeter and tunnel mechanism can be concluded.





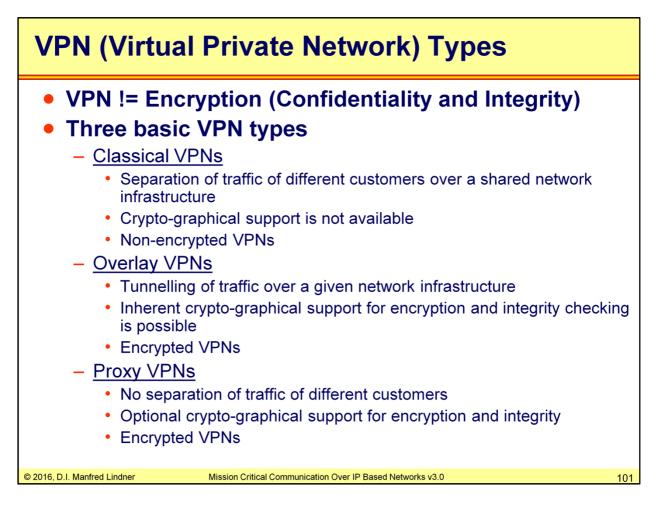
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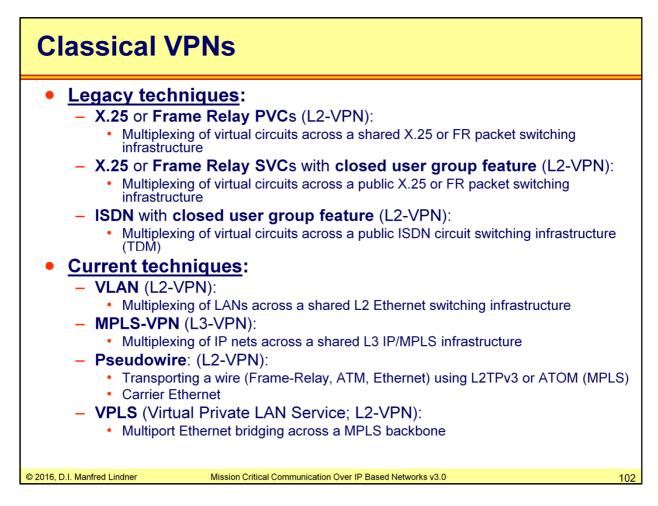


It is important to know that VPN does not automatically include support for encryption and integrity.

Classical VPN techniques like Frame Relay, VLAN, MPLS-VPN, VPLS, and LISP-VPN concentrates just on separation of traffic of different customers over a shared infrastructure.

Overlay VPNs like IPsec, SSL-VPN, and DMVPN have inherent crypto-graphical support for encryption and integrity checking. They can be seen as security tunnels between security gateways or between end systems and may operate either over a shared environment or on top of a classical VPN. Typically based on a point-to-point security relationship these techniques have scalability and performance issues (number of relationships, keys, states, key management).

With GETVPN based on IPsec with group encryption (point-to-multipoint security relationship) these scalabilities problems can be solved. Therefore GETVPN as tunnel-less technology is also called Proxy VPN doing neither traffic separation nor using a tunnel but still achieve privacy/integrity for traffic in transit.



SVC ... Switched Virtual Circuit

PVC ... Permanent Virtual Circuit

ATOM ... Any Transport Over MPLS

Overlay VPNs	
 GRE (Generic Route Encapsulation) Old technique often used in the Internet for transporting multiprotocol traffic (e IPv4 multicast, IPv6 unicast or IPX-Novell) over an IPv4 unicast-only backbox No encryption support but multicast is possible 	e.g. ne
 IPsec VPN Site-to-site VPN between VPN gateways or client-to-site VPN between an ensystem with VPN-client-SW and a VPN concentrator Point-to-point security associations Currently for unicast only, scalability problem for full mesh 	d-
 SSL VPN Alternative to IPsec client-to-site VPNs Originally based on HTTP over SSL 	
 DMVPN (Dynamic Multipoint VPN) Cisco implementation for large scale IPsec VPN Combines mGRE, dynamic NHRP/NHS and IPsec protection Multicast support is possible but could be suboptimal (Hub and Spoke) 	
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Proxy VPNs / Alternate VPNs
 GETVPN (Group Encrypted Transport VPN) Cisco implementation Point-to-multipoint security associations using group keys, tunnel less technology Multicast possible if backbone supports it
 LISP (Locator / Identifier Separation Protocol) Cisco novel approach for separation of identity ("Who I am", EID address space) from location ("Where I am", RLOC address space) Identity and location is normally represented by a just single IP address
 Network based solution Available already in Cisco IOS and NX-OS
 Open specifications and implementations Experimental RFCs 6830 - 6836 OpenLISP (open-source for FreeBSD) LISP mobile node (open-source for Linux and Android)
 Base VPN behavior By separating EIDs from RLOCs of IP WAN service provider
 Encrypted VPN possible By combining LISP with GETVPN
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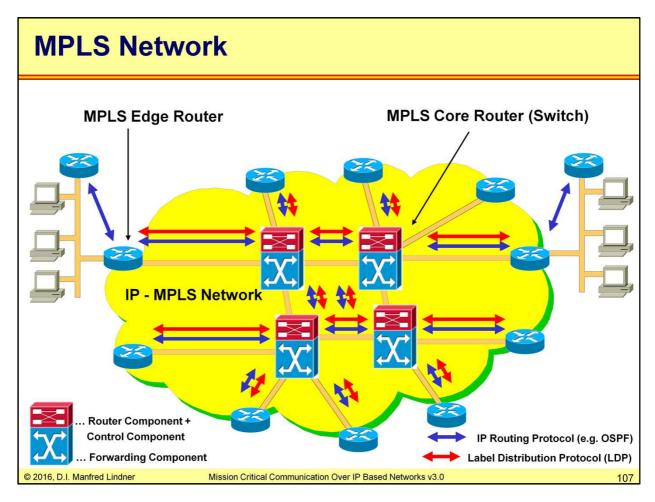
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MPLS Principle			
 Traditional IP uses the same information for 			
 Path determination (routing) 			
 Packet forwarding (switching) 			
MPLS separates the tasks			
 L3 addresses used for path determination 			
 Labels used for switching 			
 MPLS network consists of 			
 MPLS edge routers and MPLS core routers 			
Edge routers and core routers			
 Exchange routing information about L3 IP networks using classical IP routing protocols (OSPF, IS-IS) 			
 Exchange forwarding information about the actual usage of labels using label distribution protocol (LDP) 			
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Routing component:

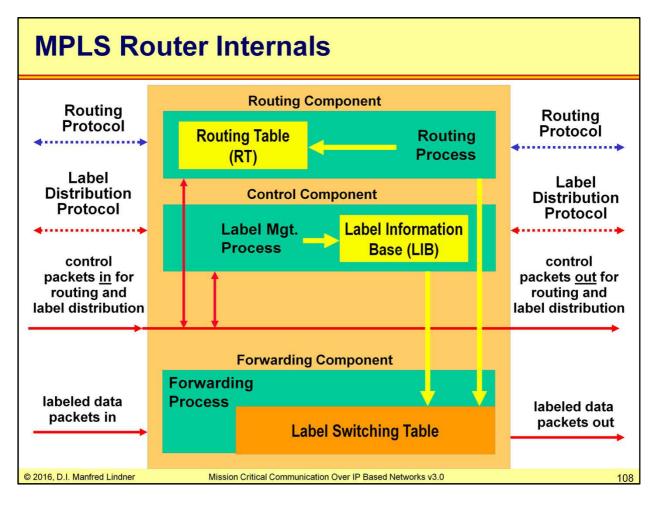
Still accomplishes traditional IP routing creating a classical IP routing table.

Control component:

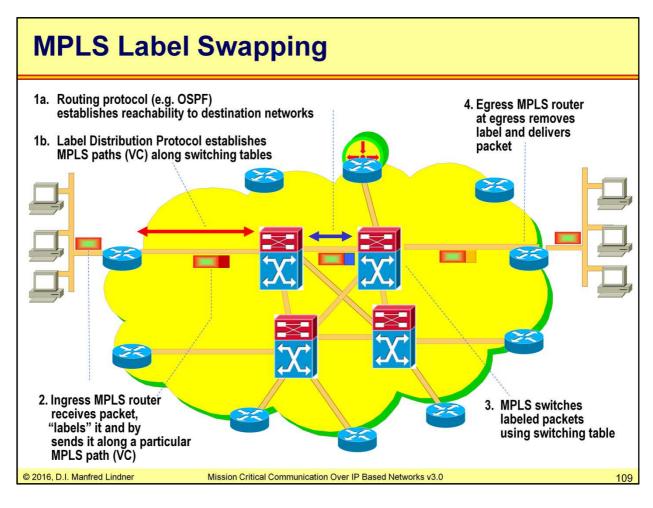
Maintains correct label distribution among a group of label switched routers using LDP (Label Distribution Protocol) for communication among MPLS core routers and between MPLS core routers and MPLS edge routers. Information about labels is stored in the label information base (LIB)

Forwarding component:

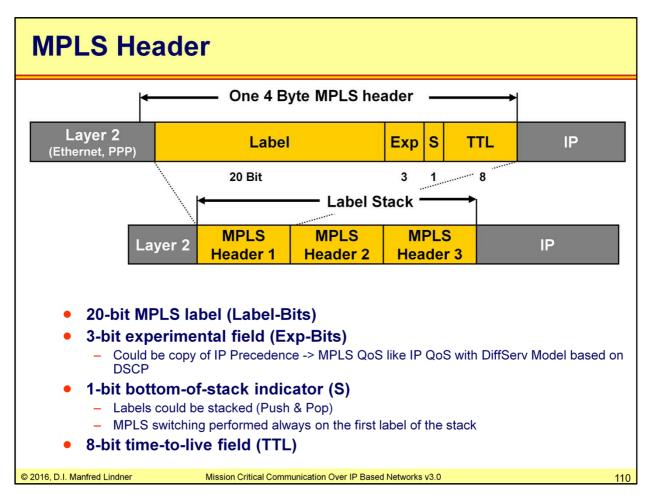
Uses label carried in the packet header together with a label switching table maintained by MPLS Router to perform packet switching/forwarding in a classical VC (virtual circuit) switching style similar to ATM (Asynchronous Transfer Mode). Label swapping is done when a MPLS packet is forwarded by a MPLS router. The difference to ATM is that label switching table is based on the state of the IP routing table whereas an ATM switching table is maintained by explicit connection setup done by a signaling protocol.



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The MPLS Header is made up of four bytes and is located between the L2 header and the L3 header. The existence of an MPLS header is indicated by the layer two type field entry 0x8848.

The MPLS header is made up of a:

20 bit label field used for forwarding,

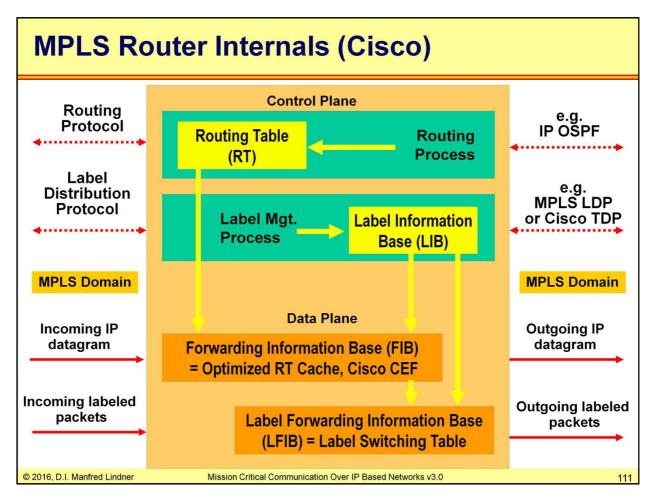
3 Experimental bits typically used to carry IP Precedence (IP TOS) settings,

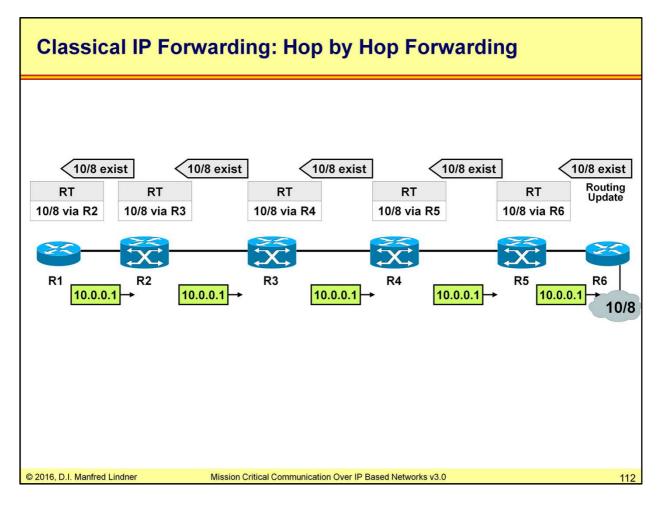
1 bit bottom of stack (0 indicates last label in the stack, 1 indicates there are some more labels on top of the bottom label)

TTL field in which by default the IP TTL value is copied to when a label is inserted.

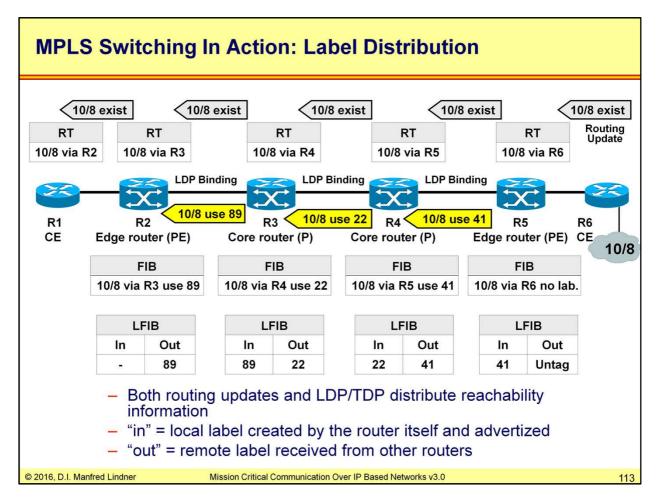
Note: The labels 0 to 15 are reserved. Therefore the lowest usable label number is 16 and the highest possible label is 1,048,575 (which is actually 2^20-1). Only four out of the 16 reserved labels had been defined (RFC 3032), which are: 0 "IPv4 Explicit Null Label", 1 "Router Alert Label", 2 "IPv6 Explicit Null Label", 3 "Implicit Null Label".

Several reasons lead to a label stack. For example, with MPLS VPNs, the top label identifies the egress router while a second label identifies the VPN itself. Thus the egress router can (as soon as the packet arrived) pop the outermost label and forward the packet to the right interface according to the inner label. Another example is MPLS Traffic Engineering (TE), where the outer label points to the TE tunnel endpoint and the inner label to the final destination itself.

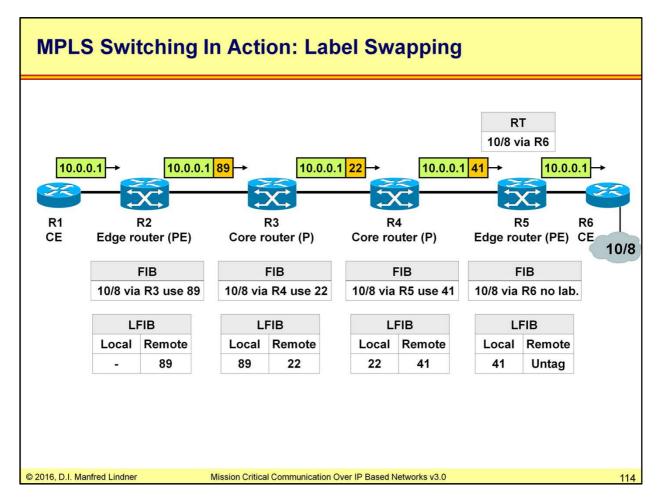




The picture above shows classical IP hop-by-hop routing using signposts established by routing protocols and stored in the corresponding routing table.

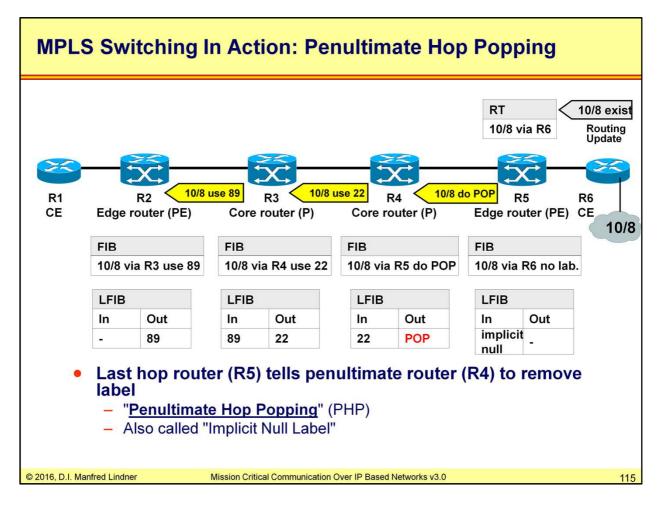


The picture above shows how a label-switched path is established from left to the right. Both routing updates as well as a label distribution protocol (LDP or TDP) distribute reachability information for this destination network.



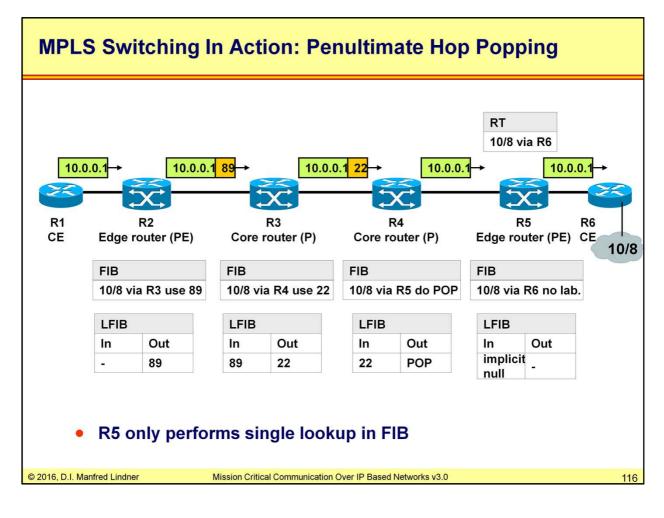
The picture above shows how packets can now be sent using a MPLS header. Label switching is performed on each hop (LSR) inside the provider domain (R2, R3, R4, R5). The LFIB tables are used to perform a fast lookup.

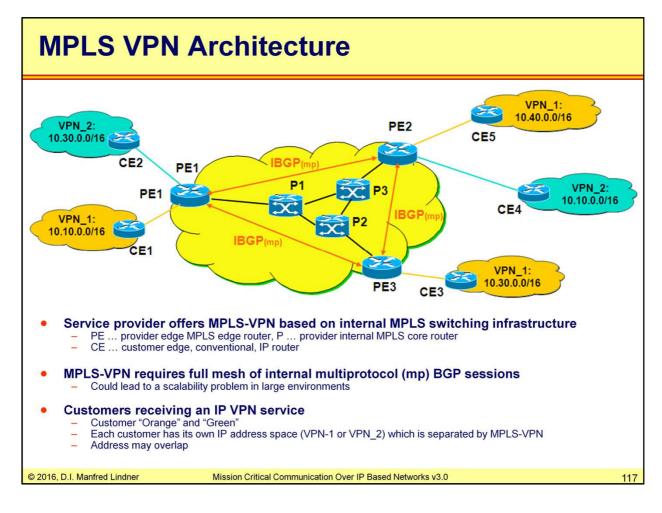
But R5 cannot find any outgoing label in its LFIB. After this unsuccessful lookup, R5 looks into the FIB and determines the next hop. Note that this double lookup would be done for every packet! Therefore it would be reasonable to remove the label even one hop earlier (the penultimate hop, R4) in order to leave R5's LFIB empty.

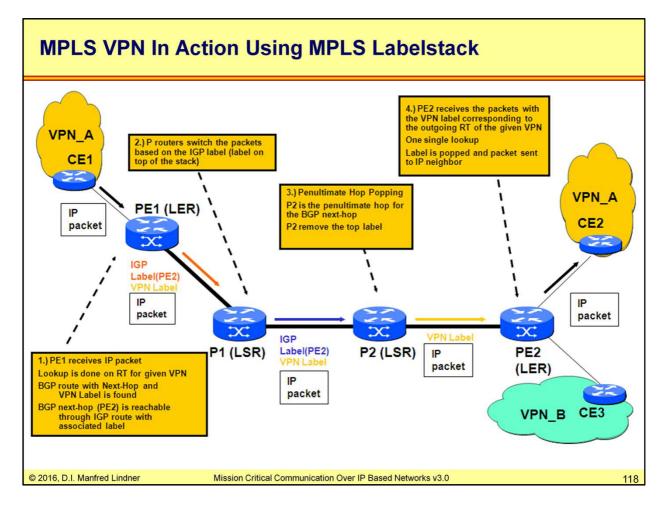


In this scenario "Penultimate Hop Popping" (PHP) is illustrated. Now R5 does not allocate an incoming label for this destination but rather announces to R4 to use an "implicit null" label. It is also said, that R4 should perform the "POP" operation. The label number "3" had been reserved to represent the "do POP" command.

Implicit Null Label and hence POP upstream sent out only for directly connected networks or aggregates of advertising router



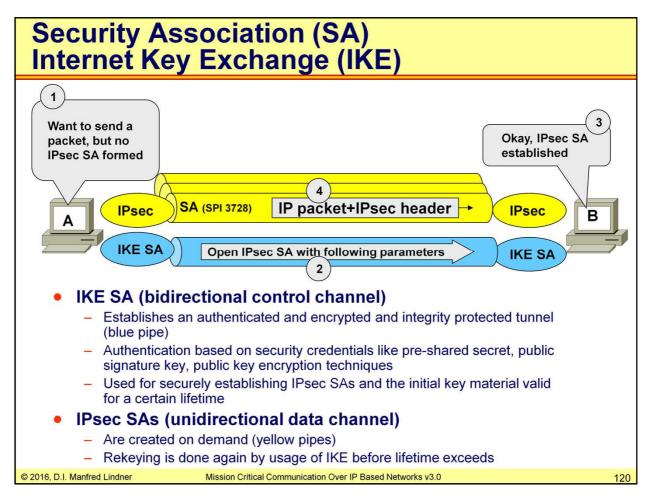




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What is IPsec?

IPsec enables a system to select required security protocols, determine the algorithms to use for the services, and put in place any cryptographic keys required. IPsec protects one path between a pair of hosts, between a pair of security gateways, or between a security gateway and a host.

Elements of IPsec:

1) Security protocols (for traffic security):

Authentication header (AH) defined in RFC 2402 obsoleted by RFC 4302, 4305 since Dec 2005. Encapsulating security payload (ESP) defined in RFC 2406 obsoleted by RFC 4303, 4305 since Dec 2005.

2) Cryptographic Algorithms:

Mandatory implementation requirements for ESP and AH are defined in RFC 4305.

Secret-key algorithms are used so far because of performance reason.

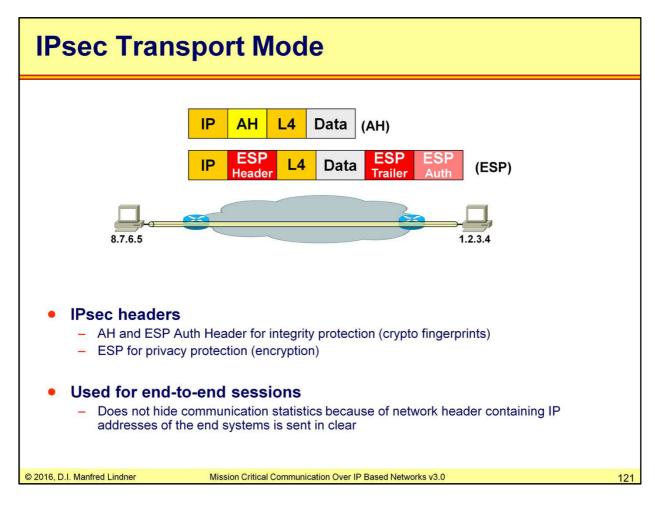
HMAC-SHA1, HMAC-MD5, AES-XCBC-MAC, DES-CBC, 3DES-CBC, AES-CBC, AES-CTR are defined in separate RFC' (see 4305, 2403, 2404, 2405, 2451, 3566, 3602, 3686)

3) Management of security associations (SA) and keys:

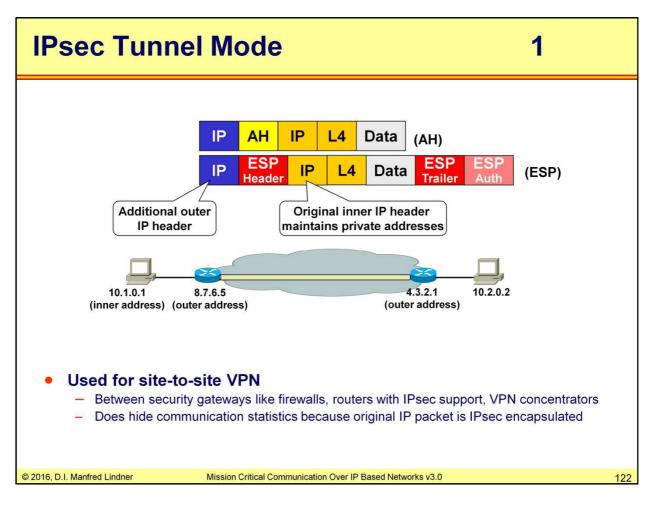
Manual management for static and small environments. Automatic management for scalable environments by ISAKMP (Internet Security Association and Key Management Protocol defined in RFC 2408 obsoleted by RFC 4306 since Dec 2005) and Internet Key Exchange (IKE, defined in RFC 2409 aka IKEv1, obsoleted by RFC 4306 since Dec 2005 -> IKEv2).

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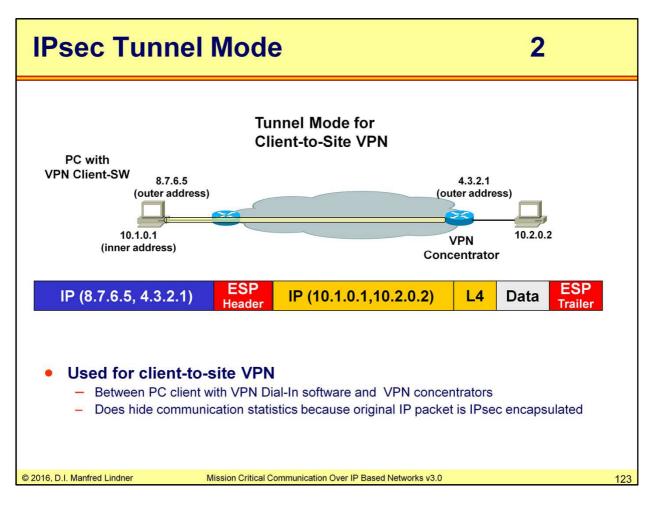
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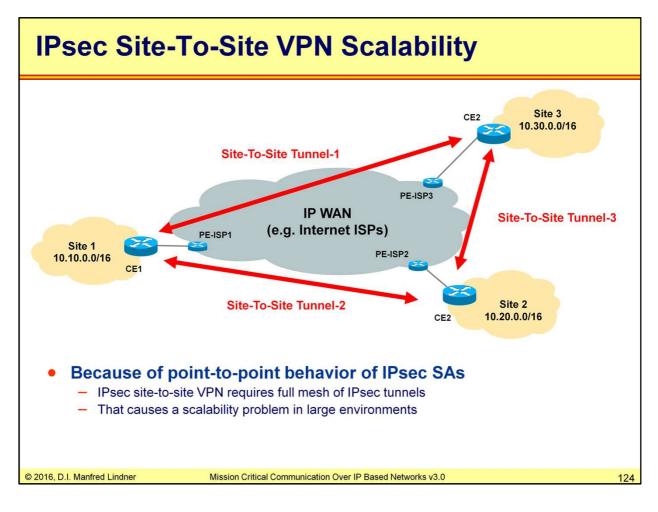
IPsec for site-to-site VPN often uses pre-shared secrets for authentication of IKE peers. Why? Usage of certificates means maintaining a kind of PKI (Public Key Infrastructure) and at least a private CA (Certification Authority) server is needed. On the other side VPN router/concentrator can physically protected in the data center

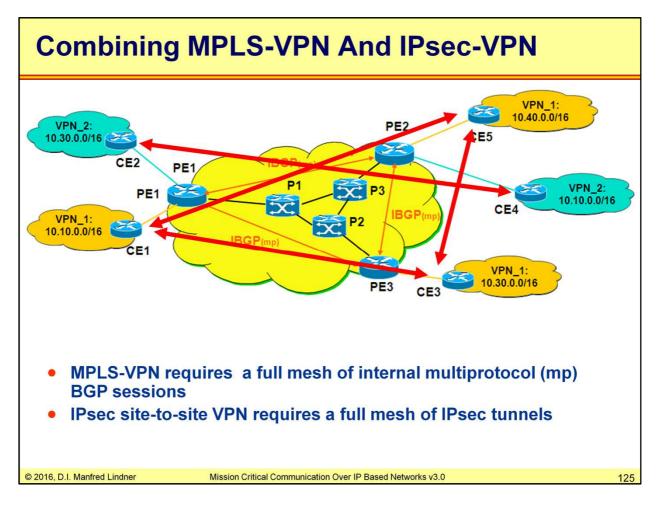
With mobile PC with IPsec for client-to-cite VPN there is a different situation. Mobile PCs calling from insecure places. Preshared secret may be compromised hence configuration and maintenance overhead if number of clients is high. Therefore a combination of IPsec, well-known RAS authentication techniques (PPP with EAP, RFC 3748) and X-AUTH is used.

Client dials-in, authenticates itself at a authentication server (VPN concentrator) using a group-key (could be a preshared secret) and a first secure tunnel is established. Now the VPN concentrator using X-AUTH asks the user of the PC for the credentials (e.g. username/password). If ok, then PC is allowed to come in. The necessary IPsec configuration is pushed from the VPN concentrator to the client to establish the final secure tunnel. Also the internal IP address of the mobile-PCs is assigned by the VPN concentrator and maybe other security settings like host-based firewall setting, OS healthy checks or disabling splitted tunneling are forced by the VPN concentrator.

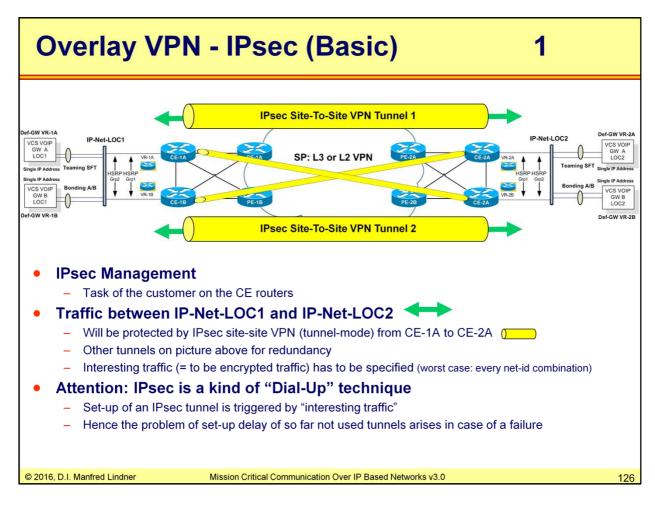
X-AUTH exchange as an add-on to IKEv1. X-AUTH exchange is an inherent optional part of IKEv2.

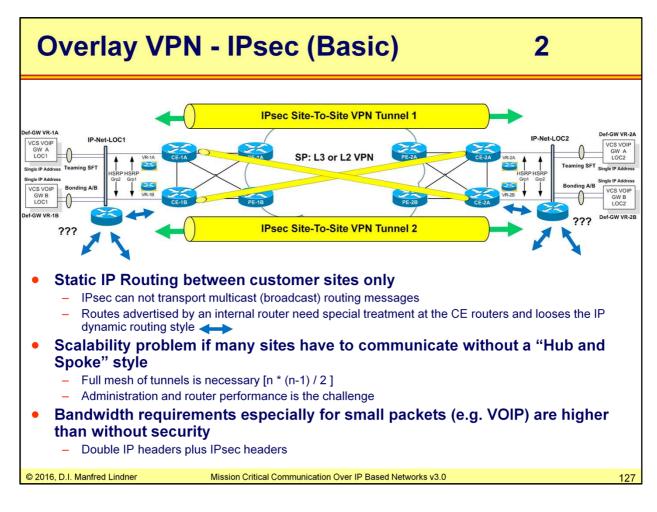
NAT (Network Address Translation) or N(P)AT (NAT with port address translation) causes problems in case of IPsec AH or ESP. You need a NAT traversal technique in such a case. NAT-T encapsulates IPsec stuff into a UDP or TCP packet.

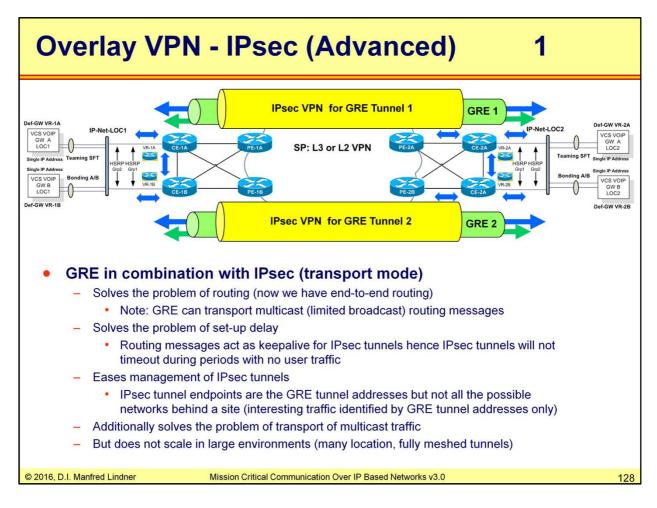


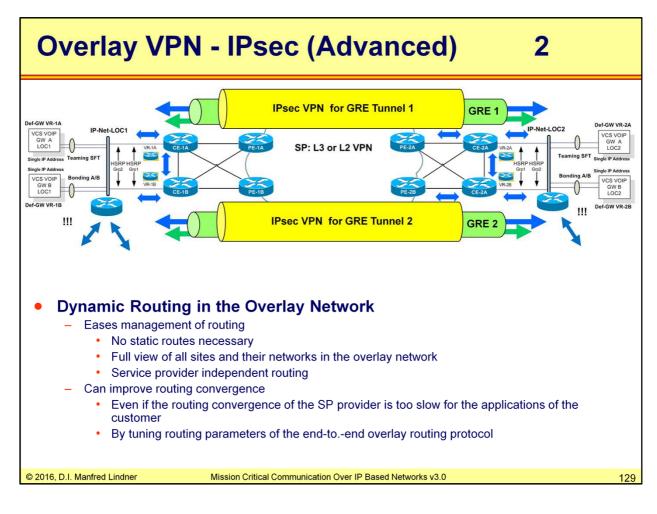


Combining MPLS VPN (Separation) and IPsec VPN (Encryption/Integrity)







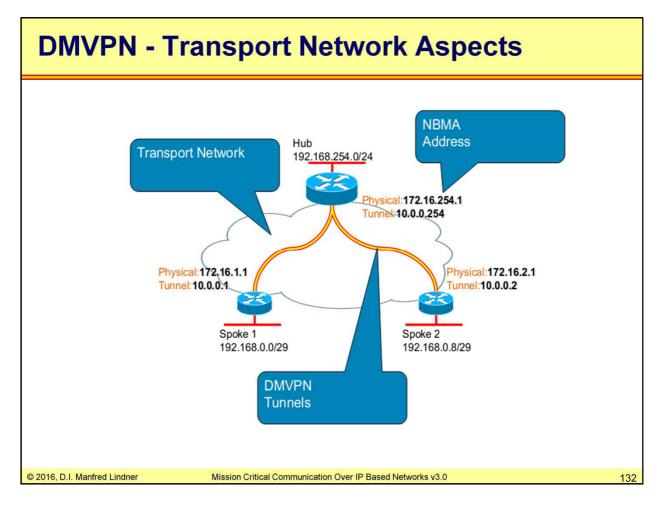


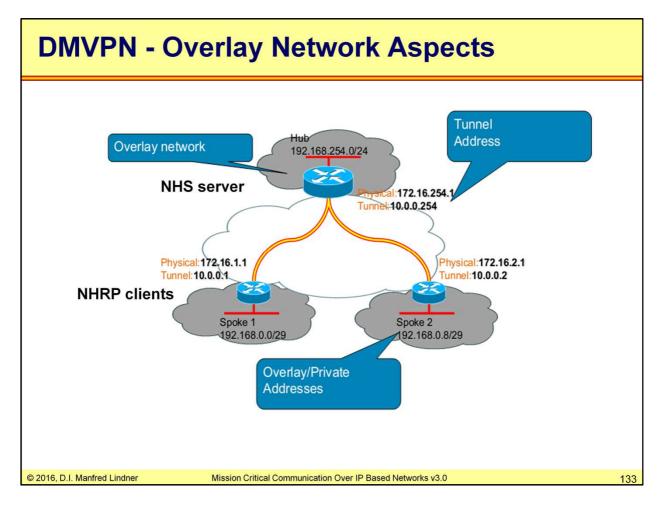
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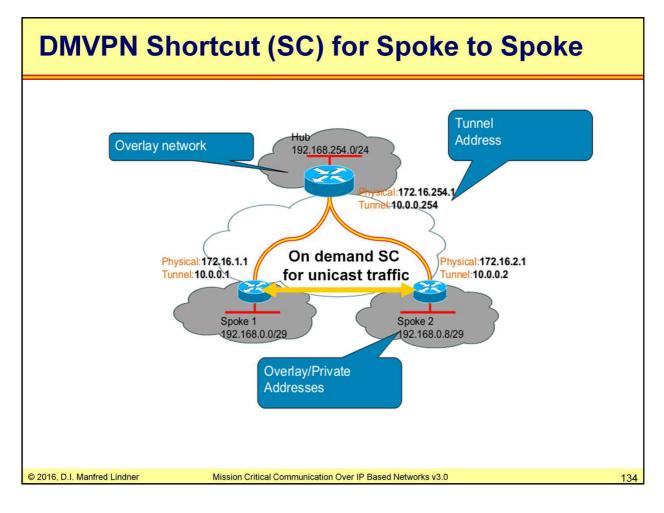
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Overlay VPN - DMVPN
 Basic IPsec or IPsec+GRE Sufficient if you have to cover a small number of sites with these techniques Maybe acceptable for larger number of sites if applications on sites requires a "Hub and Spoke" communication style Not scalable for a large number of sites or "Any To Any" communication style
 DMVPN (Dynamic Multipoint VPN) Serves large scale IPsec VPNs with overlay IP routing between sites Combines IPsec protection with GRE and NHRP/NHS (Next Hop Resolution Protocol / Next Hop Server); NHS located at the hub site IPsec tunnels between hub and spokes are activated automatically IPsec tunnels between spokes are activated on demand and ceases after interesting unicast traffic has gone (DMVPN Phase 2) Multicast replication is possible on hub site only Configuration for multi-homed sites, redundant hubs and redundant service providers could be tricky and complex Two independent convergence processes Overlay routing and NHRP
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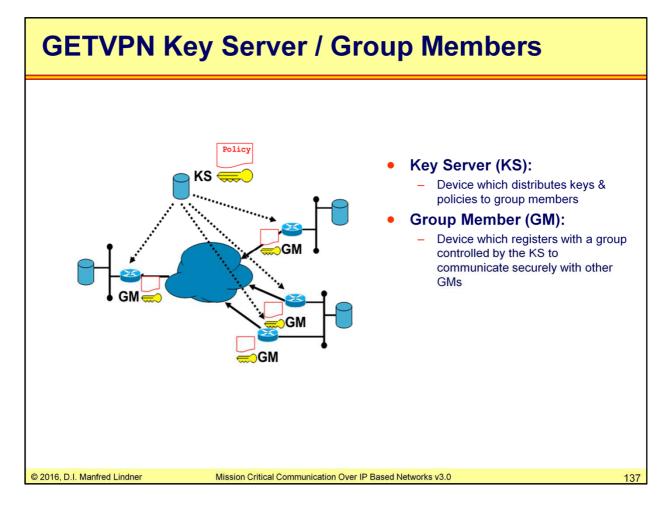


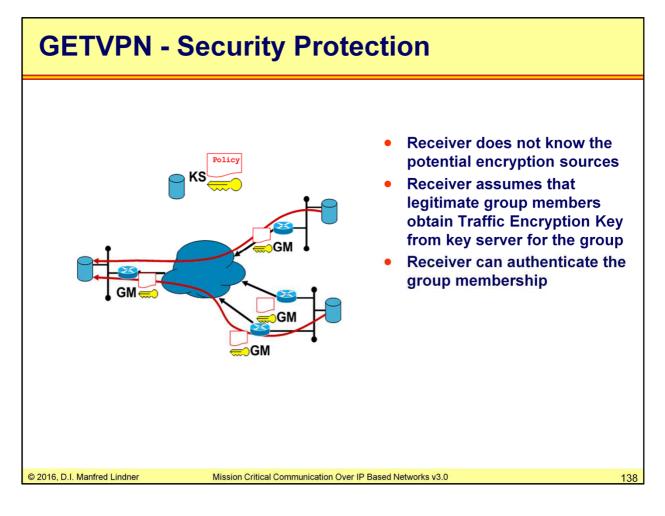
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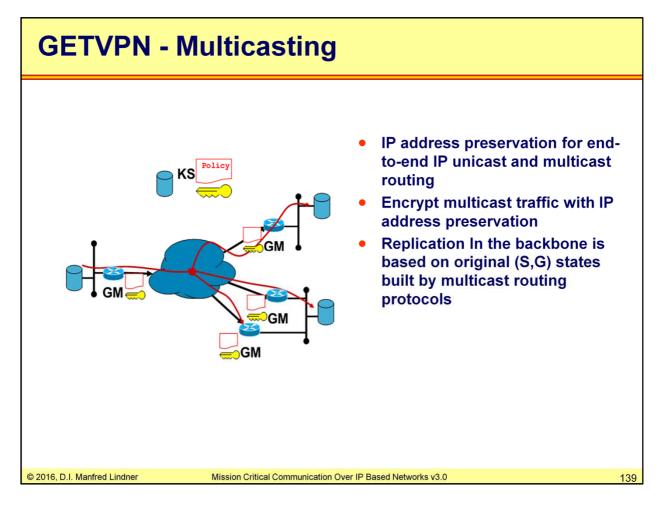
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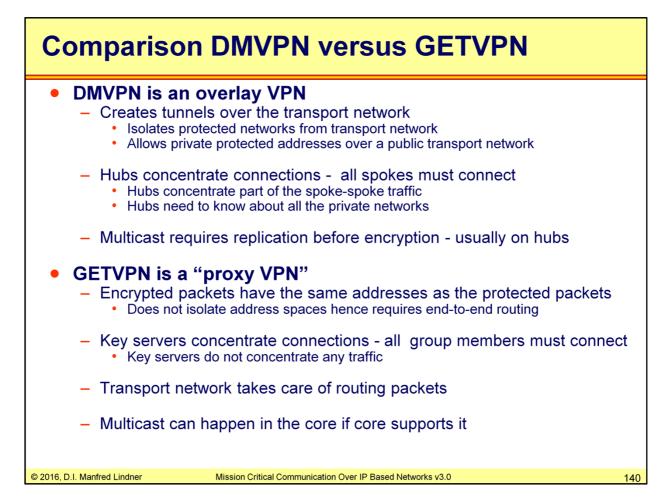
Proxy VPN - GETVPN
 IPsec technology Established security associations between two partners only IKE tunnel for authentication and rekeying IPsec tunnel for user data protection
 GETVPN (Group Encrypted Transport VPN) Breaks the basic IPsec concept of point-to-point security associations There are no security associations anymore A GETVPN endpoint just take the group key to encrypt the messages in tunnel mode and passes it on
 All partners are getting their key material from a group key server which is used for rekeying too
 There is no IP address and routing separation between sites and the backbone All IP addresses of sites will be seen in packets from the backbone All encrypted messages are proceeded by the original source and destination addresses hence communication statistics will be seen in the backbone
 Multicasting is possible If backbone supports multicast routing and multicast forwarding
 Group key servers located in the backbone need to be well protected
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The slide shows how a single multicast message is passed on along the multicast distribution tree in the backbone network. Of course in such a case an end-to-end multicast routing environments is necessary (meaning IGMP multicast group membership protocol and PIM-SM multicast routing protocol).

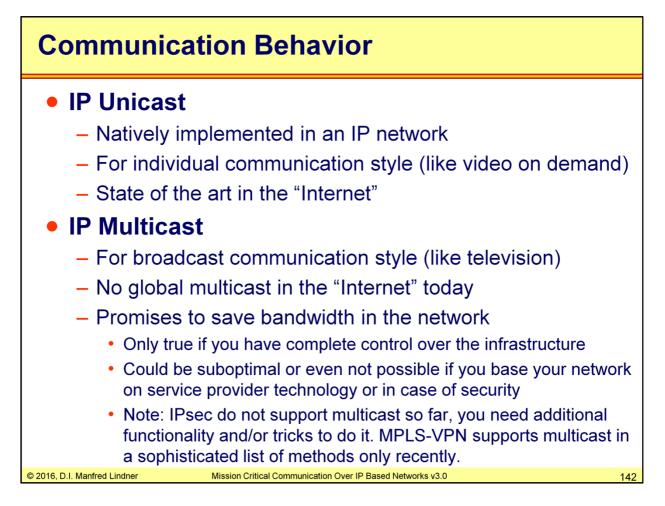


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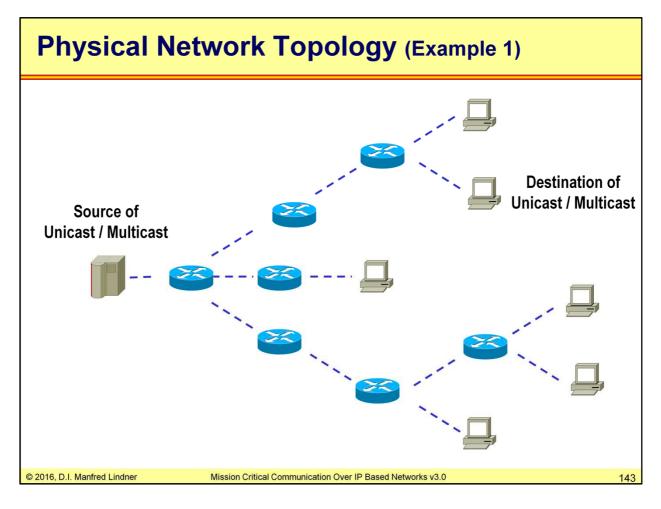
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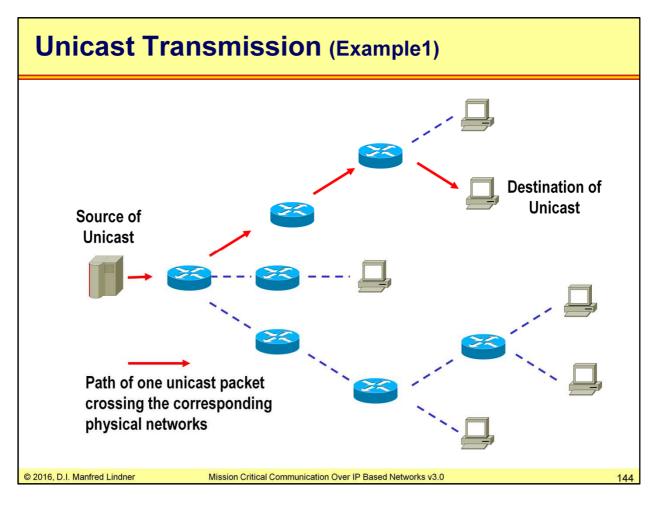
Unicast is the usual style for individual communication between two processes from one source to one destination. It does not matter if communication is unidirectional or bidirectional. It is natively implemented in any IP network by unicast destination-based IP routing. Because unicast is per se a point-to-point relationship any protocol providing reliability by retransmissions of lost messages (like TCP) and any security protocol acting on point-to-point security relationship (like IPsec) providing privacy and integrity can be applied on top of it.

Multicast is an optional style for unidirectional communication from one sender process to a group of receiver processes. The goal is to save communication bandwidth in the network by sending out a message for the group just once and the network will duplicate the message at appropriate points in the network in order that every multicast group member gets exactly one copy of the original message. The decision for forwarding a multicast message by an IP multicast enabled router is based on the source address (from where did the message come) and the knowledge about where group members addressed by the multicast group address are located in the network. Compared to IP unicast routing it is "routing on the head". Multicast routing tries to find the best interface to the source! On the other hand, traditional unicast routing wants to determine the best interface to the destination.

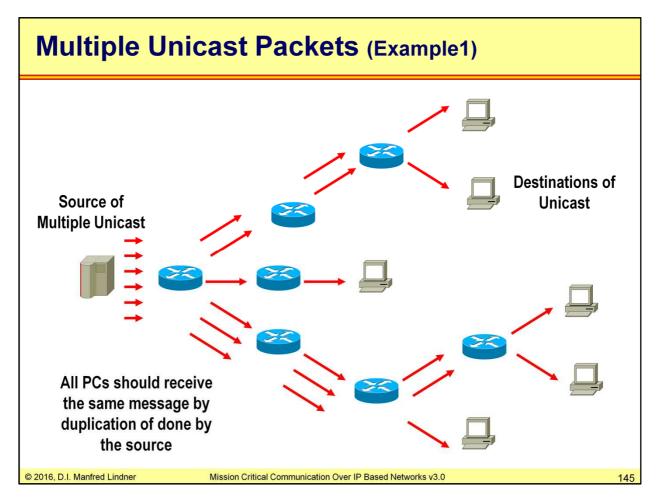
Because of the multicast style putting a reliable protocol like TCP on top of it is not possible. So IP multicast can provide a best-effort service only. Adding privacy and integrity by a security protocol is only possible if the security protocol uses group encryption keys (like in GETVPN).



We want to discuss the base principles of unicast and multicast using the above physical network topology. The dashed blue lines are the physical network links (e.g. Ethernet or serial).

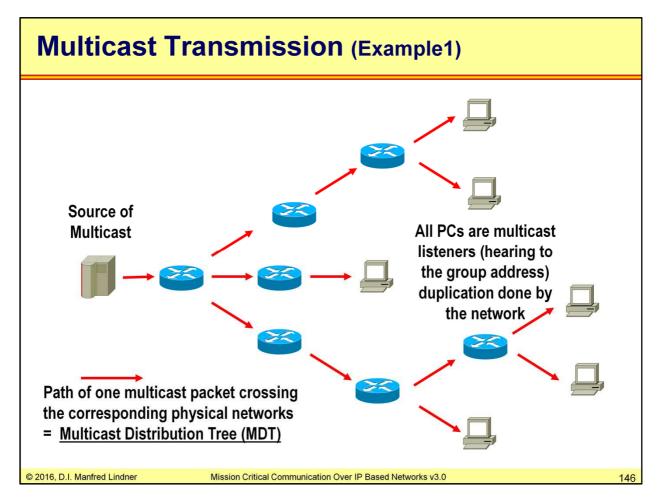


The picture shows how an IP datagram address to a unicast destination address is forwarded hopby-hop based on the unicast IP routing table.

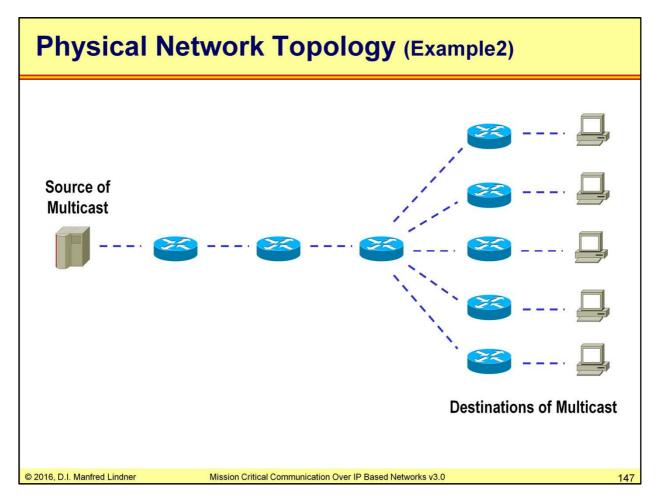


The picture shows how we can emulate a kind of group addressing by using multiple unicast IP datagram generated by the source station and addressed to multiple unicast destination address. In our example all PCs on the right should receive the same information. As you can see parts of the physical network will get more traffic because of this duplication done by the source.

The closest interface to the source is necessary in order to check whether a multicast packet arrived indeed on the upstream interface - an interface which belongs to the MDT. This check is called "Reverse Path Forwarding" (RPF). Using RPF, each router that receives a multicast packet checks (using its routing table) whether this receiving interface is actually the closest to the source. If this is the case then this interface is an upstream interface and the packet can be forwarded (flooded) through all other interfaces. Cisco routers perform a RPF check every 5 seconds by default.



If multicast transport is enabled in the network a single IP datagram generated by the source station and addressed to the multicast group address will just follow the multicast distribution tree (MDT) from the source to all multicast listeners. The duplication is done by the multicast routers whenever a fork in the occurs at that tree. The red arrows in the picture represent the multicast distribution tree. Multicast routing techniques will establish a MDT based on the knowledge first where receivers for a given multicast group address are located (the domain of local IGMP – Internet Group Management Protocol) and second if the multicast IP datagram arrives on an interface which is on the shortest path from the source to the corresponding router (domain of PIM – Protocol Independent Multicast routing protocols).

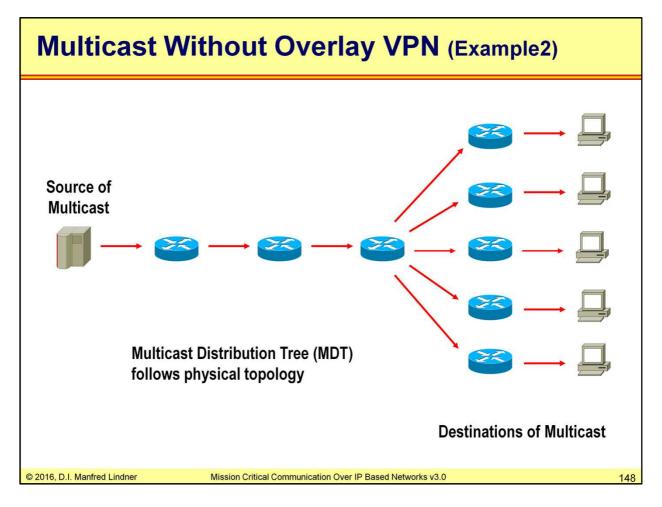


For the following discussions we want to use another physical network topology together with an overlay network. Reason for that overlay maybe a network unable to transport multicast or security.

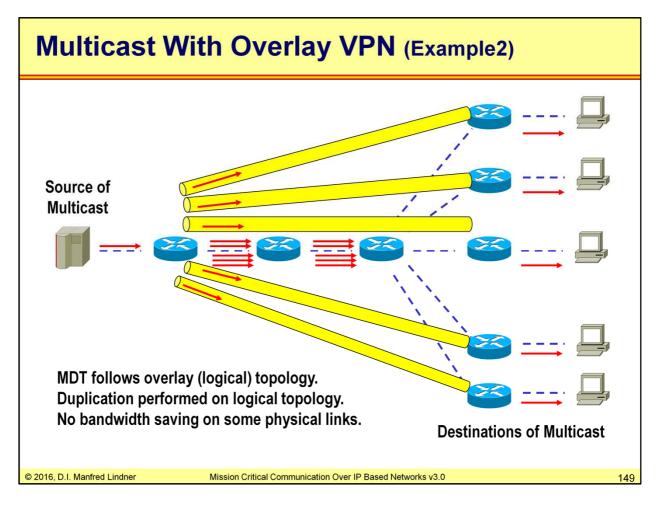
Adding privacy and integrity for multicast by means of a security protocol is only possible if the security protocol uses either group encryption keys (like in GETVPN) or multicast traffic is forced into GRE-IPsec tunnel as described already in the routing sections of IPsec VPN technologies

On the other side, if you create - caused by such requirements - an overlay VPN on your own like usage of DMVPN or GRE-IPsec, IP multicast may be supported. But even if it is supported in most cases it will be suboptimal regarding saving of bandwidth, because an overlay has no knowledge of the underlying network topology. For example imagine a meshed network offering potential for bandwidth saving by multicast technology. If you but a star-shaped overlay topology on top of it (that is what DMVPN is doing) it is clear that has limited benefit. It will save maybe some bandwidth in the overlay tunnels but that does not mean that is an advantage in the underlay network. Remember that tunnels leaving from a single end-point (e.g. router as GRE-IPsec VPN overlay entry point) will cause duplication of multicast on every tunnel even if this router is connected just with one physical link to the IP WAN.

The following slides show first the difference between MDT (Multicast Distribution Tree) following the physical topology and MDT following the logical topology caused by overlay and second problems involved (duplication on just a single physical link) when applying multicast on top of an overlay VPN.



This pictures shows a MDT (Multicast Distribution Tree) following the physical topology and appropriate duplication at the fork router two hops apart from the multicast listeners.



This pictures shows a MDT (Multicast Distribution Tree) following the logical (overlay) topology. Duplication is done at the logical fork router (entry point into overlay tunnels). This causes in the physical network a duplication of a single multicast datagram and hence wastes bandwidth on the links between first and third router (seen from the source).

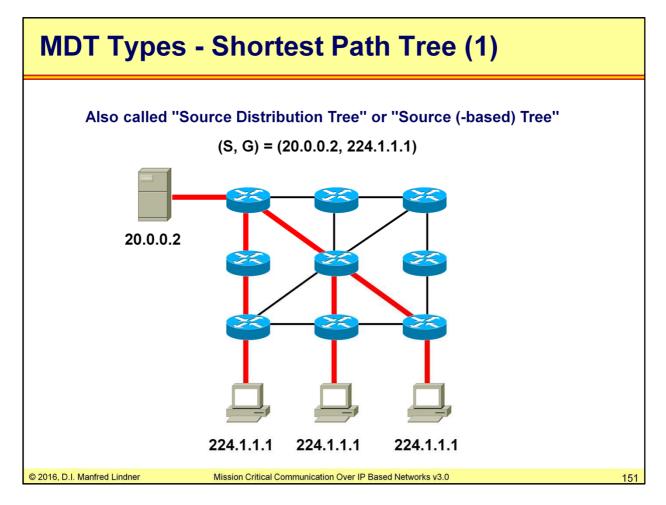
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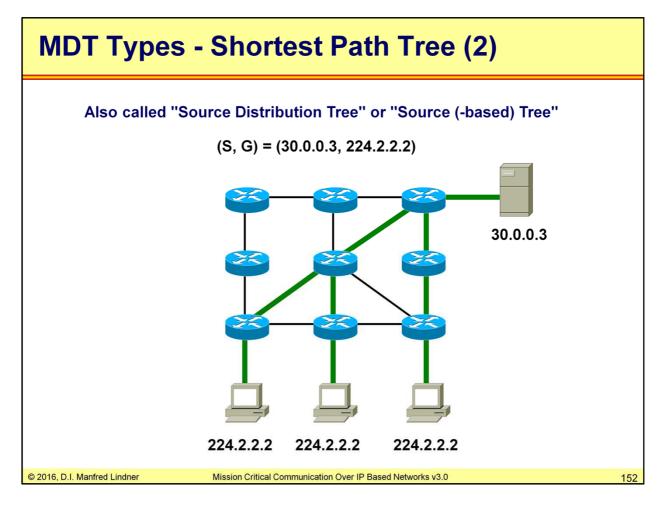
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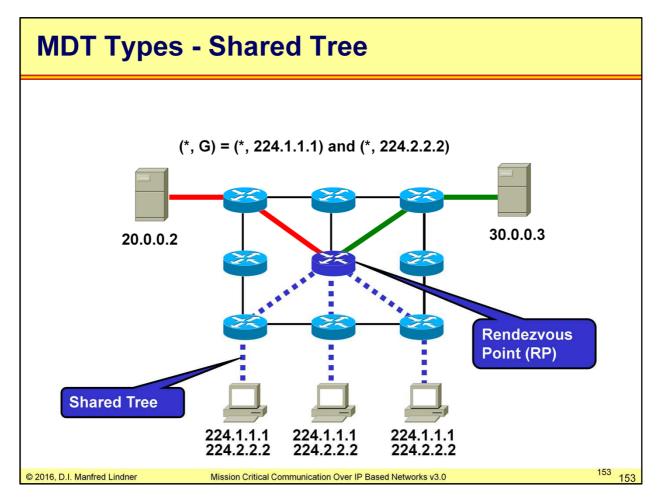


"Shortest Path Trees" (SPT) are also called "Source Distribution Trees" or "Source Trees". The basic idea is that a separate tree is created for each single source. The picture above shows only one source based tree. This distribution method consumes much memory in the involved routers—of order $O(S \cdot G)$ —but it provides optimal paths from source to all receivers and minimizes delay.

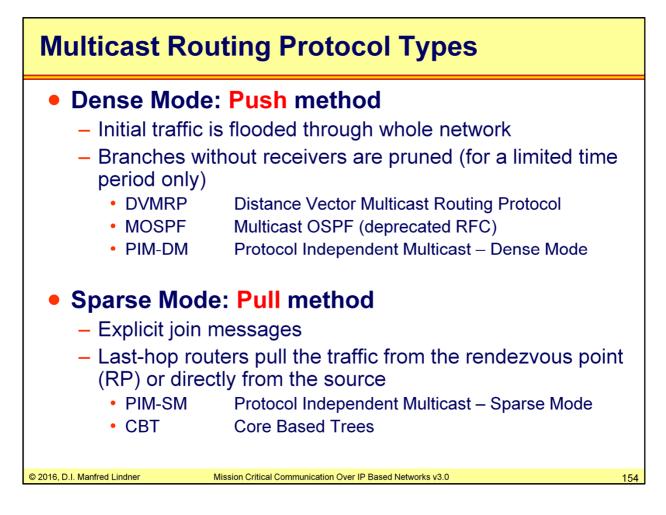


This picture shows another SPT. Each SPT is identified by a pair of addresses, that is, the unicast source address S and the multicast group address G, thus (S, G). The SPT principle is the most implemented method, found in DVMRP, PIM-DM, and other protocols. Note that each router must maintain state information for each (S, G) combination, including timers, interface lists, etc (suppose there are hundreds of sources and hundreds of groups...)

The main point here is that a separate SPT is built for every source "S" sending to group "G". Traffic is forwarded via the shortest path from the Source!



Shared trees utilize a so-called "Rendezvous Point" (RP), which distributes multicast traffic to its attached receivers. The idea is similar as the supermarket principle: "Customers should not have to visit every manufacturer but rather buy everything at the shop around the corner." In this sense, the RP acts as supermarket and offers multicast traffic from several sources. Typically, each RP is a leaf of a SPT, which is rooted at a source. That is, the shared tree principle is mostly used in combination with a SPT. Shared trees consume memory of order O(G) but might result in sub-optimal paths from the source to all receivers. Furthermore they may introduce extra delay. Thus, only a clever combination of both SPT and shared trees might be most efficient.

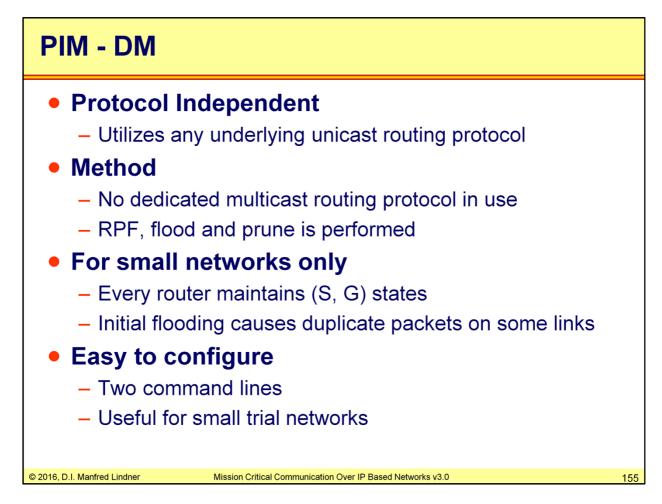


Multicast routing protocols are either dense mode or sparse mode.

The dense mode principle uses a "push" method to create the distribution tree. Multicast packets are flooded throughout the network and each router creates its outgoing interface list (OIL) using the RPF check and "prune" messages to cut off unnecessary branches of the tree. That is, after the initial flood, branches without receivers are pruned. But after a timeout, traffic is flooded throughout the network again. Typically every 3 minutes a flood and prune occurs.

The sparse mode principle uses the opposite method in that routers which want to be part of the tree must send explicit "join" messages. Thus, the sparse mode supports a "pull" method for tree establishment. Note: Branches without receivers never get any multicast traffic!

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The Protocol Independent Multicast - Dense Mode (PIM-DM) supports any underlying unicast routing protocols, including static, RIP, IGRP, EIGRP, IS-IS, BGP, and OSPF.

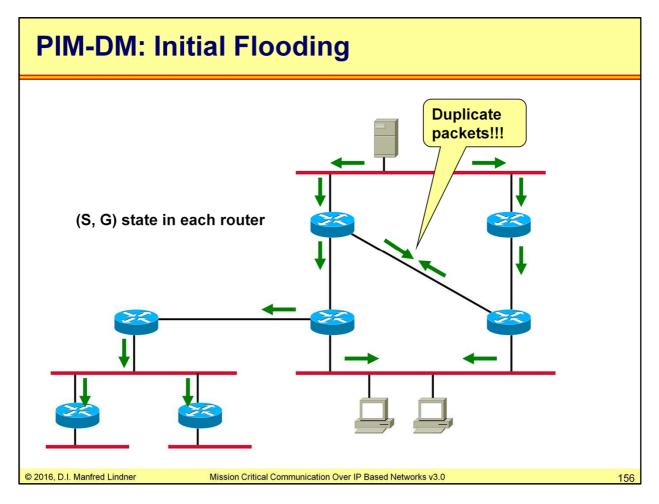
When a PIM-DM router receives multicast traffic via its (upstream) RPF interface it forwards the multicast traffic to all of its PIM-DM neighbors.

But then, the next-hop routers might receive packets also on non-RPF interfaces! Clearly this silly method results in duplicate packets on some links. These non-RPF flows are normal for the initial flooding of data and will be corrected by a PIM DM pruning mechanism.

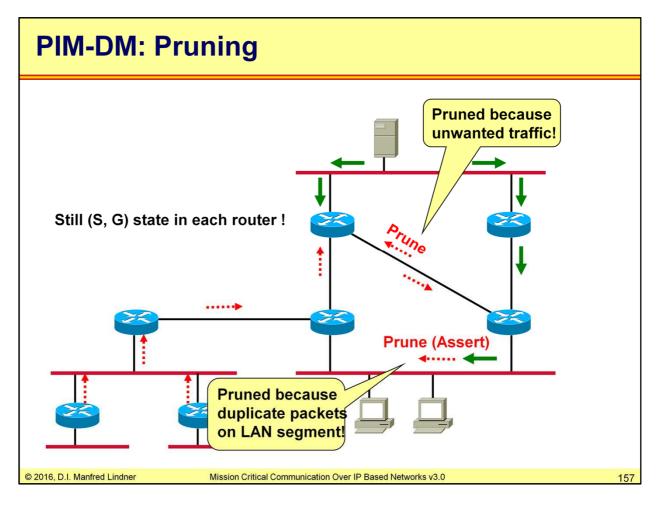
Special "assert" messages are used to prune another routers interface. Flood and prune is performed every 3 minutes. If the metric is equal, then the highest IP address on an interface wins.

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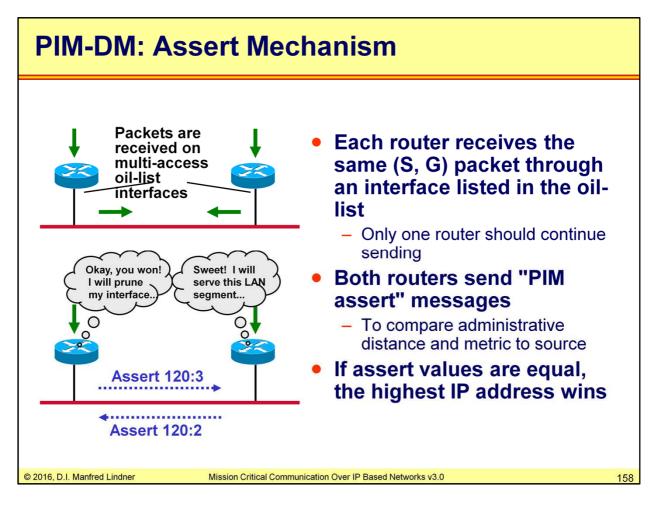
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The example above shows some routers which receive packets on non-RPF interfaces. The routers will discard these packets because only packets received through the upstream interface are considered as good packets. Duplicate packets can occur on some links during the initial flooding of data and will be removed by a PIM DM pruning mechanism, following in the next step. Also note, that each router must maintain a (S, G) state.



Pruning occurs after the initial flooding (which is done every 3 minutes by default) and serves for two purposes: First, branches can be cut off when there are no further receivers downstream; secondly, a router can use a so-called assert message to stop another router from sending packets to its non-upstream (i. e. non-RPF-) interface. The latter method forces the other router to prune its own interface. Again: The prune state lasts three minutes by default. Then a new flooding occurs over all links! Note, that each router must still maintain the (S, G) state.



The PIM assert mechanism is used to eliminate duplicate flows on the same multi-access segment. The assert mechanism is only performed when duplicate packets appear on this link.

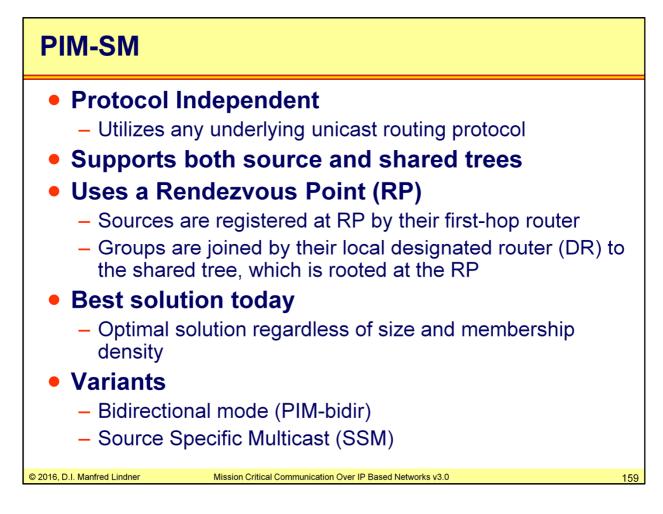
When a router receives a (S, G) packet via a multi-access interface which is listed in the (S, G) oillist, then it will send an assert message, telling the other router a so-called assert value.

The assert value contains both the administrative distance of this router and the metric toward the source. The administrative distance is evidentially the high-order part of this assert value. Obviously the other router sends also an assert message. Now both routers compare these values to determine who has the best path (i. e. lowest value) to the source. If both values are the same, the highest IP address is used as tiebreaker. Losing routers prune their interface, whereas the winning router continues to forward multicast traffic onto the LAN segment.

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The Protocol Independent Multicast – Sparse Mode (PIM-SM) has been defined in RFC 2362 and is the most useful multicast protocol today. PIM-SM relies on a explicit pull concept. Traffic is only forwarded to receivers that ask for it (i. e. send a join message).

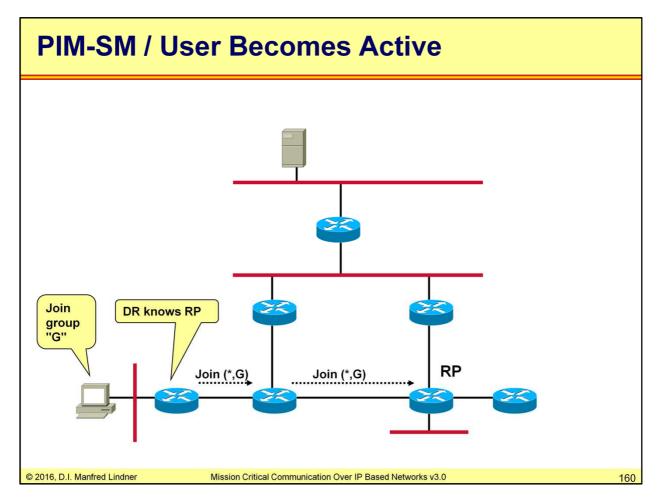
PIM-SM utilizes a Rendezvous Point (RP) which roots a shared tree to the groups. The groups are joined by their local designated router (DR) to this shared tree. Basically, PIM SM uses shared distribution trees, but it may also switch to the source rooted distribution tree.

Sources are registered to RPs by so called register packets, which are created by the first hop routers, closest to the source. A single copy of the multicast packet is sent through the RP to the registered receivers. Group members are joined to the shared tree by their local designated router. A shared tree that is built this way is always rooted at the RP.

By the way: PIM-SM is the only solution recommended by Cisco.

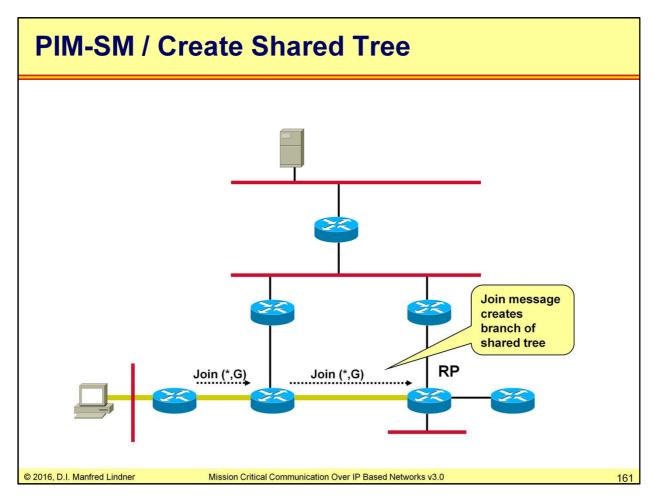
The bidirectional PIM mode (PIM-bidir) had been designed for many-to-many applications such as needed for conferencing and whiteboarding purposes.

The Source Specific Multicast (SSM) is a variant of PIM-SM that only builds source specific shortest path trees. This solution does not need an active RP and uses the source-specific group address range 232/8.

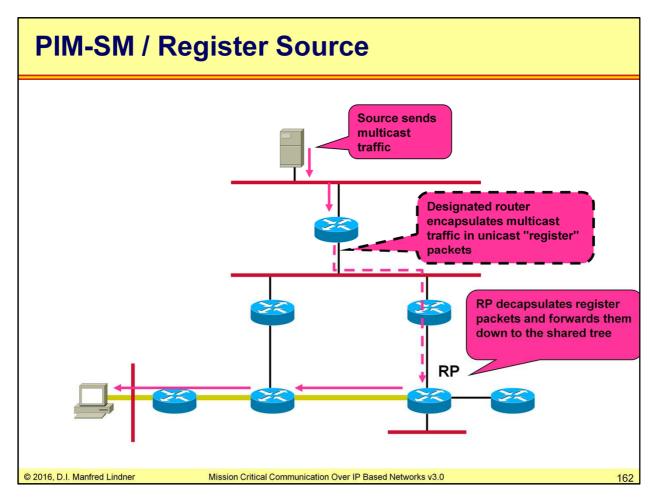


User joins group: The picture above shows how a receiver tells its designated router (DR) that he becomes active and wants to listen to group G. This is done using IGMP on the local LAN segment.

The DR sends a Join (*, G) to the RP. Obviously the DR must know the IP address of the RP. Obviously the DR does not need to know the IP address of the source. Obviously the receiver should at least know what he wants to listen to.

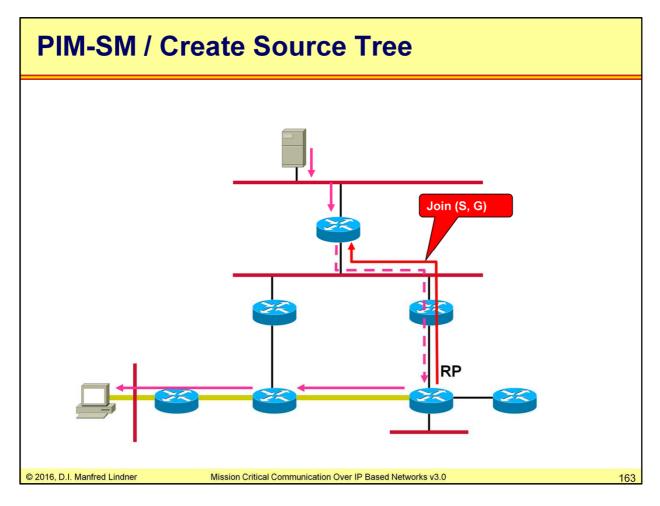


Shared tree to RP: This (*, G) join message is forwarded hop-by-hop toward the RP and hereby a branch of the shared tree is established. Now multicast traffic for group G may flow down the shared tree to the receiver.

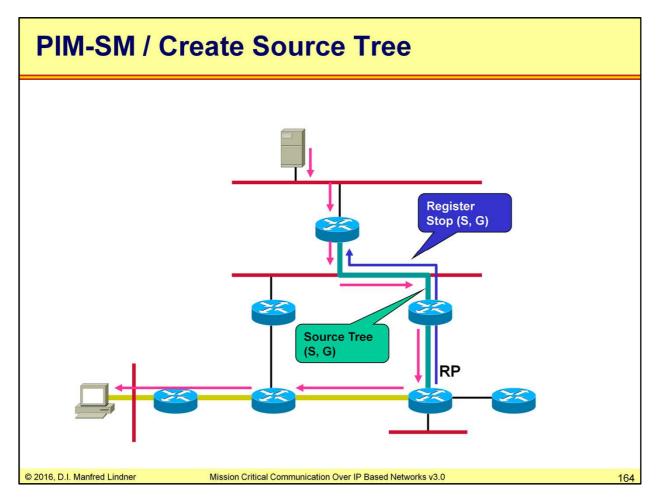


DR registers at RP: The source (for G) becomes active and sends multicast packets, which are encapsulated by the first router (DR) into unicast packets. These "register" packets are sent to the RP. Obviously this DR must also know the IP address of the RP.

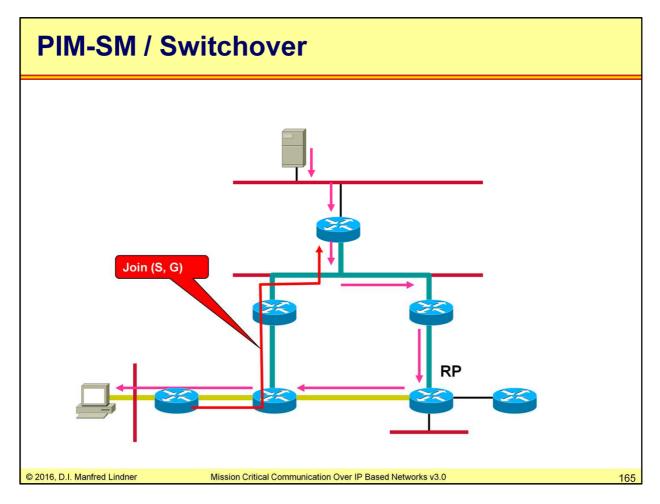
The RP decapsulates this packets and forwards the multicast packets (which had been carried inside the register packets) downstream to the group G.



RP joins SPT: Now the RP creates a shortest-path tree (SPT) by sending an (S, G) join toward the source. Now (S, G) states are created in all routers along this new SPT path. Note: Also the RP must maintain a (S, G) state.

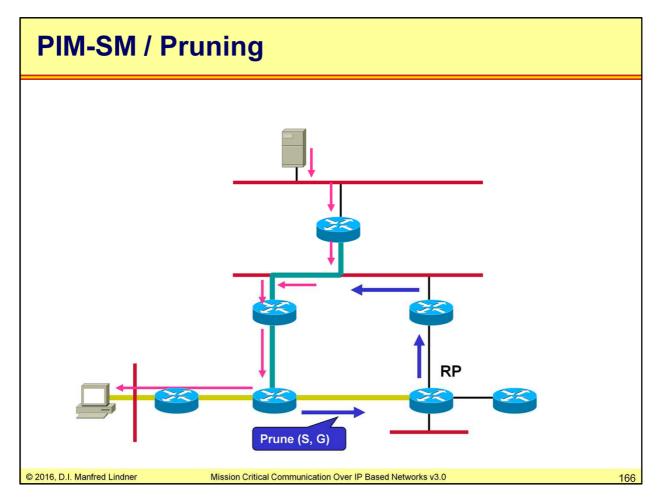


RP stops registering: As soon as native multicast packets arrive at the RP (over the newly established SPT) the RP sends a "Register Stop (S, G)" message to the first-hop router, in order to stop the sending of unnecessary register packets.



Shortcut: PIM-SM is able to switchover to the shortest connection to the source. That is, last-hop routers (i.e. routers with directly connected members) can switch to the Shortest-Path Tree and bypass the RP if the traffic rate is above a configured threshold called the "SPT-Threshold".

Note: The default value of the SPT-Threshold in Cisco routers is zero. Therefore the default behavior for Cisco PIM-SM leaf routers is to immediately join the SPT to the source as soon as the first packet arrives via the (*,G) shared tree.



Disconnect from RP: Now, special (S, G) RP-bit prune messages are sent up the shared tree to prune only the (S, G) traffic from this shared tree. This prune is important to avoid duplicate packets.

RP may disconnect from source DR: When the (S, G) prune (with RP-bit set) arrives at the RP the RP sends (S, G) prune messages back toward the source to stop the unnecessary (S, G) traffic. Note: Of course the RP may only do this if the RP has received an (S, G) RP-bit prune via all branches, i. e. no receiver on the shared tree wants to receive the (S, G) traffic from the RP anymore.

Now we learned:

PIM-SM can also create SPT (S, G) trees but in a much more economical way than PIM-DM (fewer forwarding states). PIM-SM is efficient, even for large scale multicast domains. PIM-SM can be efficiently used for both sparse and dense distribution of multicast receivers. There is no need to flood multicast traffic at any time. On the other hand a RP is needed at least for the initial setup of a MDT.

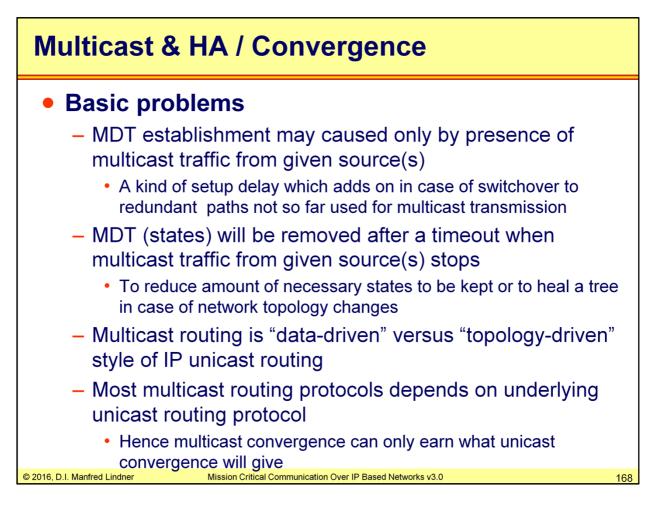
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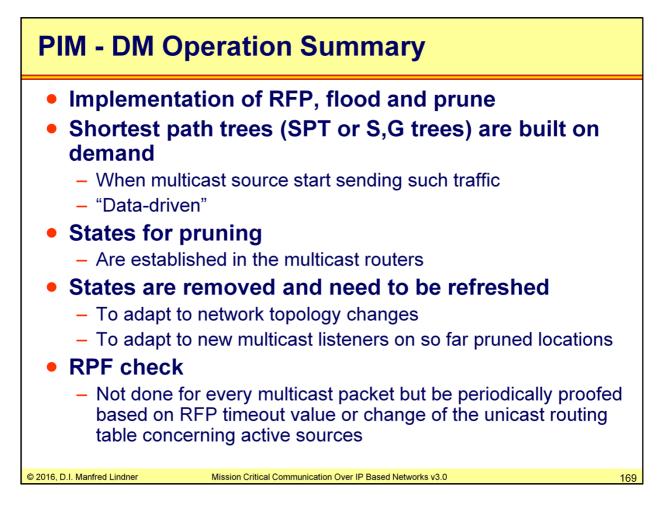


High availability based on redundancy of components / physical paths together with automatic switchover (rerouting techniques) needs more careful investigations compared to HA for unicast communication. Depending on the particular multicast routing technique used there are three basic problems.

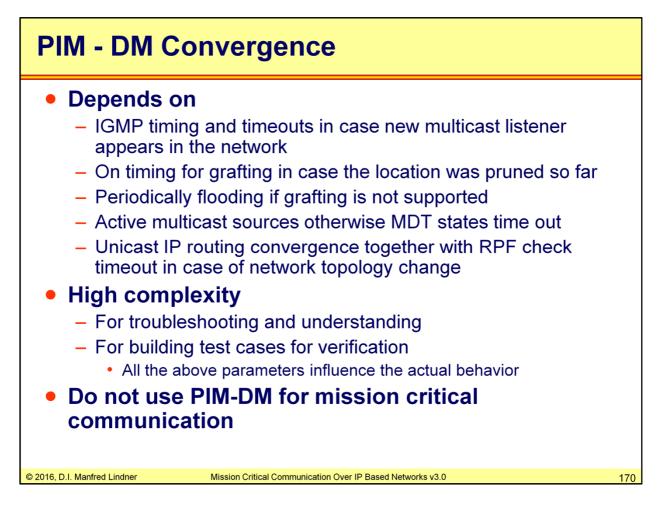
First problem: Multicast distribution trees (MDT) are established when multicast traffic from a given source appears in the network for the first time. So we have a kind of setup delay which may not be tolerable for HA.

Second problem: If a multicast traffic stops then after a timeout the states representing the multicast distribution tree in the network are removed. So verifying that a multicast distribution tree is available is not just as easy as with unicast IP routing. Unicast IP routing tables are established concerning reachability in the network ("topology-driven") but need no unicast traffic in order to be erected. Multicast distribution trees are typically "data-driven" to express that multicast data traffic is necessary for establishing of "multicast IP routing table". The reason for that: Source IP address of multicast traffic may change over time (e.g. if several sources at different places contributes multicast data in a conference style for the same group address). In principle a multicast distribution tree is a shortest path tree from the source to all known multicast receivers. If you have many sources then there are many such shortest path trees spanned over the network. In a huge network to calculate that for all possible source locations does not scale. Hence it is data-driven and not topology-driven.

Third problem: Most multicast routing depends on the availability of traditional unicast IP routing in order to verify the shortest path towards the source of multicast traffic or towards the rendezvous point. So in case of a network failure only after convergence of the unicast routing the additional tasks for erecting a new multicast distribution tree can be done. Hence multicast routing inherits time behavior of the unicast routing in a similar way as a customer inherits routing convergence behavior of the service provider network in case of a L3-VPN model.



PIM DM (Protocol Independent Multicast routing Dense Mode): Basically it is an implementation of RPF (reverse path forwarding) check which looks if a multicast packet arrives on the interface which is on the shortest path to the multicast source. If so, the multicast packet will be duplicated to all other interfaces. If not - meaning the multicast packets arrives on an interface which is not on the on the shortest path to the multicast source - the multicast packet will be discarded. Using this technique a shortest path from the source to all network parts can be established. Now - after multicast traffic actually arrives from the source - a downstream router can decide based on IGMP, if it needs that multicast traffic or not. If not it will send to the upstream router a "prune" routing message to stop this unwanted traffic and the upstream router will install a state to stop duplication traffic on the interface towards downstream router. Downstream and upstream are terms used according to the shortest path tree to the multicast source also called SPT (Source-Path-Tree) or S,G tree.



Now let us analyze the PIM DM in more detail concerning routing convergence. It need IGMP (Internet Group Membership Protocol) to get aware which multicast groups are necessary at a given location. IGMP allows a multicast listener to tell the local multicast router to which multicast addresses he/she is interested in. Based on IGMP a multicast router can make its decision if a given multicast address needs support (forwarding of multicast traffic) or not.

What happens if group membership changes on a pruned part of the SPT? States are removed after a certain timeout (3 minutes per default) and multicast traffic will flood the network again using RPF. So downstream routers have a new chance to decide if to prune or not. If 3 minutes are too long there is an additional method of "grafting" to speed up. Whenever a downstream router has pruned for a multicast group address but then recognizes via IGMP that a local multicast listener appears, it can send a graft message to the upstream router to immediately disable the state hence get the corresponding multicast traffic without waiting for 3 minutes refresh interval.

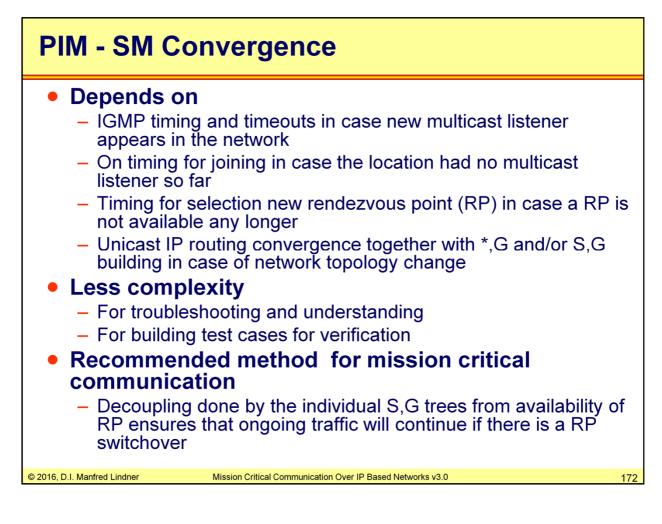
So far we have considered only setup and refresh of a MDT for a given multicast group with given source(s). What happens if there is failure in the network and a change of topology? When multicast traffic is still produced by the source, RPF will establish a new SPT after IP unicast routing has converged. RPF checks depend on shortest path calculation done by the unicast routing protocol to the multicast source hence the new SPT will reach a consistency after IP unicast has reached consistency and the downstream routers have pruned the trees accordingly. During time of change in the network we will experience flooding of multicast packets which may introduce additional delay for convergence.

PIM - SM Operation Summary		
 Presence of multicast listeners 		
 Creates share 	ed trees or *,G trees towards a rendezvous point (RP)	
States for join		
	n the multicast routers	
 Time out if no 	t periodically refreshed	
Multicast sour	rce traffic	
 First hop route transport system 	er uses register encapsulation is to reach the RP via unica em	ast
• Optional:		
transport syst	G tree from RP to source with join messages if multicast em is available toward source	
 This stops reg 		
•	ers of multicast listeners	
	lual S,G tree towards the source	
	e *,G tree towards RP	
 If all multicast necessary any 	: listeners have built there individual S,G tree the RP is no ymore for that particular source/group combination	ot
Hence		
 – RP for meetin 	ig to establish individual S,G trees on the fly	
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PIM SM (Protocol Independent Multicast routing Spares Mode): This kind of multicast routing was developed to overcome the deficits of PIM DM namely first periodical flooding the whole network with multicast traffic in order to refresh or rebuilt the multicast distribution trees and second the necessary amount of state information in the network.

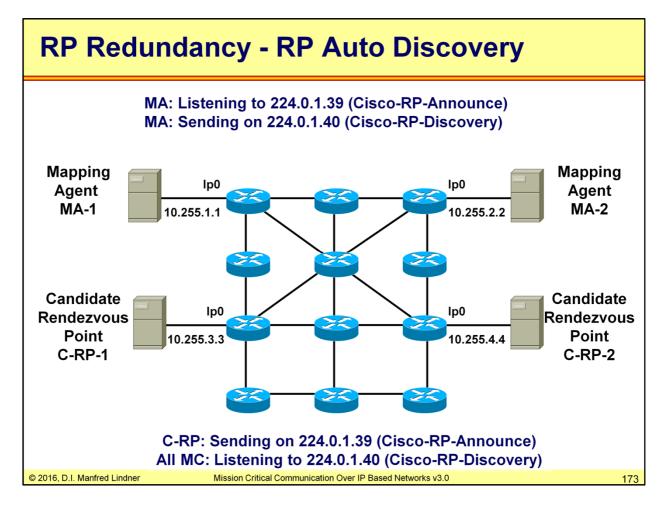
Multicast routers know by configuration or auto-discovery about IP address of a rendezvous point acting as core. Multicast listeners are supported starting from the rendezvous point with a "shared" multicast distribution tree (so called *,G tree in comparison to S,G tree). Every router - after recognizing by IGMP that certain group address is required by its local listeners - will sent a multicast "Join" message upstream to the rendezvous point. For determination of upstream unicast routing is used to find the shortest path to the rendezvous point. The next upstream router - depending on if the *,G tree was already erected towards it or not - will either move on the "Join" message towards the rendezvous point or will add the interface where the "Join" was received to the so far established *,G tree. Establishment of the *,G tree does not depend on presence of multicast traffic for a certain group. It is "topology-driven" based on the knowledge where the rendezvous point and the potential multicast listeners are located. The *,G tree will be refreshed by periodical "Join" messages from the downstream routers as long as there are some listeners present. If no listeners are known anymore the *,G tree will disappear. If now a multicast source starts sending multicast traffic the first router - knowing about the rendezvous point - will encapsulate that multicast message in a unicast message ("Register" message) destined for the rendezvous point. The rendezvous point will decapsulate the message in will forward it in multicast style along the *,G tree to all listeners registered so far. If another source from a different location starts sending of multicast traffic for the same group, the traffic will arrive encapsulated at the rendezvous point and will take the same *,G tree to reach all listeners of that group. Therefore the name "shared" tree where all source of multicast traffic take the same multicast distribution tree. In PIM DM there would be two or more different S,G trees if two or more sources are present at the same time. PIM SM scales much better in the case that most multicast listeners are in a local distance to the rendezvous point (sparse mode). Hence multicast sources far away from the rendezvous point need no multicast transport system in the network because of unicast style of "Register" messages. On the other side if a full multicast network is available then optionally the rendezvous point can establish a S,G tree using "Join" messages towards the upstream router. For determination of upstream again unicast routing is used to find the shortest path to the source. S;G tree expresses that this multicast distribution tree is used only for multicast traffic from that particular source S for a given multicast group G.

There is another optimization for a multicast router which has joined the *,G tree. On presence of incoming multicast traffic arriving at the *,G tree a multicast router of such a location can decide to built a (private) S,G tree towards the source. After establishment of this source-based tree the router can leave the *,G tree. Now multicast traffic towards this router uses a separate S,G tree from the source location to the corresponding location on its own. Cisco PIM SM multicast routers make this decision based on the amount of multicast traffic arriving on the *.G tree. The default value is 0% meaning a private S,G tree is immediately established. Now you can fully understand the name rendezvous point. It used just to meet and direct multicast traffic to your location. Later multicast traffic will use the private S,G tree and the rendezvous point is not necessary anymore.



What happens in case of a network failure influencing the already installed trees? The multicast router will recognize that the upstream interface is not anymore on the shortest path towards the rendezvous point or source, will remove the state and will initiate a new "Join" after the IP unicast routing has converged. Actual timing when *,G and S,G trees are available again depends on if a failure can be directly detected by the router (e.g. interface down) or if the router can recognize a change by looking to the unicast routing table, where changes depend on unicast routing protocol or BFD timeouts. But again multicast routing convergence depends on underlying unicast routing convergence plus necessary time to build the new distribution trees.

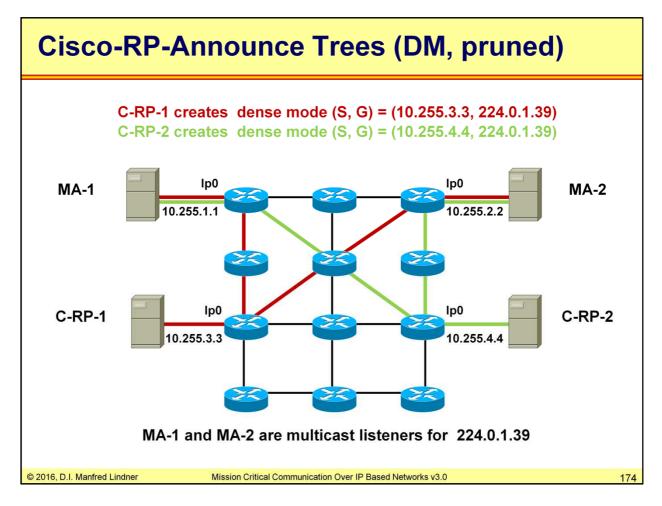
Another critical point is the presence of rendezvous point. If you use the technique of private S,G trees then it has no influence on ongoing multicast streams. Only new multicast streams which need to meet at rendezvous point first cannot be transported if the rendezvous point is absent. If you do not use the technique of private S,G trees then of course the outage of a single rendezvous point (RP) is a disaster.



Cisco solves the problem of RP being a of single point of failure with a "RP Auto-Discovery" procedure. The timing of the procedure has to be tuned to reach seconds convergence time.

RP-Auto-Discovery works as follow. Some routers are configured as mapping agents (MAs), some routers are configured as candidate rendezvous points (C-RPs). MAs use multicast dense mode techniques to discover potential C-RPs. One of the C-RPs is declared as the actual RP by the MAs, the others are standby RPs. Multicast routers are informed by the MAs about the actual RP. If there is change of presence of a RP or MA protocol timeouts will detect that change. Of course that will influence the overall availability of the multicast routing system.

Technique can also be used to provide a kind of load balancing concerning RP. So RP-1 can cover a certain range of IP multicast groups and RP-2 can cover another range of IP multicast groups. Both can act as backup for the other.



C-RP is a candidate for a multicast rendezvous point

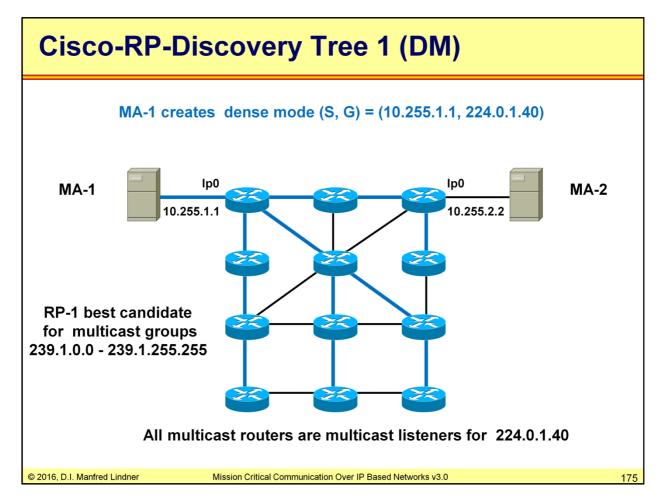
MA is mapping agent allowing C-RPs to register

Auto-RP Procedure 1:

C-RPs advertize themselves and their corresponding MC groups for which they are responsible to the Cisco-RP-Announce 224.0.1.39 multicast group.

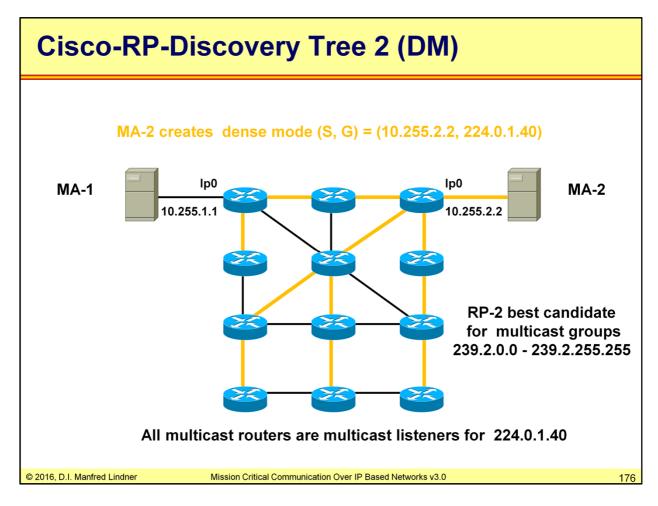
MAs listens to the Cisco-RP-Announce 224.0.1.39 multicast group, select the best candidate for RP (highest IP address).

In order to allow the Auto-RP procedure to work (to allow MA routers to join the 224.0.1.39 group and all routers to join the 224.0.1.40 group in all circumstances) a new mode was created by Cisco: the so called "ip pim spares-dense mode". As long as no RP is known every router is using dense-mode. If RP is known routers switchover to spares-mode operation.



Auto-RP Procedure 2:

MAs select the best candidate for RP (highest IP address as tie-breaker) for a given multicast group range and announce this using Cisco-RP-Discovery 224.0.1.40 multicast group. Any router configured for PIM-SM listens to 224.0.1.40 and learns the correct RP for each known group.



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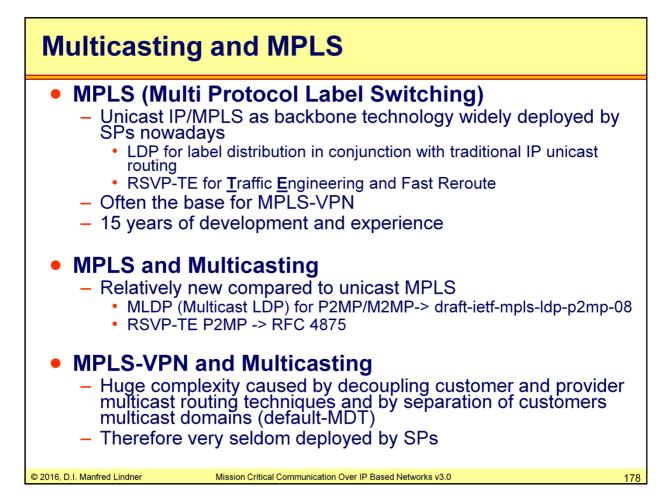
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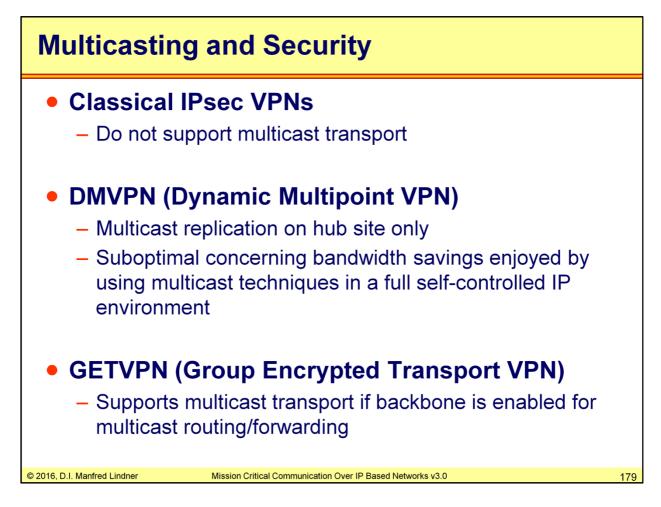
Summary

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Unfortunately overlay VPNs have either no support for multicast (IPsec) or only suboptimal support for multicast (DMVPN). Even most classical VPNs like MPLS-VPN do not offer support for multicast. So be careful when enforcing a multicast communication style in your solution. It depends on the VPN technique involved, if it is possible or not. GETVPN - because of group encryption - can be combined with IP multicast without any problem.

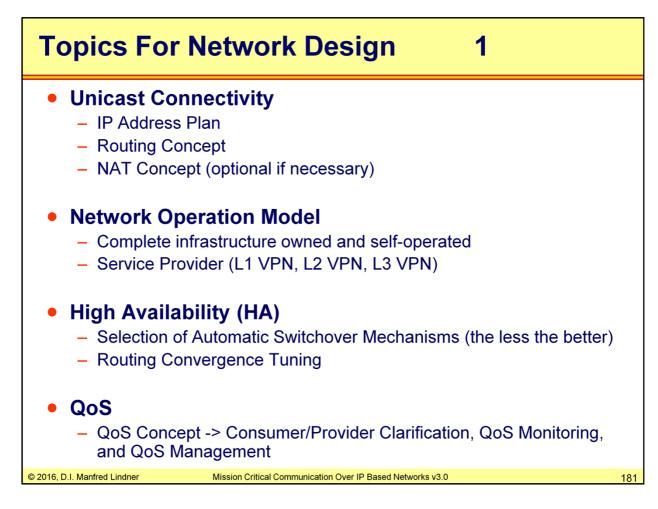
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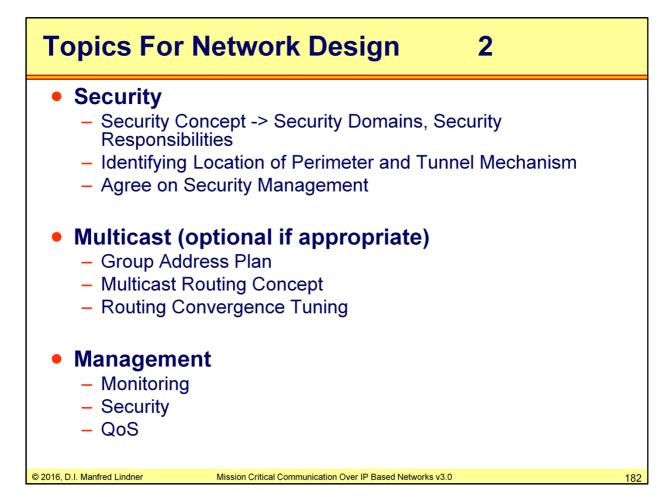
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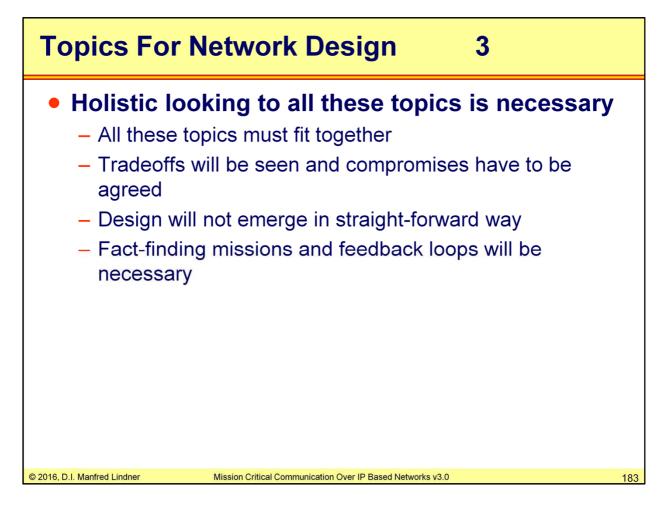
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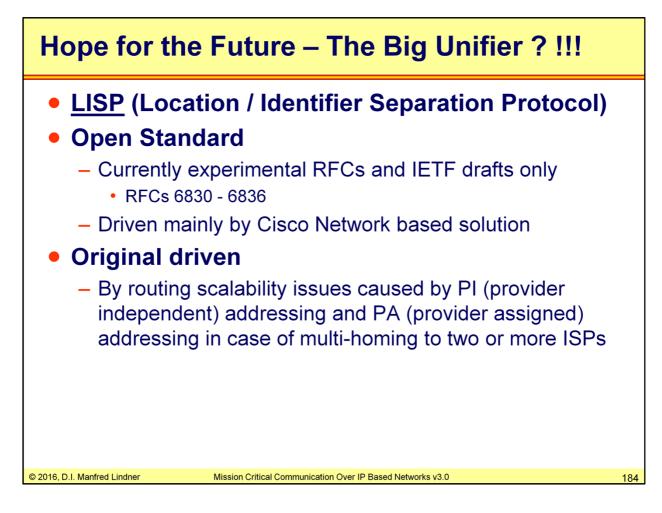
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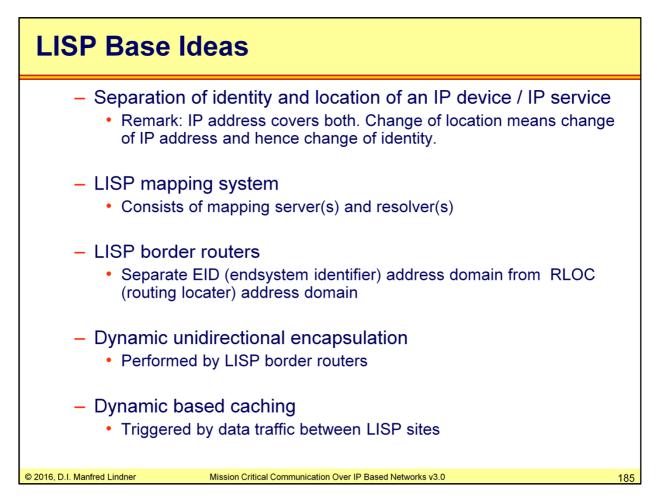
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LISP Results	
 What comes out: Multi-homing and routing scalability Ingress traffic engineering (TE) in case of multi-homing without complex BGP configuration 	
 But also a lot of other use cases: Especially interesting for enterprises Disaster recovery, deployable systems Mobility and GEO-redundancy Connection of IPv6 islands over IPv4 infrastructure, transition to IPv6 Virtualization, VPN Cloud computing as combination of mobility, multi-tenancy and segmentation (VPN) VM mobility (VM move across IP subnets instead of subnet extension) LISP mobile node And many others to be discovered 	
 Easy start No changes at the end systems No changes in the IP WAN (service provider) infrastructure LISP capable routers at the border only Incremental deployment possible with benefiting from LISP day-one by usage of proxies Wission Critical Communication Over IP Based Networks v3.0 18 	

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Information about LISP

- www.lisp4.net
- lisp.cisco.com
- IETF RFC 6830 6836
- OpenLISP.org
- LISPmob.org

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